

NM/CT 870 & Discovery NM/CT 670

Pre-Installation Manual



5483063-1EN
Revision 10
US English
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Revision History - 870 & D670

Direction + Revision	Date	Description of Changes
5483063_r10	May 2022	<ul style="list-style-type: none"> • Figure 1-1 NM Gantry on Dolly Measurements on page 40 • Table 4-2 Heat Output in Scan Room on page 104 • Table 5-1 System Power Characteristics on page 106 • Table 5-2 Nominal Power Line Ranges on page 107
5483063_r9	March 2021	<ul style="list-style-type: none"> • New format, typos and minor corrections across manual • Updated Table 2-4 Floor Leveling Specifications on page 83 • Updated EMI and EMC to comply with IEC60601-1-2 Edition 4.0 EMC standard for medical electrical equipment, including: <ul style="list-style-type: none"> • 3.5 EMI Considerations on page 98 • Appendix C EMC Compliance on page 142 • Added ISO center height in Figure 2-15 CT Gantry Center of Gravity Points on page 70 • Added Inrush Current to Table 5-4 Power Supply Requirements on page 108
5483063_r8	July 2019	<ul style="list-style-type: none"> • Updated Table 1-3, Components and Clearance — Metric[40-50-60-70], p.1-16 • Updated Table 1-6, Components and Clearance — Imperial[40-50-60-70], p.1-21 • Updated Table 2-3, Components in Scan and Console Rooms[50-60-70], p.2-26 • Updated Figure 2-16: Table Views[40-50-60-70], p.2-19 • Replaced Figure 2-29: Reduced Serviceability Configuration Room Layout[70], p.2-41 • Updated Table 2-4, Weight of Components, p.2-57 • Added Figure 2-55: NM Acquisition Computer Center of Gravity Points[30-40-70], p.2-78 • Updated Table 4-4, Heat Output in Scan Room[70], p.4-7 • Updated Table 5-15, Sub-system Inter-connection Cables[70], p.5-29 • Updated Table 5-18, Customer Supplied Cables and Wiring[50-60-70], p.5-38 • Added section RSVP Requirements[30-40-5060-70], p.6-2
5483063_r7	June 2018	<ul style="list-style-type: none"> • Added the floor slope specification for the Model B table in Table 2-9, under Floor Levelness and Flatness, p.2-103. • Updates in System Cable Information, p.5-26 • Updated Chapter 6: Network Requirements

Direction + Revision	Date	Description of Changes
5483063_r6	March 2018	<ul style="list-style-type: none"> • Incorporated NM/CT 870 system into the manual • Added a reference to the global site readiness checklist in Project Coordination, p.1-4. • Updated Figure 2-29: Reduced Serviceability Configuration Room Layout, p.2-43 • Updated Figure 2-36: Component Movement Curves, p.2-55 • Reduced room height requirement Ceiling Requirements, p.2-112
5483063_r5	Jan 2018	<ul style="list-style-type: none"> • Added rigging information in Rigging, p.1-12 • Added a description of the NM Gantry configuration during transportation in Table 1.3.4, p.1-13 • Added new Center Of Gravity diagram for the NM gantry in Figure 2-44 • Corrected the Pass/Fail values for the example in the Floor Flatness & Slope specification in Table 2-9 • General – updated the system diagrams to show only one cable duct in the table pivot plate • Replaced the Drills & Cable Ducts Figure 2-61 with a clearer diagram • Modified a typo in the Hybrid Table weight • Updated the Table Center of Gravity diagram in Figure 2-49 • Removed the elongated and square rooms in Ch.2.2.2, System Layout Drawings • Added new Center of Gravity diagram for the CT gantry Figure 2-46, NIO Console Figure 2-50, CT PDU Figure 2-51, PIDB Figure 2-52 • Updated Altitude requirements in Table 4-1 • Updated the D670 Air Flow Figure 4-1 • Modified a typo in the continuous and maximum power demand in Table 5-12 • Added the PDU to PIDB interconnect cable information to Table 5-15 • Added information regarding the maximum connector sizes in the interconnect cables Ch., Connector Sizes[5060-70] • Added the D670 NM Partial UPS cable information to App.E, NM Partial UPS • Fixed previous revision history
5483063_r4	Jan 2017	New system configuration added: Discovery 670 DR, page iv
5483063_r3	Sept 2016	<ul style="list-style-type: none"> • Updated CT gantry, table in Table 1-3, p.1-16, Table 1-6, p.1-21, Table 2-4, p.2-63 • Updated CT center of gravity in Figure 2-47, p.2-77, Table 2-10, p.2-118 • Updated COG values in Figure 2-47, p.2-77, Figure 2-49, p.2-80, Table 2-10, p.2-118 • Updated ceiling height in Ceiling Requirements, p.2-112 • Updated center of gravity values in Subsystem Centers of Gravity and Anchoring Points, p.2-118 • Updated the maximum altitude specification in Table 4-1

Direction + Revision	Date	Description of Changes
5483063_r2	April 2015	<ul style="list-style-type: none"> • Updated to include D670ES in configurations with Optima CT scanners (items indicated by -<D670 Color> D670/OPT) • Addition of IMPORTANT note to Detector Head Precautions, p.1-7 • Update of UPS specifications in: Table 1-3, p.1-16 and Table 1-6, p.1-21 • Removal of CT Console table diagram from Chapter 1 • New room layout Figure 2-29: Reduced Serviceability Configuration Room Layout, p.2-43 & Section on page 44 • Update of Figure 2-30: Minimal Room Layout, p.2-46 • Update of Figure 2-31: Example of Room Layout, p.2-48 • Update of UPS specifications in Table 2-4, Weight of Components, p.2-63 • Update of Table 2-7, Drilling and Anchor Chart, p.2-96 • Update of Figure 2-67: Patient Table Pivot Floor-Plate Anchoring Holes[15-30-40-5060-70], p.2-102 • Update of 2.4 Seismic Requirements, p.2-117 and Table 2-10, Subsystem Centers of Gravity and Anchoring Points, p.2-118 • Addition of UPS to Table 4-4, Heat Output in Scan Room, p.4-8 • Update of Figure 5-11: MDP (A1) Connected to Power Input Distribution Box (PIDB) – Configuration Options[5060-70], p.5-36
5483063_r1	May 2014	<p>New/updated information:</p> <ul style="list-style-type: none"> • Addition of -D670/OPT system • Detector-less option • Vibration specifications • Heat output • Floor leveling
5454645_r1	Nov 2012	Minor updates (remove part numbers)
5336223_r3	April 2011	Minor updates
5336223_r2	Feb 2011	Change installation flow
5336223_r1	June 2010	New manual

Language Policy

DOC0371395 - Global Language Procedure

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<p>ĮSPĖJIMAS (LT)</p>	<p>Šis vadovas yra išverstas į keletą kalbų.</p> <ul style="list-style-type: none"> • Jei kliento paslaugų teikėjui reikalingas vertimas į kitą kalbą, kurios nėra kliento dokumentacijos portale, už vertimo paslaugų suteikimą atsako klientas. • Neatlikite įrangos techninės priežiūros, kol neperžiūrėjote ir neišsiaiškinate šio techninės priežiūros vadovo. • Nepaisant šio įspėjimo dėl elektros smūgio, mechaninio arba kitokio pavojaus gali būti sužalotas paslaugų teikėjas, operatorius arba pacientas.
<p>TWISSIJA (MT)</p>	<p>Dan il-manwal huwa disponibbli f'diversi lingwi.</p> <ul style="list-style-type: none"> • Jekk fornitur tas-servizz ta' klijent ikun jehtieg lingwa għajr dawk ipprovduti fil-Portal tad-Dokumentazzjoni tal-Klijent, hija r-responsabbiltà tal-klijent li jipprovdni servizzi ta' traduzzjoni. • Tippruvax tagħmel service fuq it-tagħmir sakemm ma jkunx gie kkonsultat u mifhum dan il-manwal għas-service. • Jekk wieħed jonqos milli josserva din it-twissija, dan jista' jwassal f'korrimnt lill-fornitur tas-servizz, lill-operatur jew lill-pazjent minn xokk elettriku, mekkaniku, jew perikli oħra.
<p>ADVARSEL (NO)</p>	<p>Denne håndboken er tilgjengelig på flere språk.</p> <ul style="list-style-type: none"> • Hvis en kundes tjenesteleverandør krever et annet språk enn de som finnes i dokumentasjonsportalen for kunder, er det kundens ansvar å levere en oversettelsestjeneste. • Ikke prøv å utfør service på utstyret med mindre man har konsultert og forstått servicehåndboken. • Om denne advarselen ikke følges kan det føre til skade på tjenesteleverandør, operatør eller pasient fra elektrisk støt, mekanisk eller annen fare.
<p>OSTRZEŻENIE (PL)</p>	<p>Niniejszy podręcznik jest dostępny w kilku językach.</p> <ul style="list-style-type: none"> • Jeżeli serwisant klienta wymaga języka, który nie został udostępniony w portalu dokumentacji klienta, obowiązkiem klienta jest zapewnienie usług tłumaczeniowych. • Nie podejmować prób serwisowania urządzenia bez uprzedniego zapoznania się z niniejszym podręcznikiem serwisowym i zrozumienia jego treści. • Nieprzestrzeganie tego ostrzeżenia może spowodować obrażenia u serwisanta, operatora lub pacjenta, spowodowane porażeniem prądem, zagrożeniami mechanicznymi lub innymi.
<p>ATENÇÃO (PT-BR)</p>	<p>Este manual está disponível em vários idiomas.</p> <ul style="list-style-type: none"> • Se o prestador de serviços de um cliente necessitar de um idioma diferente dos fornecidos no Portal da Documentação do Cliente, o fornecimento dos serviços de tradução é de responsabilidade do cliente. • Não tente realizar manutenção do equipamento a menos que o manual de serviço tenha sido consultado e seja entendido. • O não cumprimento deste aviso resultará em lesões ao provedor de serviço, operador ou paciente de choque elétrico, mecânico ou outros riscos.
<p>ATENÇÃO (PT-PT)</p>	<p>Este manual está disponível em vários idiomas.</p> <ul style="list-style-type: none"> • Se o fornecedor de serviços de um cliente necessitar de um idioma diferente dos fornecidos no Portal de Documentação do Cliente, é da responsabilidade do cliente assegurar os serviços de tradução. • Não experimente reparar o equipamento sem primeiro consultar, e compreender, o presente manual de assistência. • O incumprimento deste aviso pode resultar em ferimentos para o técnico de reparação, o operador ou o paciente decorrentes de perigos de eletrocussão, mecânicos ou outros.

<p>ATENȚIE (RO)</p>	<p>Acest manual este disponibil în mai multe limbi.</p> <ul style="list-style-type: none"> • Dacă furnizorul de servicii al unui client necesită o limbă diferită de cele furnizate în Customer Documentation Portal (Portalul cu documentație pentru clienți), este responsabilitatea clientului să furnizeze servicii de traducere. • Nu încercați să efectuați întreținerea echipamentului decât dacă ați consultat și ați înțeles acest manual de service. • Nerespectarea acestei avertizări poate duce la rănirea furnizorului de servicii, a operatorului sau a pacientului din cauza șocurilor electrice, mecanice sau a altor pericole.
<p>ПРЕДУПРЕЖДЕНИЕ (RU)</p>	<p>Это руководство доступно на нескольких языках.</p> <ul style="list-style-type: none"> • Если поставщику услуг заказчика требуется языковая версия, отличная от предложенных на портале документации для заказчиков, перевод руководства на необходимый язык осуществляется стороной заказчика. • Не начинайте эксплуатацию оборудования без предварительного надлежащего ознакомления с этим руководством. • Если вы проигнорируете это предупреждение, поставщик услуг, оператор или пациент могут получить механические травмы, травмы вследствие поражения электрическим током или другие увечья.
<p>UPOZORENJE (SR)</p>	<p>Ovaj priručnik je dostupan na nekoliko jezika.</p> <ul style="list-style-type: none"> • Ako korisnikov serviser zahteva neki drugi jezik osim onih koji su dostupni na portalu sa korisničkom dokumentacijom (Customer Documentation Portal), klijent mora da obezbedi prevod. • Nemojte pokušavati da servisirate opremu ako niste proučili i razumeli ovaj priručnik za servisiranje. • Nepoštovanje ovog upozorenja može da izazove povrede serviseru, operatera ili pacijenta kao posledicu strujnog udara, mehaničkih ili drugih opasnosti.
<p>UPOZORNENIE (SK)</p>	<p>Táto príručka je k dispozícii v niekoľkých jazykoch.</p> <ul style="list-style-type: none"> • Ak poskytovateľ služieb daného zákazníka požaduje jazyk odlišný od jazykov dostupných na portáli s dokumentáciou pre zákazníkov, za prekladateľské služby zodpovedá zákazník. • Nepokúšajte sa vykonávať servis na zariadení, pokiaľ ste si neprečítali a nepochopili pokyny v servisnej príručke. • Nedodržanie tohto varovania môže byť príčinou úrazu poskytovateľa servisu, obsluhy alebo pacienta v dôsledku zásahu elektrickým prúdom alebo v dôsledku mechanických alebo iných nebezpečenstiev.
<p>OPOZORILO (SL)</p>	<p>Ta priročnik je na voljo v več jezikih.</p> <ul style="list-style-type: none"> • Če ponudnik storitev stranke potrebuje priročnik v jeziku, ki ni na voljo na portalu z dokumentacijo stranke, mora stranka zagotoviti prevod. • Opreme ne poskušajte servisirati, če niste prebrali in razumeli tega servisnega priročnika. • V primeru neupoštevanja tega opozorila lahko pride do telesnih poškodb ponudnika storitev, upravljavca ali pacienta zaradi električnega udara, mehanskih ali drugih nevarnosti.

<p>ADVERTENCIA (ES)</p>	<p>Este manual se encuentra disponible en varios idiomas.</p> <ul style="list-style-type: none"> • Si el proveedor de servicios de un cliente requiere un idioma distinto de los proporcionados en el Customer Documentation Portal (Portal de documentación para clientes), es responsabilidad del cliente proporcionar los servicios de traducción. • No intente realizar el mantenimiento del sistema a menos que haya consultado y comprendido este manual de servicio. • El incumplimiento de esta advertencia puede causar lesiones al suministrador de servicios, el operador o el paciente debido a descarga eléctrica, mecánica u otros riesgos.
<p>VARNING (SV)</p>	<p>Denna manual är tillgänglig på flera språk.</p> <ul style="list-style-type: none"> • Om en kunds tjänsteleverantör behöver ett annat språk än de som tillgängliggjorts på portalen för kunddokumentation är det kundens ansvar att erbjuda översättningstjänster. • Försök inte att reparera utrustningen utan att först rådfråga och förstå denna servicehandbok. • Om denna varning inte beaktas kan det leda till skada för tjänsteleverantör, operatör eller patient genom elektrisk stöt, mekaniska eller andra faror.
<p>DİKKAT (TR)</p>	<p>Bu kılavuz birden fazla dilde sunulmaktadır.</p> <ul style="list-style-type: none"> • Bir müşterinin servis sağlayıcısı Müşteri Belgeleri Portalı'nda sağlananlardan farklı bir dil talep ederse çeviri hizmeti sağlamak müşterinin sorumluluğundadır. • Bu servis kılavuzuna başvurmadan ve içeriğini anlamadan ekipman üzerinde servis işlemi yapmayı denemeyin. • Bu uyarıya uyulmaması; elektrik çarpması, mekanik tehlikeler veya başka tehlikelerden ötürü servis sağlayıcı, operatör veya hastanın yaralanmasıyla sonuçlanabilir.
<p>ПОПЕРЕДЖЕННЯ (UK)</p>	<p>Цей посібник доступний кількома мовами.</p> <ul style="list-style-type: none"> • Якщо постачальник послуг замовника використовує мову, яку не вказано на порталі з документацією для замовників, послуги з перекладу має забезпечити замовник. • Не починайте роботу з обладнанням без попереднього належного ознайомлення з посібником із використання. • Якщо ви проігноруєте це попередження, постачальник послуг, оператор або пацієнт можуть зазнати механічних травм, ураження електричним струмом або інших тілесних ушкоджень.
<p>CẢNH BÁO (VI)</p>	<p>Tài liệu hướng dẫn này có sẵn ở một số ngôn ngữ.</p> <ul style="list-style-type: none"> • Nếu nhà cung cấp dịch vụ của khách hàng yêu cầu ngôn ngữ khác với ngôn ngữ được cung cấp trong Cổng Thông Tin Tài Liệu Khách Hàng, khách hàng có trách nhiệm cung cấp dịch vụ dịch thuật. • Không cố bảo dưỡng thiết bị trừ khi đã tham khảo và hiểu rõ hướng dẫn sử dụng này. • Việc không chú ý đến cảnh báo này có thể dẫn đến thương tích cho nhà cung cấp dịch vụ, người vận hành hoặc bệnh nhân do điện giật, nguy hiểm cơ học hoặc các mối nguy hiểm khác.

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Safety Notices - NM800 & NM600

Safety Labels in This Document

This manual addresses the following safety classifications:

 **DANGER**



Danger is used to identify conditions or actions for which a *specific hazard* is known to exist, which *will cause severe or fatal personal injury* or substantial property damage if the instructions are ignored.

 **WARNING**



Warnings are used to identify conditions or actions for which a *specific hazard* is known to exist, which *may cause severe or fatal personal injury* or substantial property damage if the instructions are ignored.

 **CAUTION**



Cautions are used to identify conditions or actions for which a *potential hazard* may exist, which *may cause minor personal injury* or property damage if the instructions are ignored.

Safety Information in the System Documentation Set



WARNING

Before any attempt is made to use/service the system, the operator and service personnel must be trained, and must read and be acquainted with all *safety-related documents* (see below).

This information will prepare all users to operate the equipment safely and correctly in order to ensure the well-being of the patient, operator and service personnel.

This document *must* be read in conjunction with the *Safety and Regulatory* and *System Description* manuals provided in the *Operator Manual set*. These, in conjunction with the information in Service Safety, provide you with all necessary safety-related safety information.

All service safety information that is specific to Pre-Installation and Installation is detailed in the relevant manual, for example: transportation, storage and conveyance precautions are specified in the *Pre-Installation Manual*, while safety details that are relevant only to installation appear in the *Installation Manual*.

Hybrid systems: The safety manuals do not cover CT-related safety in detail. All CT-related safety procedures, regulatory information and warnings are included in the *CT Service Documents* (provided separately).

Safety-related Documents

Safety-related and general information is available in the manuals provided with the system as follows:

- **Service Safety Manual**
 - Spatial orientation
 - Service clearance
 - Service-related safety mechanisms and procedures
 - Service-related safety labels and labels on interior system components (under system covers)
 - EMC and service tools information
- **Information provided within the Operator Manual Set:**
 - **Safety and Regulatory User Guide**
 - Intended use (including medical purpose, patient population and operator profile)
 - General safety warnings and instructions
 - Safety mechanisms and procedures

- Operator and patient safety during clinical operation
- Equipment and data safety
- **System Description and Safety Manual for Operators**
 - Detailed system description
 - System specifications
 - Startup and shutdown procedures
- **Quality Control Operation Guide**
 - Tests and other QC procedures performed by the operator
 - Daily QC
 - Periodical tests and retuning
- **Adhesive Labels and Rating Plates User Guides**
 - Labels on the exterior of system components

Indications, Terminology and NM800 & NM600 System Names

Indications

The following indications are relevant for all documents in the Service documentation set.

- The images in this manual are for demonstration only. There may be minor differences that do not affect functionality.
- Some of the described features may be optional, depending on system model/configuration. Whenever items or procedures differ between the different configurations, this is indicated.
- This manual might refer to different hybrid patient table configurations or different gantry rotor mechanics. Whenever procedures differ between the different configurations, this is indicated at the beginning of the procedure.
- When there are system-specific differences, this is indicated using system-specific abbreviations as detailed in:
 - NM800 Series - [Table 1 NM800 Series on page 24](#)
 - NM600 Series - [Table 2 NM600 Series on page 24](#)
- **General Terminology:**
 - **NM** is an abbreviation for **Nuclear Medicine**.

- The terms **NM System**, **Gamma camera** and **Camera** are used interchangeably.
- **SPECT** stands for Single Photon Emission Computed Tomography.
- **Hybrid systems terminology and naming (870/D670/850/860/O640):**
 - The term **Hybrid systems** indicates all systems with a CT subsystem
 - The terms **Hybrid** and **SPECT/CT** may be used to designate a combination of SPECT and CT imaging modalities.
 - In the context of Hybrid SPECT/CT imaging, the term **NM** may refer to **SPECT**.
 - In the context of CT imaging, the term **x-ray** is synonymous with **CT**.
 - In the context of these systems, the term **Hybrid** refers to **Hybrid SPECT/CT Imaging**.
 - The abbreviation D670/OPT may be used to indicate the D670 or 870 CT sub-system.
- **D670 Coding for System-Specific Differences**

Discovery NM/CT 670 is available in several configurations, with different CT devices.

Most of the material provided in this manual is relevant for all Discovery NM/CT 670 models.

When an item refers to a specific configuration it is indicated as follows:

System full name	Abbreviation	Markings for system-specific material	
Discovery NM/CT 670 is available in several configurations, with different CT devices. In contexts where the specific CT model is relevant, this is indicated as follows:			
All Discovery NM/CT 670 models	D670	D670	D670
Discovery NM/CT 670 with Brightspeed Elite CT	D670/BSE	D670/BSE	D670/BSE
Discovery NM/CT 670 with Optima CT540, including the following: <ul style="list-style-type: none"> • Discovery NM/CT 670 Pro • Discovery 670 DR • Discovery NM/CT 670 ES 	D670/OPT	D670/OPT	D670/OPT

*1 To identify the configuration of a specific system, go to **System Configuration** > **Admin** tab and view the information in the **System Information** area (not accessible with Operator login).

*2 When details are relevant only for a specific model or configuration, the abbreviation will be followed by additional model identification.

System Names and Coding for System-Specific Differences

This manual may use the following abbreviations/terms to indicate differences between systems.

NOTE

- To identify the configuration of a specific system, go to **System Configuration > Admin** tab and view the information in the **System Information** area (not accessible with Operator login).
- When details are relevant only for a specific model or configuration, the abbreviation will be followed by additional model identification, for example 870CZT.

Table 1 NM800 Series

System full name	NM Detector Technology	Integrated CT Sub-system	Abbreviation
NM800 Series refers to all of the following systems:			NM800
• NM 830	Single NaI crystal	NA	830
• NM/CT 850	Single NaI crystal	CT850	850
• NM/CT 860	Single NaI crystal	CT860	860
• NM/CT 870, including:			870
• NM/CT 870 DR	Single NaI crystal	Optima CT540	
• NM/CT 870 CZT	Multiple CZT crystals	Optima CT540	

Table 2 NM600 Series

System full name	Abbreviation
NM600 Series refers to all of the following systems:	NM600
• Brivo NM 615	B615
• Discovery NM 630	D630
• Optima NM/CT 640	O640
• Discovery NM/CT 670	D670^(*)
• Discovery NM/CT 670 Pro	
• Discovery 670 DR	
• Discovery NM/CT 670 ES	
• Discovery NM/CT 670 CZT	

Table 2 NM600 Series (Table continued)

System full name			Abbreviation
(*) D670 systems are available in several models, with different CT devices and/or NM detector technology. In contexts where the specific CT model and/or NM detector technology is relevant, this is indicated as follows:			
System full name	NM Detector Technology	Integrated CT Sub-system	Abbreviation / Markings for system-specific material
Discovery 670 DR	Single NaI crystal	Optima CT540	D670-OPT or D670-OPT – Material specific to all D670 systems with Optima CT540 CT sub-system
Discovery NM/CT 670 Pro			
Discovery NM/CT 670 ES			
Discovery NM/CT 670 CZT	Multiple CZT crystals	Optima CT540	D670-OPT – When related to the CT sub-system D670CZT – When related to the CZT NM detectors
Discovery NM/CT 670	Single NaI crystal	Brightspeed Elite CT	D670-BSE – Material specific to D670 with Brightspeed CT

Service Documentation Set

Safety-Related Documents

Name	Additional Details
<i>Safety Manual for Service Users</i>	Part of Service documentation collection. Single manual applicable to all NM800 & NM600 systems.
Operator Guides: <ul style="list-style-type: none"> • <i>System Description & Safety Manual for Operators</i> • <i>NM Cameras Safety and Regulatory User Guide</i> • <i>Quality Control Guide</i> 	Available via the <i>Operator Documentation set</i> on the system (via [?]) at the NM acquisition station.

Service Manuals

Name	Comments
------	----------

<i>Pre-Installation Manual</i> <i>Installation Manual</i> <i>Planned Maintenance Manual</i> <i>Wiring Diagrams</i>	Part of Service documentation collection. Separate manuals available per system or group of systems.
<i>System Configuration Manual</i> <i>Calibrations, Map Creation and System Tests Manual</i> <i>Service Utilities Manual</i> <i>FRU Replacement Procedures</i>	Part of Service documentation collection. Manuals are applicable to all NM800 & NM600 systems.
<i>FRU Spare Parts List</i> <i>Software Installation Manual</i>	Provided separately

CT Service Documents for Hybrid Systems

Name
Provided separately <ul style="list-style-type: none"> • 870/D670 with Optima CT 540: <ul style="list-style-type: none"> • D670/OPT Optima CT 540 Installation Manual • D670/OPT Optima CT 540 Service Manual • D670 with Brightspeed CT: <ul style="list-style-type: none"> • D670/BSE BrightSpeed Installation Manual- Mechanical Installation • D670/BSE BrightSpeed Installation Manual- Electrical Calibration, Installation Manual Integration & Testing • D670/BSE BrightSpeed Service Manual • CT Service Methods Part of Service CD

Document Conventions

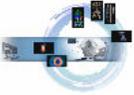
The following conventions are used throughout the manual:

Important

Calls attention to important comments.

NOTE

Contains tips and general comments.

Description	Example
Keys on the operator keyboard, hand-held controller (RCU) or gantry control panels and the gantry	<ul style="list-style-type: none"> • Press <SET> / <Ctrl>
Software interface buttons	<ul style="list-style-type: none"> • Click [OK] / [Apply] / [Cancel]
Names of items in the graphical interface including:	
<ul style="list-style-type: none"> • Names of dialog boxes, windows, tabs, areas and lists • Menu items • Field and icon labels 	<ul style="list-style-type: none"> • Click System Setup (tools icon), then select Maintenance > Utilities • To Do List • Properties field
System messages	Press Y to continue.
System parameters whose actual values must be defined by the user	Type-in the Patient ID
Hyperlinks	See Figure 1 Sample Image on page 27
File names or paths	root/opt/tacqdb/manuals
References to other documents	<i>Safety Manual</i>
Sample Image	<p>Figure 1 Sample Image</p> 

Chapter 1 General System Requirements

1.1 Objectives and Overview

This manual provides all information necessary to prepare the site for the installation of the system, taking into consideration the information required for different professionals such as architects, construction engineers, electrical contractors, and all other personnel involved in construction and preparation of the site.

Important

Good site preparation is essential for smooth and efficient installation and for proper functioning of the system. Poor site planning may compromise system efficiency, operator efficiency, operator comfort, and/or patient comfort.

The information provided in this *Pre-Installation Manual* is general in its nature, and must always be used in conjunction with the drawings and specifications prepared specifically for your site.

If the site is considering a future system upgrade, use the pre-installation manual of the intended system type, during site planning. Special attention should be paid to room size, floor requirements, electrical power requirements, cable paths (ducts), and environmental requirements (air conditioning for heat dissipation).

When upgrading a system, the site's power, structure and floor loading requirements must be evaluated for upgrade suitability according to this manual.

1.2 Customer Responsibilities

It is the customer's responsibility to prepare the site in accordance with all the specifications provided in this manual, and in conjunction with the site-specific drawings. It is essential to verify all aspects of the site configuration before construction is started, as subsequent changes can be costly or impractical.

A detailed checklist is provided in [Appendix A Customer Checklist on page 128](#). It is the customer's responsibility to ensure that all requirements in the checklist are fulfilled and the site conforms with all the specifications and requirements in this manual.

The customer is responsible for all aspects of site preparation, including, but not limited to, the following tasks:

- Assigning a project coordinator (see [1.2.2 Project Coordination on page 30](#))

- Planning and construction or renovations required for installation of the system, in accordance with the specifications included in this manual, including:
 - [2.2 Room Size, Layout and Considerations on page 53](#)
 - [Chapter 2 Equipment Description and General Construction Requirements on page 44](#)
 - [3.1 Radiation Protection and Shielding Requirements on page 93](#)
 - [Chapter 4 Environmental HVAC Requirements on page 101](#)
 - [5.1 Power Feed on page 106](#)
 - [Chapter 6 Network and GE Remote Access Requirements on page 126](#)
- Complying with all national, state, or local regulatory requirements for the country in which the installation occurs, for example:
 - Fire control devices as required by local codes
 - Permits, inspections, radiation licensing etc.
 - Earthquake-related regulations
 - Local regulations for service clearance and egress
- Assuring regulatory compliance for the use of radioactive isotopes and preparation of the required isotopes (see [1.2.1 Using Radioactive Isotopes on page 29](#))
- Safe storage of the system and auxiliary equipment prior to and during installation
- Floor tile removal and replacement in area of table and gantry
- Ensuring adequate accessibility for all system components and auxiliary equipment to the site

1.2.1 Using Radioactive Isotopes

Since the system involves the use of radioactive isotopes, compliance with Nuclear Regulatory Commission regulations, or similar regulatory requirements (depending on the country), must be adhered to and all permissions obtained well in advance. It is recommended that regulatory compliance is arranged early in the site planning process.

It is essential that all preparations are completed so that required source materials can be obtained prior to installation, including calibration sources. Take into consideration that these sources may have fairly long delivery lead times, yet may also have a short half life, so that it may not be advisable to store them for long periods of time.

The site must provide a list of isotopes in order to coordinate the calibrations plan prior to installation.

1.2.2 Project Coordination

The site project coordinator is the primary contact and liaison between GE and all site-related functions, including the purchaser, the construction planners, architects and contractors, and other site administrative personnel.

To ensure a successful installation, it is recommended that the site nominates a single site project coordinator, preferably a person familiar with similar medical construction projects, manages the entire project. Ideally, the project coordinator is involved in every phase from pre-installation and installation, from conceptual planning through to system start up, working closely with GE to ensure that the client upholds all requirements in this *Pre-Installation Manual*.

At the end of site preparation, the site project coordinator must verify that:

- The latest **Global Site Readiness Checklist** is being used (available via “GLOBAL HPM LINKS”)
- The checklist has been completed and submitted prior to equipment delivery

1.3 Delivery Requirements

The system is packed for shipment with the minimum number of component packages.



DAMAGE TO EQUIPMENT

The system components are sensitive to excessive mishandling, including dropping, shock, vibration, tipping or hoisting. Vibration damage to components may not be evident until after system installation is complete.

The system components must **never** be dropped. A drop from a height greater than 1 cm (½") may induce structural damage to the frame or other major components.

To avoid damage to sensitive components, dock-to-dock shipment is recommended. Other methods are acceptable, provided the system is not dropped or otherwise mishandled.

1.3.1 Temperature and Detector Precautions During Transportation and Delivery

NOTE

Refer to the *CT Pre-Installation Manual* for information related to the CT sub-system.

1.3.1.1 Temperature Precautions

Extreme temperatures must be avoided during system transportation and delivery. Ensure that the system is not exposed, for an extended period of time, to temperatures or humidity outside the following specifications.

Temperature range:	-34°C to +60°C (-29°F/+140°F)
Humidity range (non-condensing):	5% to 95%

NOTE

Component freezing occurs if the system is exposed to temperatures below -18°C (0°F) for a period of longer than two days. Allow a minimum of 12 hours for the system to adjust to ambient room temperature, prior to installation.

1.3.1.2 Detector Head Precautions



CAUTION

DAMAGE TO DETECTORS

Detector heads are very fragile. Always handle with extra care.

Detector heads are extremely sensitive to temperature gradients (sudden changes in temperature).

Failing to comply with the following instructions could cause irreversible damage to the detector heads.

Important

The conveyance path from the unloading area to the temperature-controlled area must be wide enough to allow passage of the detector heads packed in the original containers.

The detector heads must be transported in their original packages, which are designed to provide good mechanical stabilization as well as a certain amount of thermal insulation.

- As soon as the detector heads are unloaded from the transportation vehicles, they must be moved to a temperature-controlled area while still in their original containers, until they are ready to be installed into the system.
- If the temperature in the storage or installation areas differs from that of the delivery route and/or ambient temperature, a stabilization period of 1 hour per 3°C (5.4°F) difference must be allowed.

1.3.2 Delivery Unloading Area and Equipment

- The minimal unload area adjacent to the delivery truck is 15m×15m (50'×50'). Make sure that the unloading and storage areas are large enough to maneuver a forklift with crates.
- It is recommended to select the delivery site so as to provide the shortest and smoothest route for component conveyance:
 - If delivered on the installation day, as close as possible to the scan room for installation
 - If delivered prior to the installation day, as close as possible to the storage area
- If a forklift is required in order to unload or move system components:
 - Allocate a forklift capable of lifting more than the maximum weight of the heaviest unit, see **Components and Clearance:** [Table 1-1 Components and Clearance — Metric on page 34](#) (metric) or [Table 1-3 Components and Clearance — Imperial on page 37](#) (imperial)
 - **Additional CT-specific Components and Clearance:** [Table 1-2 Additional CT-specific Components and Clearance — Metric on page 36](#) (metric) or [Table 1-4 Additional CT-specific Components and Clearance — Imperial on page 38](#) (imperial).
 - Take into account sufficient floor space to maneuver the forklift near the delivery truck.

1.3.3 Conveyance of Crated System Components Within the Site

Regardless of whether the system is being delivered from the unloading area to storage, from the unloading area to unpacking area for installation or from storage to the installation area, take care to adhere to the following guidelines:

- Ensure that there is a free path, including an elevator if necessary, to wheel the components to the installation area.
- Verify that the route selected has sufficient clearance and load carrying capacity.
 - **Components and Clearance:** [Table 1-1 Components and Clearance — Metric on page 34](#) (metric) or [Table 1-3 Components and Clearance — Imperial on page 37](#) (imperial)
 - **Additional CT-specific Components and Clearance:** [Table 1-2 Additional CT-specific Components and Clearance — Metric on page 36](#) (metric) or [Table 1-4 Additional CT-specific Components and Clearance — Imperial on page 38](#) (imperial).
- The subsystems may be lifted only with a forklift and only when attached to their original shipping pallets.



CAUTION

DAMAGE TO SYSTEM COMPONENTS

Lifting of the gantry without its original shipping pallet or using a crane may damage the system and is prohibited.

- If the outer crating is removed after delivery, do not detach the subsystems from their original shipping pallets before they are conveyed to the scan room for installation.
- The center of gravity of each item, including lifting height and position, is marked on the subsystem crate. When conveying the subsystems within the site, and particularly if there are slopes in the delivery path, make sure to take the center of gravity into account.
- Always lower system components at the slowest reasonable rate.
- If the system components are to be transferred from an unloading site outside the building, special facilities must be provided to ensure smooth conveyance.
- Uneven temporary ramps may cause vibrations that could damage some components.
- System components may be moved via flat-bed tow truck or by rolling them across **smooth** sidewalks or other paved surfaces.
- When moving the gantry off a flat-bed tow truck, attach the straps to the lowest point possible on the dolly.

1.3.3.1 Rigging Limitations



Do not lift the gantry assemblies by their dollies. Do not transport the gantry assemblies across any surface by any means other than the dollies provided by GE. The assemblies have no lifting points and are not designed to be lifted by any special rigging attached to the gantry assemblies themselves.

 **DANGER**

POSSIBLE SEVERE PERSONAL INJURY OR DEATH

The dollies are not designed to be used as an attachment point for any method of lifting the subsystems.

Attaching lifting straps, cables or mechanisms to the dolly handles or any other part of the dolly is strictly prohibited.

NOTE

If it is determined that the subsystems must be lifted by crane or other lifting method the PM or person responsible for local siting of the system shall NOT proceed with the installation without consulting directly with GE Engineering.

Lifting the subsystems by crane or other lifting method should always be avoided. All alternate methods of delivery should be evaluated including the removal of any obstructions, doorways, walls, and windows.

If lifting is still required:

- The entire gantry assembly and both gantry transport side dollies must be placed on a lifting platform. GE does not provide a lifting platform.
- The entire patient table must be lifted while sitting on a lifting platform. The patient table shall be lowered to its transport position so the table base is in contact with the platform.
- The platform must be designed so no lifting straps or cables come in contact with any part of the gantry or table subsystems or its side dollies.
- The lifting platform shall bear the entire load. No part of the subsystem shall bear any load during the lift.

1.3.4 Crated and Uncrated Weights, Measurements and Clearance - Tables

The following tables provide you with crate and component measurements, weights and other data, in order to assist you in planning conveyance routes and storage areas. The order of the components in the list constitutes the recommended order of conveyance and delivery to the scan room for installation.

- **Components and Clearance:** [Table 1-1 Components and Clearance – Metric on page 34](#) (metric) or [Table 1-3 Components and Clearance – Imperial on page 37](#) (imperial)
- **Additional CT-specific Components and Clearance:** [Table 1-2 Additional CT-specific Components and Clearance – Metric on page 36](#) (metric) or [Table 1-4 Additional CT-specific Components and Clearance – Imperial on page 38](#) (imperial).

Table 1-1 Components and Clearance – Metric

Component name	Crated		Uncrated					Weight (kg)
	Crate size (cm) (without dollies) (H×W×L)	Weight (kg)	Minimal dimensions (cm)					
			Door width	Corridor / elevator width	Corridor / elevator length	Width of corridors w.90° turns	Height	
Pre-installation kit	75×40×175	15	any	any	any	any	any	15
NM gantry with detectors and dollies; without collimators	220×120×225	2413	140	140	222	250	200	2238
Table	140×90×300	785	100	100	280.9	250	any	557
NM Acquisition station	80×60×60	30	any	any	any	any	any	<20
Peripherals and accessories	115×100×150	50	any	any	any	any	any	50
Collimators on cart/s	170×90×115	370 (for heaviest set)	55	55	100	112	150	330 (heaviest set)

Table 1-1 Components and Clearance – Metric (Table continued)

Component name	Crated		Uncrated					Weight (kg)
	Crate size (cm) (without dollies) (H×W×L)	Weight (kg)	Minimal dimensions (cm)					
			Door width	Corridor / elevator width	Corridor / elevator length	Width of corridors w.90° turns	Height	
CT gantry, including dollies and side rail	231×137×200	870/D670-OPT2111 D670/BSE 2150	115	115	281	250	200	870/D670-OPT 2041 D670/BSE 2080
NM/CT covers	207×105×197	90	any	any	any	any	any	25
Optional Items								
NM UPS	May vary but not more than 60×40×80	May vary but not more than 80	any	any	any	any	any	May vary but not more than 60
<ul style="list-style-type: none"> • ECG Trigger Monitor • Xeleris • SmartConsole • Monitors 	May vary but not more than 80×80×80	May vary but not more than 15	any	any	any	any	any	<13
Detectors Dismount Option								
NM gantry without detectors; with dollies	220×150×168	2175	94.5	94.5	222	188	195	1690
Detector 1	93×86×100	320	86	86	100	100	98	320
Detector 2	93×86×100	320	86	86	100	100	98 ^{*7}	320 ^{*8}

*1 The minimum door width required in order to bring the system components into the scan room also depends on the width of the corridor leading to the room. In order to verify that the measurements comply with the requirements, when planning or measuring the width of the scan room door, use the graphs provided in [Figure 1-2 Required Door Opening vs Corridor Width When 90° Turn Required for NM Sub-systems on page 41](#).

*2 The corridor width required in order to move the system components from the unloading area to the scan room depends on the angles of turns on the corridor. For the required width when the angle is 90°, see [Figure 1-3 Required Corridor Width for 90° Turns to Convey NM Sub-system on page 42](#).

*3 May be delivered a few days prior to system delivery, as part of the final room check and preparation for installation.

*4 SmartConsole is provided only for 870 systems

*5 20 mm clearance above the floor

*6 Weight of gantry without detectors in the in-site transportation configuration: 1380 kg + weight of the dolly: 310 kg

*7 50 mm clearance above the floor

*8 The specified weight includes the packing. The detectors must be conveyed crated (unpacking is allowed only at the room or designated area where the detectors to be installed)

Table 1-2 Additional CT-specific Components and Clearance – Metric

Component name	Crated		Uncrated					Weight (kg)
	Crate size (cm) (without dollies) (H×W×L)	Weight (kg)	Minimal dimensions (cm)					
			Door width	Corridor / elevator width	Corridor / elevator length	Width of corridors with 90° turns	Height	
CT PDU	123×90×70	D670/BSE 440	100	100	100	100	any	D670/BSE 350
CT console (NIO)	65×47×83	May vary, but not more than 115	any	any	any	any	any	May vary, but not more than 88
CT accessories	115×100×150	50	100	110	150	180	any	50
CT sub-system covers	190×100×170	537	80	80	100	128	199	30
MDP (Main Disconnect Panel)	100×70×50	60	any	any	any	any	any	45
Optional Items								
CT UPS	86×46×81		any	any	any	any	any	205
Contrast Injector	May vary but not more than 80×80×80	May vary but not more than 15	any	any	any	any	any	<13
AW Workstation								

*1 The minimum door width required in order to bring the system components into the scan room also depends on the width of the corridor leading to the room. In order to verify that the measurements comply with the requirements, when planning or measuring the width of the scan room door, review the graphs in [Figure 1-2 Required Door Opening vs Corridor Width When 90° Turn Required for NM Sub-systems](#) on page 41.

*2 The corridor width required in order to move the system components from the unloading area to the scan room depends on the angles of turns on the corridor. For the required width when the angle is 90°, see [Figure 1-3 Required Corridor Width for 90° Turns to Convey NM Sub-system](#) on page 42.

*3 A1 or other; if ordered from GE, delivered in advance as part of the site preparation and must be installed prior to system installation

*4 In some cases, an alternative MDP is supplied, in order to comply with local electricity standards, see [5.6.2 Power Input Distribution Box \(PIDB\) with MDP \(A1\)](#) on page 118

Table 1-3 Components and Clearance – Imperial

Component name	Crated		Uncrated					Weight (lb)
	Crate size (") (without dollies) (H×W×L)	Weight (lb)	Minimal dimensions (")					
			Door width	Corridor / elevator width	Corridor / elevator length	Width of corridors w.90° turns	Height	
Pre-installation kit	29.5×5.7×68.9	33	any	any	any	any	any	33
NM gantry with dollies; without collimators	86.6×59×66.1	5320	55.1	55.1	88.6	98.4	78.75	4934
Table	55×35.4×118.1	1731	39.4	39.4	111.4	98.4	any	1228
NM acquisition station	31.5×23.62×23.62	66	any	any	any	any	any	<44
Peripherals and accessories	45.3×39.4×59	110	any	any	any	any	any	110
Collimators on cart/s	67×35.4×45.3	816 (heaviest coll. set)	22	22	39.4	45.3	59	727.5 (heaviest coll. set)
CT gantry, including dollies and side rail	91×54×78.75	870/D670-OPT 4808 D670/BSE 4740	45.3	45.3	110.6	98.4	200	870/D670-OPT 4500 D670/BSE 4586
NM/CT covers	81.5×41.3×77.6	198	any	any	any	any	any	55
Optional Items								
NM UPS	May vary but not more than 23.6×15.7×31.5	May vary but not more than 174	any	any	any	any	any	May vary but not more than 130
<ul style="list-style-type: none"> • ECG Trigger Monitor • Xeleris • SmartConsole • Monitors 	May vary but not more than 31.5×31.5×31.5	May vary but not more than 33	any	any	any	any	any	<28.6
Detectors Dismount Option								
NM gantry without detectors and with dollies	86.6×59×66.1	4795	37.2	37.2	87.4	74	76.7	3726
Detector 1	36.6×33.8×39.4	705	33.8	33.8	39.3	39.3	38.5	705

Table 1-3 Components and Clearance – Imperial (Table continued)

Component name	Crated		Uncrated					Weight (lb)
	Crate size (") (without dollies) (H×W×L)	Weight (lb)	Minimal dimensions (")					
			Door width	Corridor / elevator width	Corridor / elevator length	Width of corridors w.90° turns	Height	
Detector 2	36.6×33.8×39.4	705	33.8	33.8	39.3	39.3	38.5 ^{*7}	705 ^{*8}

*1 The minimum door width required in order to bring the system components into the scan room also depends on the width of the corridor leading to the room. In order to verify that the measurements comply with the requirements, when planning or measuring the width of the scan room door, use the graphs provided in [Figure 1-2 Required Door Opening vs Corridor Width When 90° Turn Required for NM Sub-systems](#) on page 41.

*2 The corridor width required in order to move the system components from the unloading area to the scan room depends on the angles of turns on the corridor. For the required width when the angle is 90, see [Figure 1-3 Required Corridor Width for 90° Turns to Convey NM Sub-system](#) on page 42.

*3 May be delivered a few days prior to system delivery, as part of the final room check and preparation for installation.

*4 SmartConsole is provided only for 870 systems

*5 20 mm clearance above the floor

*6 Weight of gantry in the in-site transportation configuration: 1380 kg + weight of the dolly: 310 kg

*7 50 mm clearance above the floor

*8 The specified weight includes the packing. The detectors must be conveyed crated (unpacking is allowed only at the room or designated area where the detectors to be installed)

Table 1-4 Additional CT-specific Components and Clearance – Imperial

Component name	Crate size (") (without dollies) (H×W×L)	Weight (lb)	Minimal dimensions (")					Weight (lb)
			Door width	Corridor / elevator width	Corridor / elevator length	Width of corridors with 90° turns	Height	
CT PDU	48.4×35.4×27.6	D670/OPT 1015	39.4	39.4	39.4	39.4	any	D670/OPT 815
CT console (NIO)	25.6×18.5×32.6	May vary, but not more than 253.5	any	any	any	any	any	May vary, but not more than 194
CT accessories	45.3×39.4×59	110	39.4	43.3	59	70.8	any	110
CT sub-system covers	75×39.4×67	1183	31.5	31.5	39.4	50.4	78.3	66
NM/CT covers	81.5×41.3×77.6	198	any	any	any	any	any	55
MDP	38.5×28×18	120	any	any	any	any	any	99

Table 1-4 Additional CT-specific Components and Clearance – Imperial (Table continued)

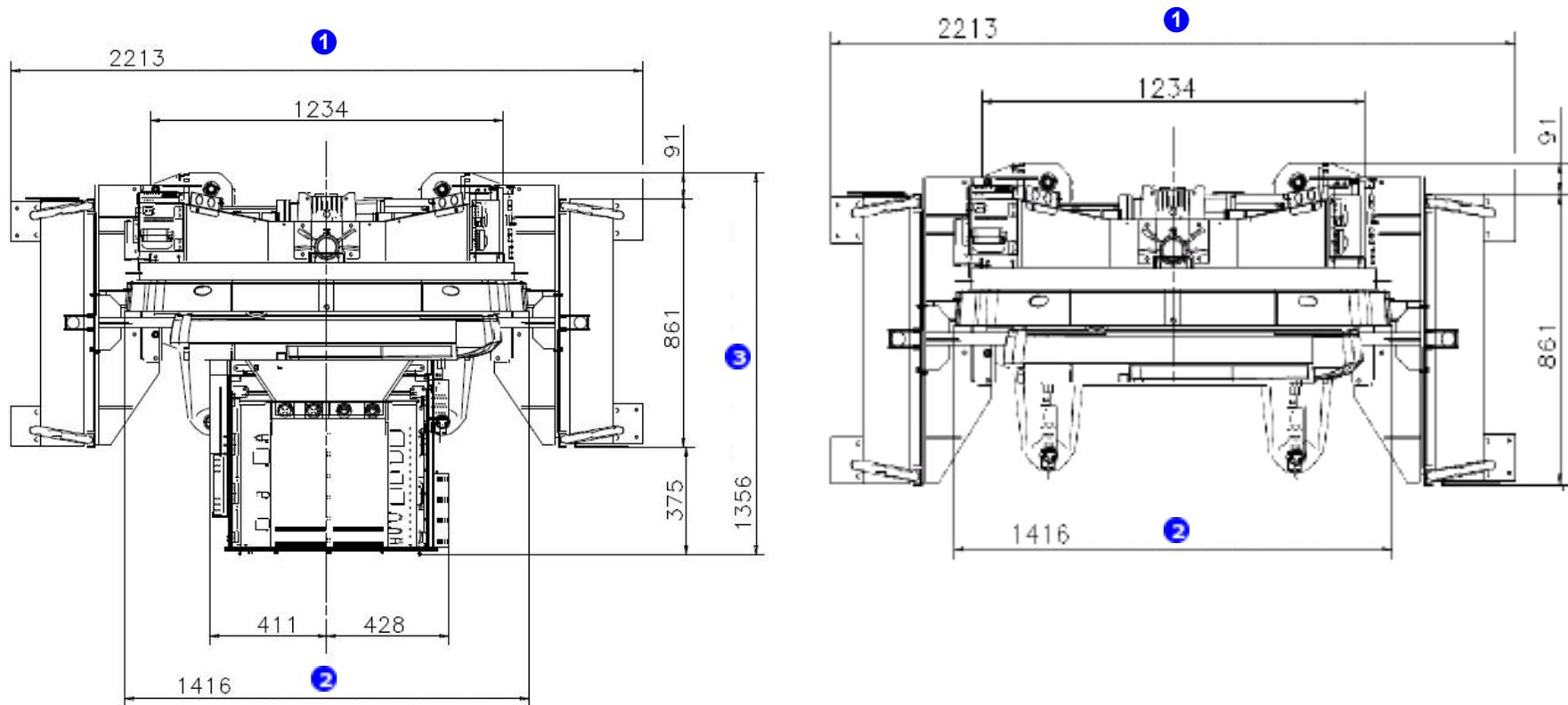
Component name	Crate size (") (without dollies) (H×W×L)	Weight (lb)	Minimal dimensions (")					Weight (lb)
			Door width	Corridor / elevator width	Corridor / elevator length	Width of corridors with 90° turns	Height	
Optional Items								
CT UPS	34×18×32		any	any	any	any	any	452
Contrast Injector	May vary but not more than 31.5×31.5×31.5	May vary but not more than 33	any	any	any	any	any	<28.6
AW Workstation								

- *1 The minimum door width required in order to bring the system components into the scan room also depends on the width of the corridor leading to the room. In order to verify that the measurements comply with the requirements, when planning or measuring the width of the scan room door, use the graphs provided in [Figure 1-2 Required Door Opening vs Corridor Width When 90° Turn Required for NM Sub-systems](#) on page 41.
- *2 The corridor width required in order to move the system components from the unloading area to the scan room depends on the angles of turns on the corridor. For the required width when the angle is 90°, see [Figure 1-3 Required Corridor Width for 90° Turns to Convey NM Sub-system](#) on page 42.
- *3 A1 or other; if ordered from GE, delivered in advance as part of the site preparation and must be installed prior to system installation
- *4 In some cases, an alternative MDP is supplied, in order to comply with local electricity standards, see [5.6.2 Power Input Distribution Box \(PIDB\) with MDP \(A1\)](#) on page 118.

1.3.5 Crated and Uncrated Weights, Measurements and Clearance - Figures

The following figures provide you with crate and component measurements, weights and other data, in order to assist you in planning conveyance routes and storage areas.

Figure 1-1 NM Gantry on Dolly Measurements



Left: WITH Detectors

Right: WITHOUT Detectors

NOTE

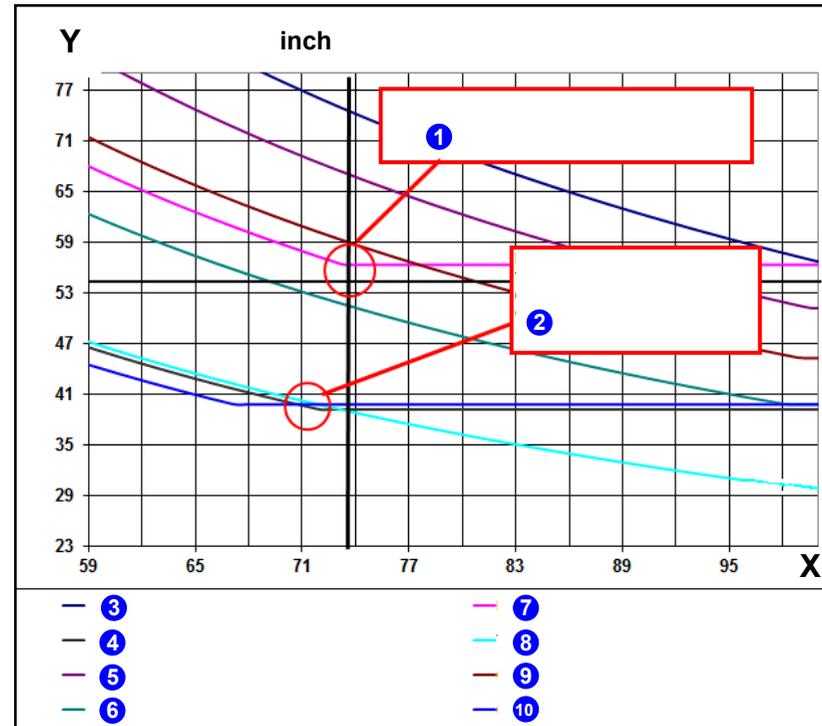
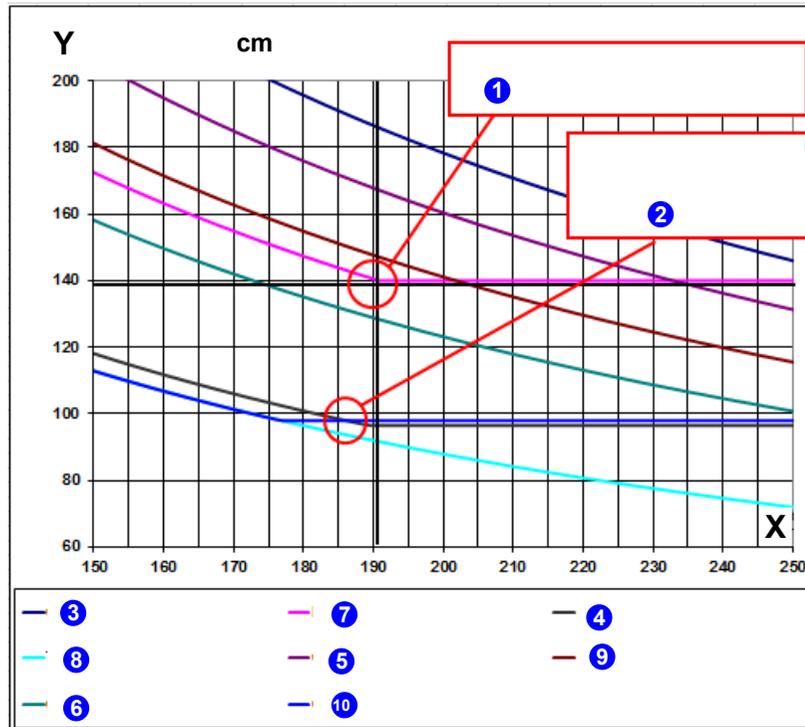
Measurements are in mm

Legend

- (1) The total width depends on the position of the wheels.
- (2) Gantry net width
- (3) Gantry net height

Figure 1-2 Required Door Opening vs Corridor Width When 90° Turn Required for NM Sub-systems

X=Corridor OUT width / Y=Required door opening



Legend

(1) Minimum door opening required to convey sub-systems **WITH detectors** into the room from corridor when 90° turn is required.

(2) Minimum door opening required to convey sub-systems **WITHOUT detectors** into the room from corridor when 90° turn is required.

(3) CT gantry on dolly with two rails

(7) NM gantry with detectors

(4) NM gantry without detectors

(8) Table requirement

(5) CT gantry on dolly with one rail

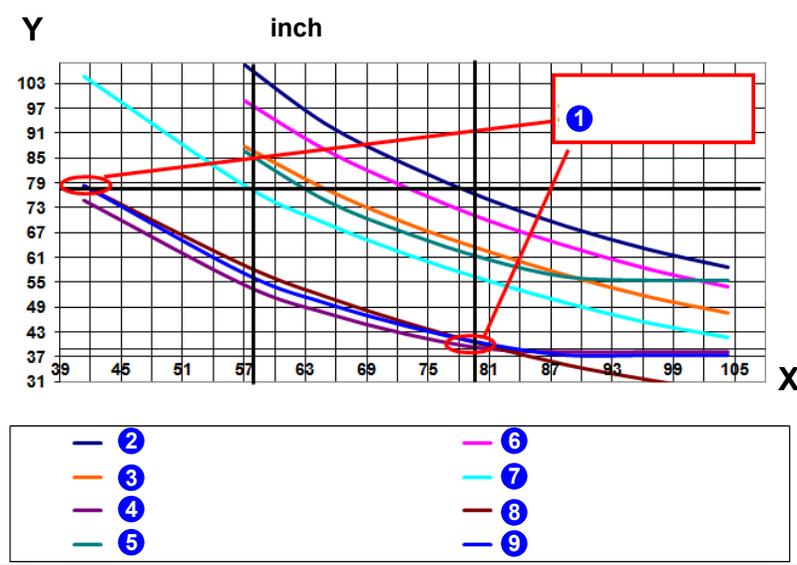
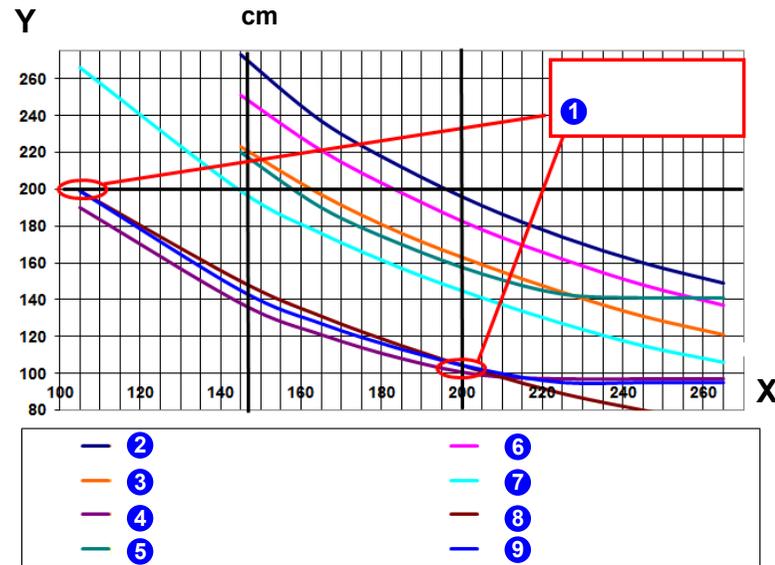
(9) CT gantry on dolly without rails

(6) CT gantry on dolly without covers

(10) CT without dolly & without covers

Figure 1-3 Required Corridor Width for 90° Turns to Convey NM Sub-system

X=Corridor OUT width / Y=Required door opening



Legend

- (1) Minimum required width of corridor to pass 90° turns
- (2) CT with dolly and two rails
- (3) CT with dolly without rails
- (4) CT without dolly no covers
- (5) NM with detectors

- (6) CT with dolly and one rail
- (7) CT with dolly no covers
- (8) Patient table
- (9) NM without detectors

1.4 Product Storage and Handling Requirements

All components must be stored in their original crating.

If the system is to be stored before installation, store in a temperature and humidity controlled environment, and protect from weather, dirt and dust. Storage longer than 12 months is not recommended. Meeting these requirements prevents rust and corrosion from forming on bearing surfaces due to condensation.


CAUTION
DAMAGE TO DETECTORS

Component freezing occurs if the system is exposed to temperatures below -18°C (0°F) for a period of longer than two days.

Gradually adjust the system to ambient room temperature prior to installation, with a change of no more than 3°C (5.4°F) per hour.

Table 1-5 Storage Conditions

Conditions	Short term storage (1-12 months)	
	Storage temperature	+4°C to +27°C
Maximum temperature rate of change	3°C/hr.	5°F/hr.
Relative humidity (non-condensing)	Between 20% and 60%	
Maximum relative humidity rate of change	5%/hr	
Air pressure	Between 700 hPa and 1060 hPa	

Chapter 2 Equipment Description and General Construction Requirements

This chapter provides the following:

- [2.1 Equipment and System Components on page 44](#)

Describes the system and its components.

- [2.2 Room Size, Layout and Considerations on page 53](#)

Provides guidelines for determining the size and layout of the scan and operator rooms and of the above components, including example layouts of typical rooms, illustrating the position and dimensions of the components.

- [2.3 Room Structural Requirements on page 66](#)

Provides floor, ceiling and wall requirements, and acoustic and vibration specifications for the scan room and the operator room.

- [2.4 Seismic Requirements on page 91](#)

Provides center of gravity information for the different system components.

2.1 Equipment and System Components

The system is an NM and CT hybrid system, comprised of an NM camera and a CT scanner. The following figures illustrate the different system components:

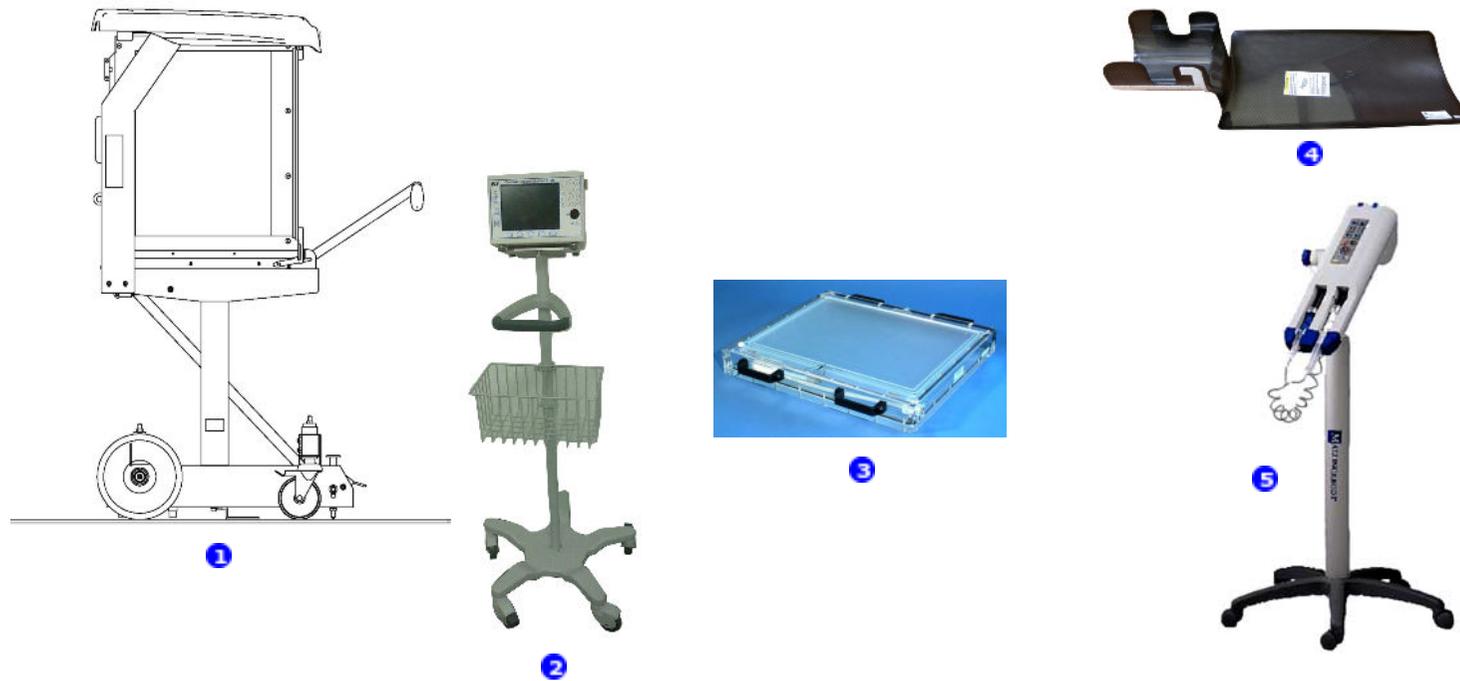
- Scan Room Fixed Components - [Figure 2-1 Scan Room Fixed Components on page 45](#)
- Scan Room Moving Components - [Figure 2-2 Scan Room Moving Components on page 46](#)
- Operator Room Components - [Figure 2-3 Operator Room Components on page 47](#)
- Gantry - [Figure 2-4 Gantry on page 48](#)
- Table Views - [Figure 2-5 Table Views on page 49](#)
- CT Power Distribution Unit (PDU) - [Figure 2-6 CT Power Distribution Unit \(PDU\) on page 50](#)
- Collimator Cart - [Figure 2-7 Collimator Cart on page 51](#)
- CT NIO Console - [Figure 2-8 CT NIO Console on page 52](#)

Figure 2-1 Scan Room Fixed Components



Legend

(1) Power Input Distribution Box (PIDB)	(7) NM detectors
(2) Main Disconnect Panel (MDP)	(8) NM gantry (see Figure 2-4 Gantry on page 48)
(3) NM UPS (optional)	(9) CT gantry (see Figure 2-4 Gantry on page 48)
(4) Gantry display (p-scope)	(10) Patient table (see Figure 2-5 Table Views on page 49)
(5) Boom	(11) CT PDU (see Figure 2-6 CT Power Distribution Unit (PDU) on page 50)
(6) Hand-held controller (RCU)	(12) CT UPS (optional)

Figure 2-2 Scan Room Moving Components**Legend**

(1) Collimator carts (see [Figure 2-7 Collimator Cart on page 51](#))

(2) ECG trigger monitor

(3) Fillable Flood Phantom (H3101AA) (CZT only).

This phantom can be filled with TC^{99m} and used to perform calibrations and quality control procedures. It is recommended for uniformity calibration, especially when performing phantom studies.

(4) Head holder extender (optional)

(5) Contrast injector

Figure 2-3 Operator Room Components



Legend

(1) Xeleris workstation (without desk); can be located in a remote location such as a reading room	(4) 870 only: SmartConsole computer (without desk) Note: Optional upgrade for 850 ES
(2) CT/NM operating console. Desk is for illustration only	(5) NM acquisition computer
(3) AW workstation (optional, without desk)	(6) CT console

Figure 2-4 Gantry

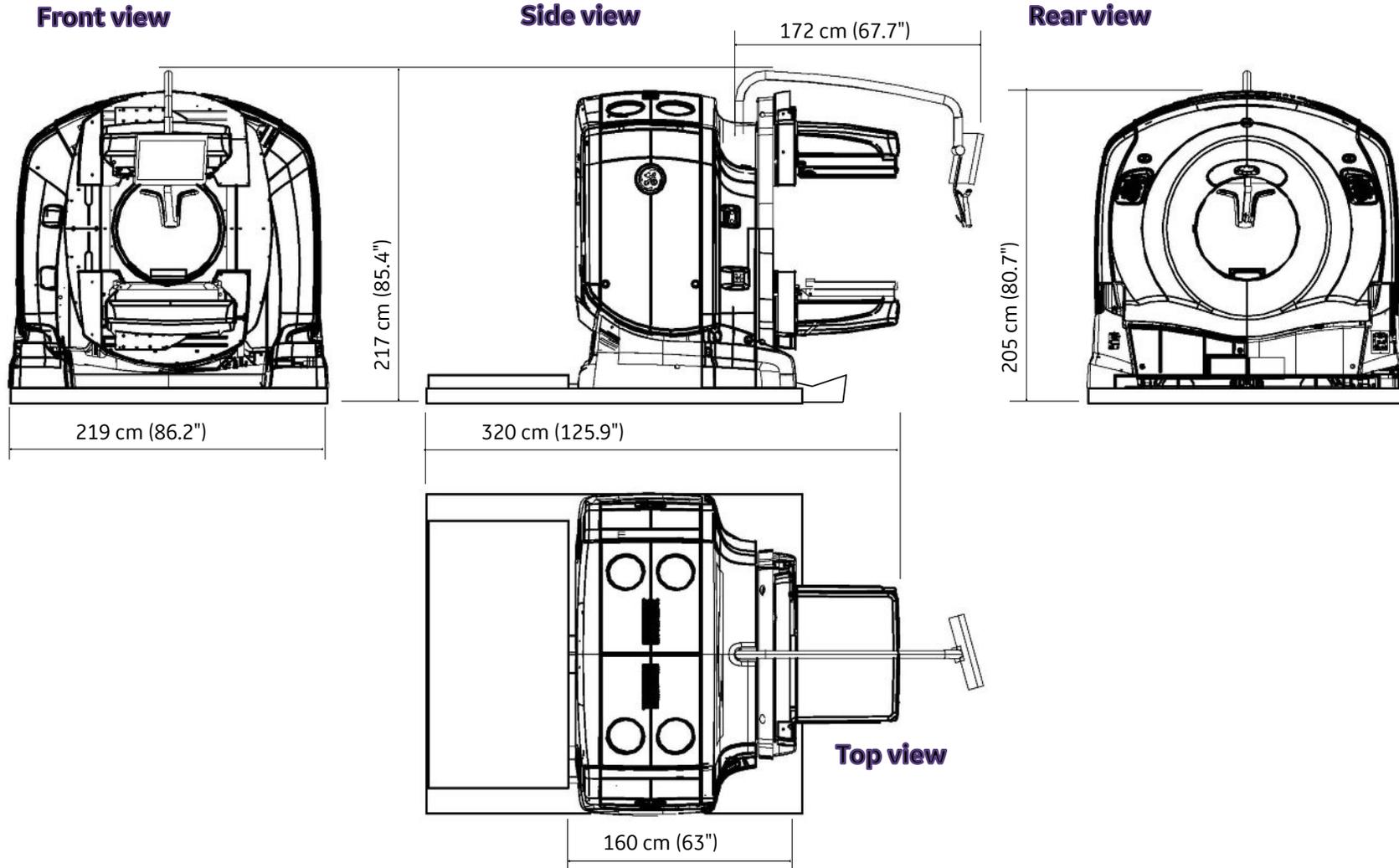
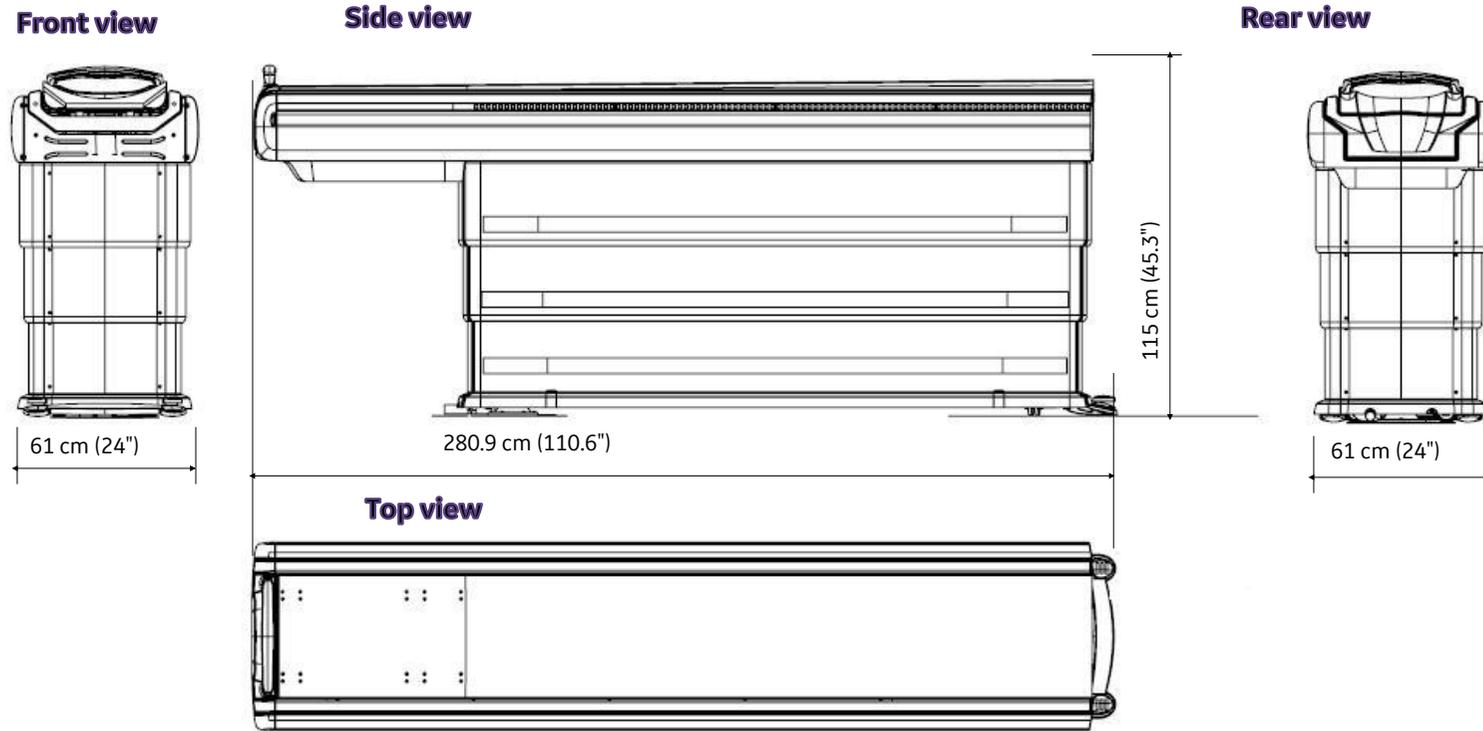


Figure 2-5 Table Views

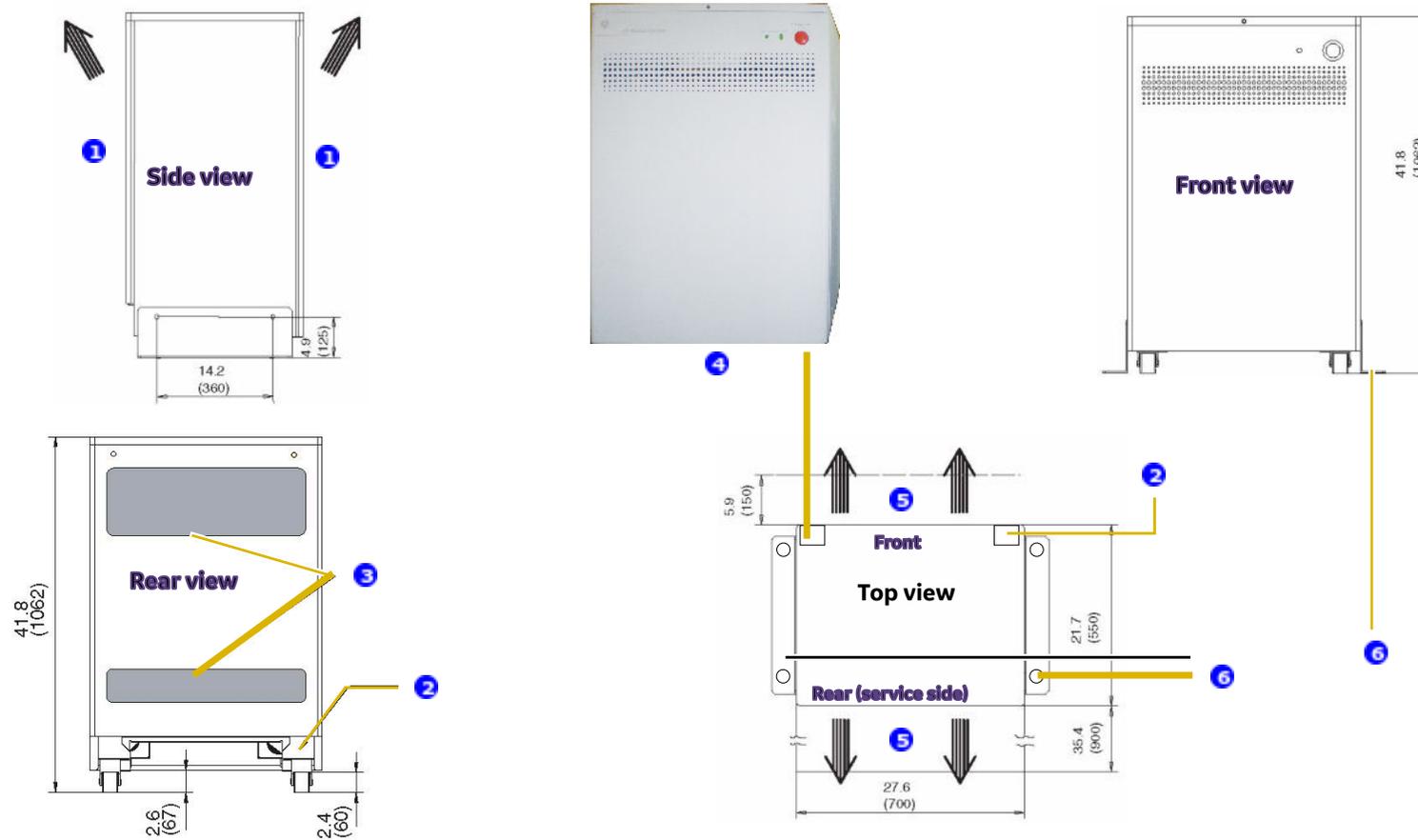


NOTE

Table covers may differ, depending on the table model.

Figure 2-6 CT Power Distribution Unit (PDU)

Dimensions are in inches (millimeters)



Legend

(1) Air Flow	(4) I/O connections panel
(2) AC power input box	(5) Minimum air flow clearance
(3) Air flow vents (convection)	(6) Seismic mounting brackets (4 holes)

Figure 2-7 Collimator Cart

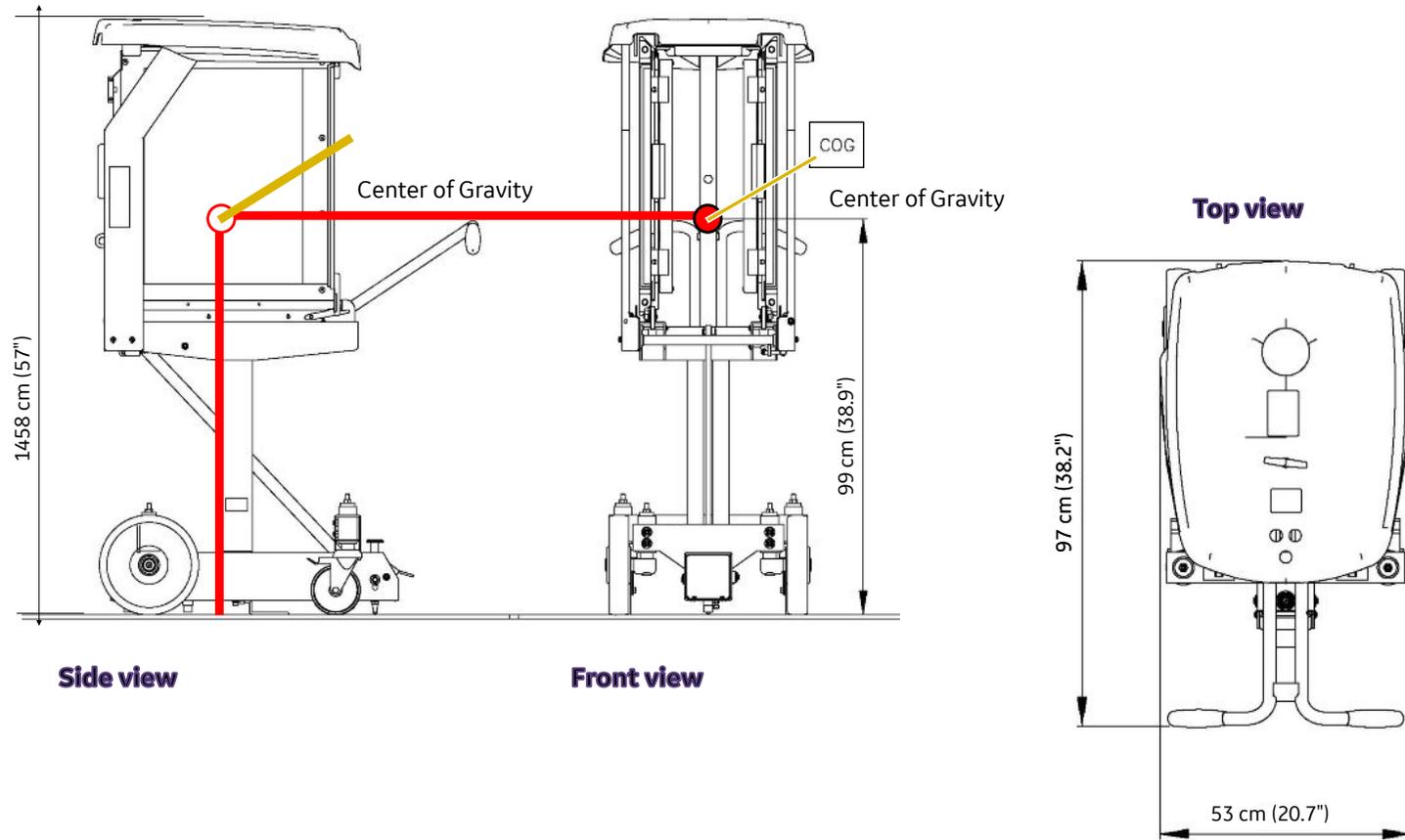
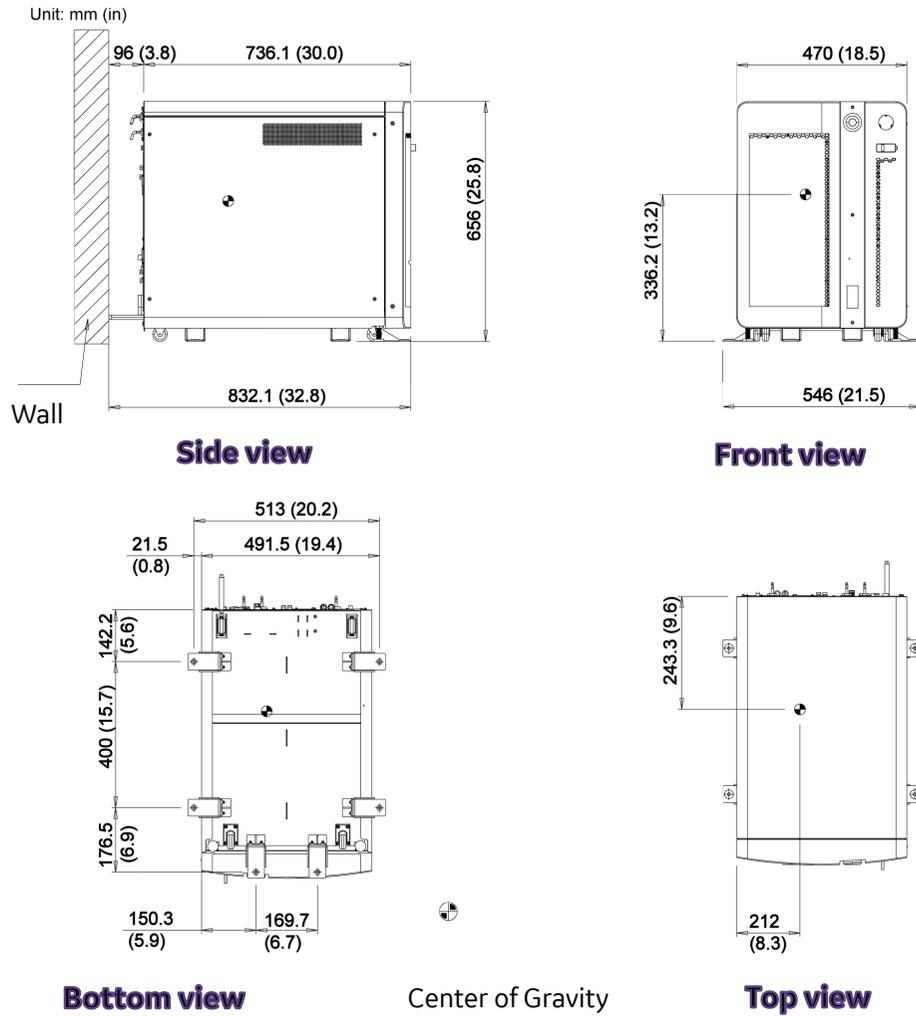


Figure 2-8 CT NIO Console

Dimensions are in mm (")



2.2 Room Size, Layout and Considerations

The system requires a main Scan Room and a separate adjoining Operator Room, which contain the following sub-systems:

Table 2-1 Components in Scan and Console Rooms

Scan Room		Operator Room (see)	Variable location
Fixed Components (see Figure 2-1 Scan Room Fixed Components on page 45)	Moving Components (see Figure 2-2 Scan Room Moving Components on page 46)		
NM gantry	Collimator cart/s	NM acquisition station	Storage cabinet (not supplied with the system)
Patient table	ECG trigger monitor	Xeleris workstation (optional)	
CT gantry	Contrast injector	FWS table (optional, not supplied with the system)	
UPS (optional)* ¹		Operator chair	
CT PDU		CT console	
MDP		AW workstation (optional)	
PIDB		SmartConsole workstation (870 only)	
EMO (wall mounted)			

*1 When a full-load UPS is used, it is recommended to install the UPS in an isolated room as the UPS adds to noise and heat dissipation levels. This should be coordinated with GE and taken into consideration when planning the room size.

This section provides guidelines for determining the size and layout of the scan and operator rooms and of the above components, and example layouts of typical rooms, illustrating the position and dimensions of the components.

The room layouts provided take into consideration all aspects of operation, operator and patient requirements and service clearance requirements.

Egress

The room layouts, diagrams and dimensions in this manual provide the required clearances for proper equipment operation and service only. The customer/purchaser is responsible for compliance with federal, state and/or local codes regarding facility egress and related facility requirements (see [Appendix D Regulatory Clearances on page 149](#)).

2.2.1 Room Dimension Requirements

NOTE

The minimal and standard system layouts described in this manual may not comply with specific local/regional/country/state requirements (such as OSHA in the USA).

Take into consideration the local regulations in force when planning room dimensions and layout (see [Appendix D Regulatory Clearances on page 149](#)).

Minimal scan room size, without operator room (L × W × H)

6.3 m×3.7 m×2.35 m (20' 8.03"×12' 1.66"×7' 8.5")

See [Figure 2-10 Minimal Room Layout on page 57](#))

870/D670-OPT:

Reduced service clearance configuration, without operator room (L × W × H)

6.15 m×3.59m×2.35 m (20.17"×11.8"×7' 8.5")

Service, egress and workspace are compromised in this configuration.

2.2.2 System Layout Drawings

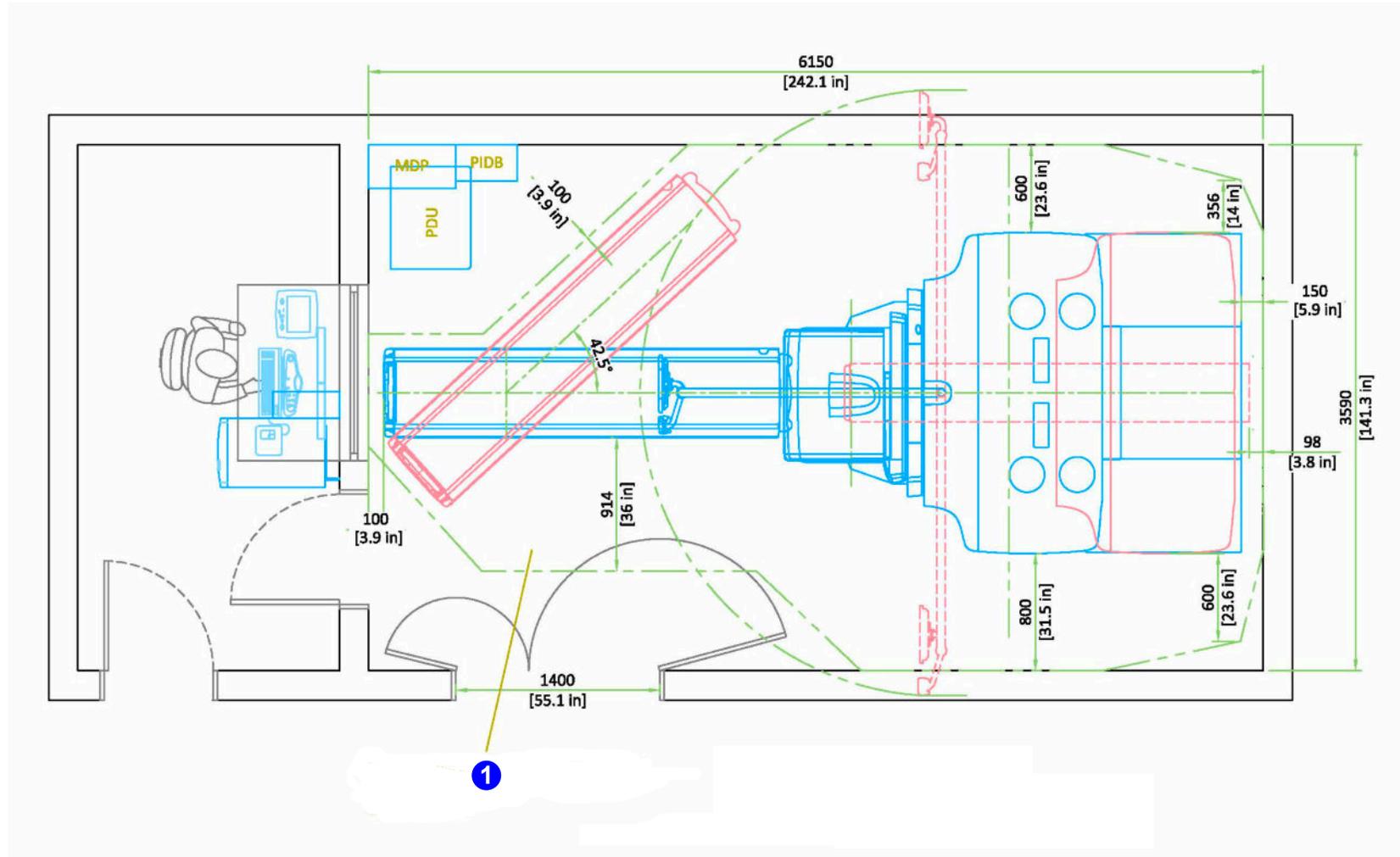
This section provides typical sample layouts, illustrating the position and dimensions of the scan/operator room and the system components, including:

- Reduced Serviceability Room Layout - [Figure 2-9 Reduced Serviceability Configuration Room Layout on page 55](#)
- Minimal Room Layout - [Figure 2-10 Minimal Room Layout on page 57](#)
- Example of Room Layout - [Figure 2-11 Example of Room Layout on page 59](#)

The room layout dimensions take into consideration all aspects of operation, operator and patient requirements and service clearance requirements (see [2.2.4 Layout Considerations on page 63](#)).

Sufficient regulatory and service clearances must be maintained around the equipment for full operation, service, and safety.

Figure 2-9 Reduced Serviceability Configuration Room Layout



Legend

(1) Service clearance has to be maintained on either side of the table, opposite to the slant direction.

Notes to figure:

- Dimensions are in mm [in"]

- Defines the minimum area required to enable installation, operation and service of the system in safe conditions.
- Does not take into account local requirements. If local requirements are stricter, they should be followed (see [Appendix D Regulatory Clearances on page 149](#)).
- Operator movement around the system is limited.
- Cannot use table extender.
- Does not take into account space for the following: Operator room / Collimator carts / Optional UPS No option for permanent objects around the CT (for example: wall ducts, sink, cabinet). Requires Small Room CT Gantry Installation Dolly during installation.
- Service clearance has to be maintained on either side of the table, opposite the slant direction.

D670/OPT Reduced Service Clearance Configuration

NOTE

D670/OPT Only

This section is relevant only for D670/OPT systems.

- In the reduced service clearance configuration, service, egress and workspace around the gantry are compromised.
- No permanent objects that reduce the CT service area around the gantry are allowed in this reduced minimal configuration.

Important

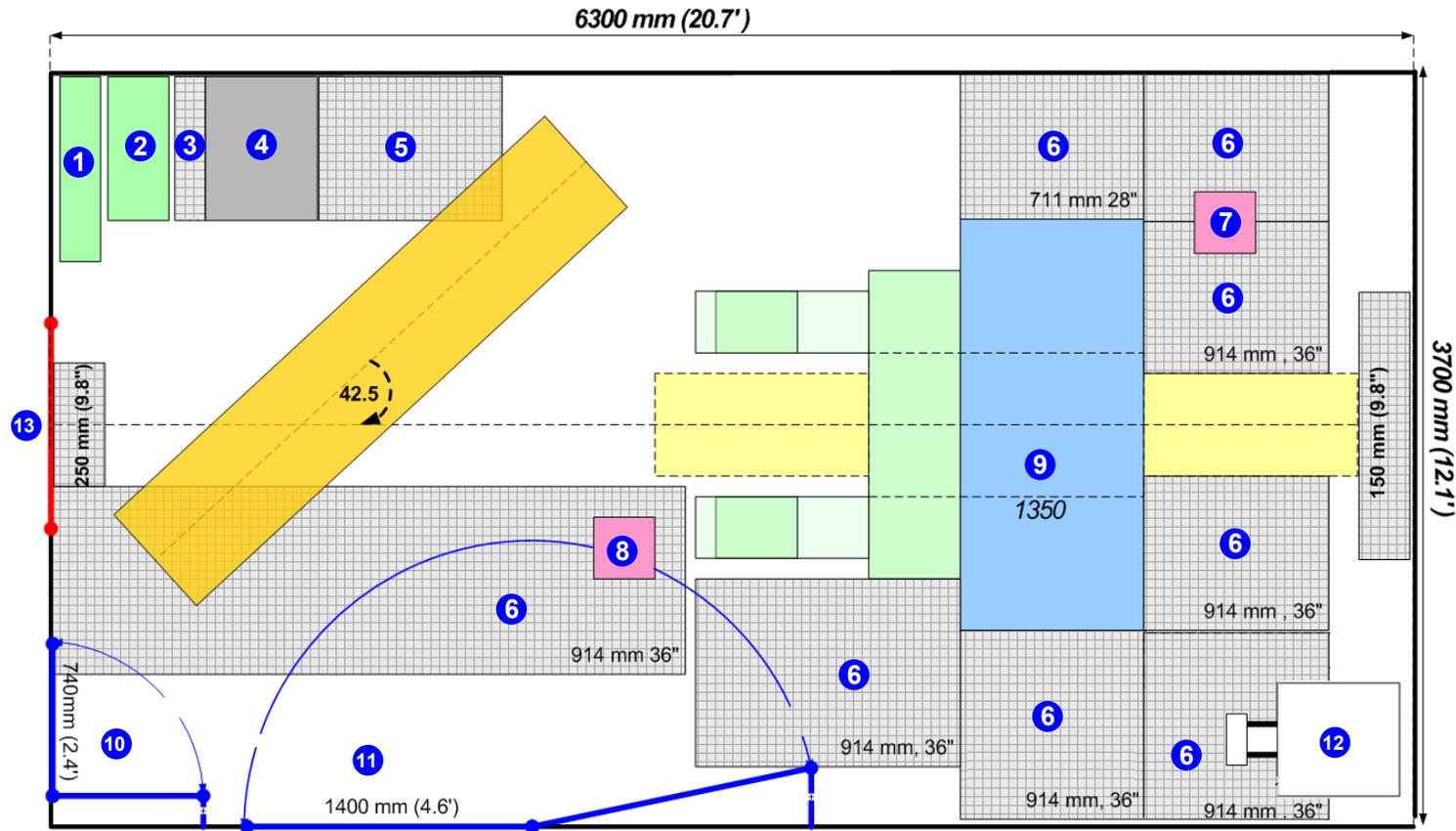
The reduced service clearance configuration severely limits space for patient care and workflow. Customer approval of site drawings signifies customer agreement to these limitations.



LIMITED EQUIPMENT AND PATIENT ACCESS

In the reduced service clearance configuration, the customer should consider workflow, customer access for patient care, and critical-care operations space requirements. Additionally, this configuration may offer only limited equipment access on the CT gantry left side when loading patients or when positioning patient equipment in the room between the gantry and the wall.

Figure 2-10 Minimal Room Layout



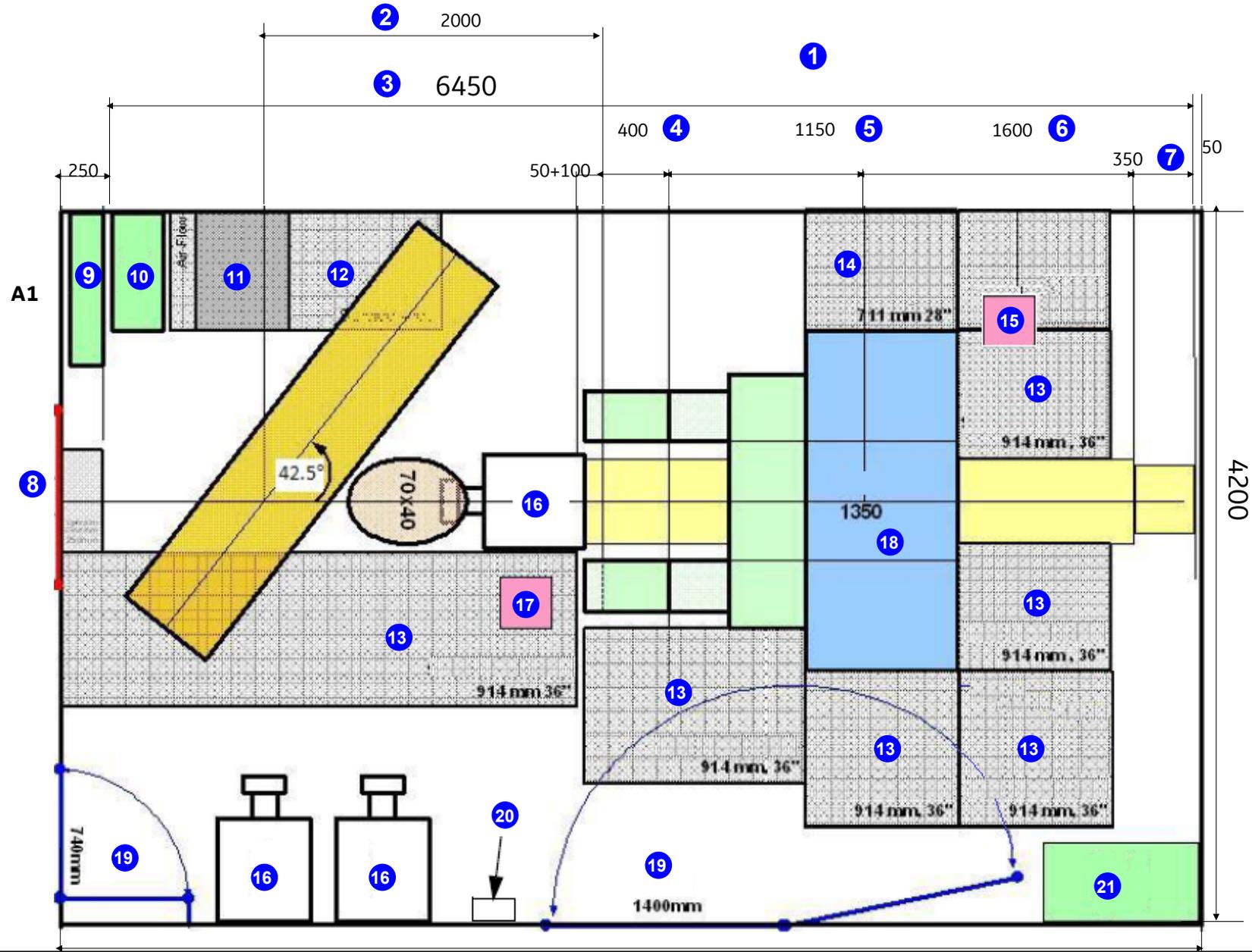
Legend

(1) MDP + PIDB	(6) Service clearance	(11) Door
(2) CT UPS	(7) Injector cart	(12) Cart
(3) Airflow	(8) ECG cart	(13) Lead glass window
(4) PDU	(9) Bore	
(5) PDU Service area	(10) Staff door	

Notes to figure:

- Defines the minimum area required to enable installation, operation and service of the system in safe conditions.
- Does not take into account local requirements.
- Operator movement round the system is limited.
- Cannot use table extender.
- The operator room is not taken into account in the room dimensions.
- Space must be allocated for the operator room. The location can differ.

Figure 2-11 Example of Room Layout



Legend

(1) Optimal + Extender Layout	(8) Lead glass window	(15) Injector cart
(2) Pivot	(9) CT UPS	(16) Cart
(3) Footprint	(10) Airflow	(17) ECG cart
(4) FOV	(11) PDU	(18) Bore
(5) NM FOV to CT	(12) PDU Service area	(19) Door
(6) CT scan length	(13) Service clearance	(20) EMO
(7) Extender	(14) OSHA egress	(21) Storage cabinet

Notes to figure:

- Dimensions are in mm
- Defines the recommended room dimensions required to enable installation, operation and service of the system in safe conditions.
- Does not take into account local requirements.
- Enables relative freedom of movement for operator and service.
- Enables installation of table extender.
- Can keep more than one collimator cart in the room, if relevant.
- The operator room is not taken into account in the room dimensions.
- Space must be allocated for the operator room, but the location can differ.

2.2.3 System Mechanical Curves

Component Movement Curves [Figure 2-12 Component Movement Curves on page 62](#) illustrates the table and gantry movement.

In addition, the contrast injector, ECG trigger monitor and collimator carts can be moved to different locations in the scan room, as demonstrated in the layout illustrations in:

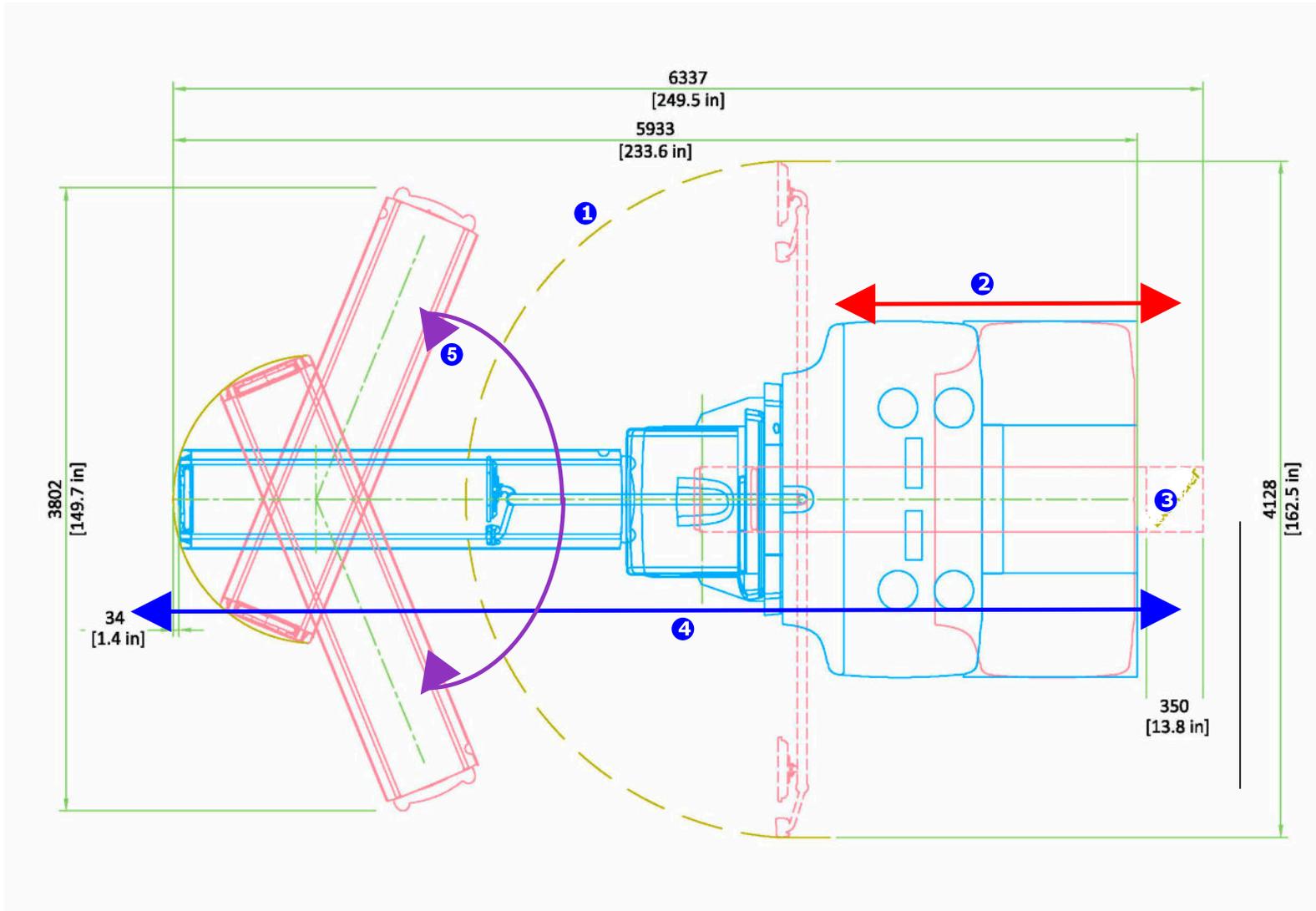
- *Minimum Room Layout* [Figure 2-10 Minimal Room Layout on page 57](#)
- *Example of Room Layout* [Figure 2-11 Example of Room Layout on page 59](#)
- *Reduced Serviceability Configuration Room Layout* [Figure 2-9 Reduced Serviceability Configuration Room Layout on page 55](#)

NOTE

In order to prevent collision with the gantry display boom, do not mount any equipment from the ceiling.

Table slanted at	Farthest point relative to system's center line
67.5°	190.5 cm (75")
55°	181.5 cm (71.5")
42.5°	157.5 cm (62")

Figure 2-12 Component Movement Curves



Legend

(1) Boom left and right swivel movement

(4) Table longitudinal movement

(2) Gantry backward/forward movement on floor rail (service only)	(5) Table left and right swivel movement round anchor axis
(3) Extender	

NOTE

Dimensions are in feet, inches (mm).

2.2.4 Layout Considerations

This section describes the considerations you must take into account when selecting a site and planning the room size and layout. In addition, it is the responsibility of the customer to ensure that all aspects of the scan and operator rooms conform with the local requirements.

Room Dimensions and System Placement

The room size and shape and the placement of the system components must enable optimal functional and working conditions, including the best possible relative positioning of the gantry, patient table and acquisition console in operator room, including:

- **Operator access in scan room**, around the gantry and patient table in order to:
 - Assist patient positioning
 - Perform examination routines
 - Act efficiently and quickly in case of an emergency, including easy access to emergency switch
- **Upgrade considerations:**
 - If a system upgrade is planned or possible, the requirements for the larger system should be assessed to avoid unnecessary future rework:
 - Room dimensions
 - Power requirements
 - HVAC requirements
 - Floor loading requirements

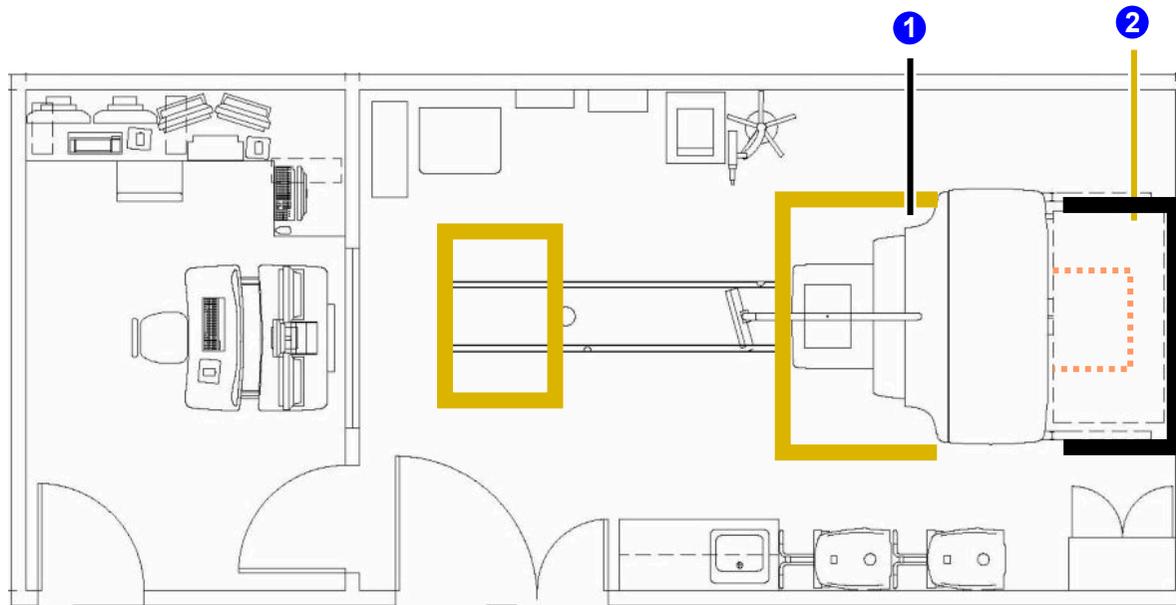
- **Seismic considerations:**

The room dimension requirements are different for seismic systems. For example, the table must have the clearance necessary to swing both ways in order to access all anchoring.

- **Safety zone considerations**

The safety zone is designated by tape on the floor, usually yellow (can also be differentiated by a change in floor coloring). This designates the area that must be free of obstructions to avoid a collision during automatic motion.

Figure 2-13 Safety Zone Marking



Legend

- (1) Detector motion area
- (2) Pallet motion area

• Operation-related considerations:

- Enable access for hospital beds, including maneuvering and positioning the bed and moving the front of the patient table during collimator exchange.
- Storage of collimator cart/s when not in use
- ECG Trigger Monitor and Contrast Injector– cable position and lengths and storage when not in use
- Space for storage and usage of ECG Trigger Monitor and Contrast Injector
- Installation and service considerations:
- Location of power connections

- Access to communication lines (Ethernet, external hardcopy device)
- Floor loading capacity and weight of system components, including storage and path of collimator carts
- Service clearance areas (see [Appendix D Regulatory Clearances on page 149](#))
- Storage cabinet for storage of service tools (optional). Depending on the room layout, it is recommended that sufficient area is allocated for a cabinet.
- Patient path from entry door to table should be without any floor hazards such as a table floor puck, conduit or cables.
- **Operator room**
 - Operator field of view, enabling direct view of patient in bore, or taking into consideration viewing via remote closed-circuit camera in the scan room and screen in the operator room
 - Radiation shielding, electromagnetic shielding, etc.
 - Space, power and network connections for additional equipment such as PACS workstation, archiving devices, etc.
- **Proximity of scan room to other utilities**
 - Avoid detrimental influences from surrounding rooms and activities, such as:
 - Radioactive or magnetic sources
 - A local wireless environment
 - Vibrations
 - Transformers from elevators, compressors, or other high power devices.
 - Plan the optimal proximity of the scan room to related utilities. In addition to patient comfort, take into consideration that background radiation activity from such utilities could negatively affect image quality and system calibration. These utilities include:
 - Waiting/injection areas, toilets
 - Viewing and processing rooms
 - Radionuclide storage and preparation area
 - Office facilities
 - Smoke detectors that use/have radioactive activity

2.3 Room Structural Requirements

Room requirements consist of the following:

- [2.3.1 Floor Requirements on page 66](#), including floor strength, anchoring, levelness and flatness, vibration and conductivity
- [2.3.1.2 Floor Loading Requirements on page 67](#)
- [2.3.2 Ceiling Requirements on page 88](#)
- [2.3.3 Wall Requirements on page 88](#)
- [2.3.4 Acoustic Specifications on page 89](#)
- [2.3.5 Vibration Specifications on page 89](#)

2.3.1 Floor Requirements

Important

It is the customer's responsibility to have appropriate tests performed and to obtain a construction engineer's assessment of the floor's suitability to meet the requirements of this section.

2.3.1.1 Floor Strength

In order to enable system mounting using the supplied floor anchors, concrete floors must have a minimum cube strength of $f'c = 4350$ psi (30 MPa) at 28 days (curing time) for 25/30 concrete and must be at least 166 mm (6.5") thick.

order to enable system mounting using the supplied floor anchors, concrete floors must have a minimum cube strength of $f'c = 4350$ psi (30 MPa) at 28 days (curing time) for 25/30 concrete.

NOTE

- Concrete strength is determined by the "Cylinder Test" (used in the USA) or "Cube Test" (used in Europe), where a cylinder or cube of concrete is cast, cured for the appropriate time and then compressed between two parallel faces until failure. The stress at the failure is taken to be the compressive strength of the concrete. The 25/30 concrete required for the system installation is concrete with a strength of 25 in the cylinder test (resulting 3625 psi), or strength of 30 in the cube test (resulting 4350 psi).
- If the system is expected to be upgraded in the future, the floor strength requirements for the larger model should be used.

It is the customer's responsibility to have appropriate tests performed to determine and measure concrete strength, and to obtain a construction engineer's assessment of the floor load capability.

2.3.1.2 Floor Loading Requirements

Table 2-2 Weight of Components

Component	Weight (kg)	Weight (lb)	Load Distribution	Comments
NM gantry (with HEGP collimators mounted on system)	2190	4828	4 pads, Ø83 mm each: +845 kg each on front pads +250 kg each on rear pads	
Patient table (without patient)	557	1228	2 wheels + axis anchored to floor	Weight of table without patient
Storage cabinet, including tools (optional)	< 130	< 287	4 legs	
CT gantry	870/D670-OPT: 1890 D670/BSE: 1850	870/D670-OPT: 4166 D670/BSE: 4078		
CT PDU	870/D670-OPT: 370 D670/BSE: 350	870/D670-OPT: 815 D670/BSE: 772	4 wheels; anchored to floor	
CT NIO console	89	196	4 wheels	
AW workstation (optional)	30	66	Placed on desk	
Collimator cart (with 2 HEGPs on cart)	330	728	4 wheels	COG point at 99 cm height; may be more than one collimator cart in scan room
NM Acquisition station	11.3	25		
ECG Trigger Monitor, Operator chair, Contrast Injector	(insignificant)	(insignificant)		
Personnel and patient	< 500	< 1102	Variable	Normally 3-4 people in room during scan/service operations
LEHR collimator	62	137		2 per system/cart
LEGP collimator	55	121		2 per system/cart
ELEGP collimator	62	137		2 per system/cart
MEGP collimator	103	227		2 per system/cart
HEGP collimator	131	288		2 per system/cart
CT UPS (optional)	350	772	4 wheels; Anchored to floor	

Table 2-2 Weight of Components (Table continued)

Component	Weight (kg)	Weight (lb)	Load Distribution	Comments
SmartConsole workstation (870 only)	11.3	25		

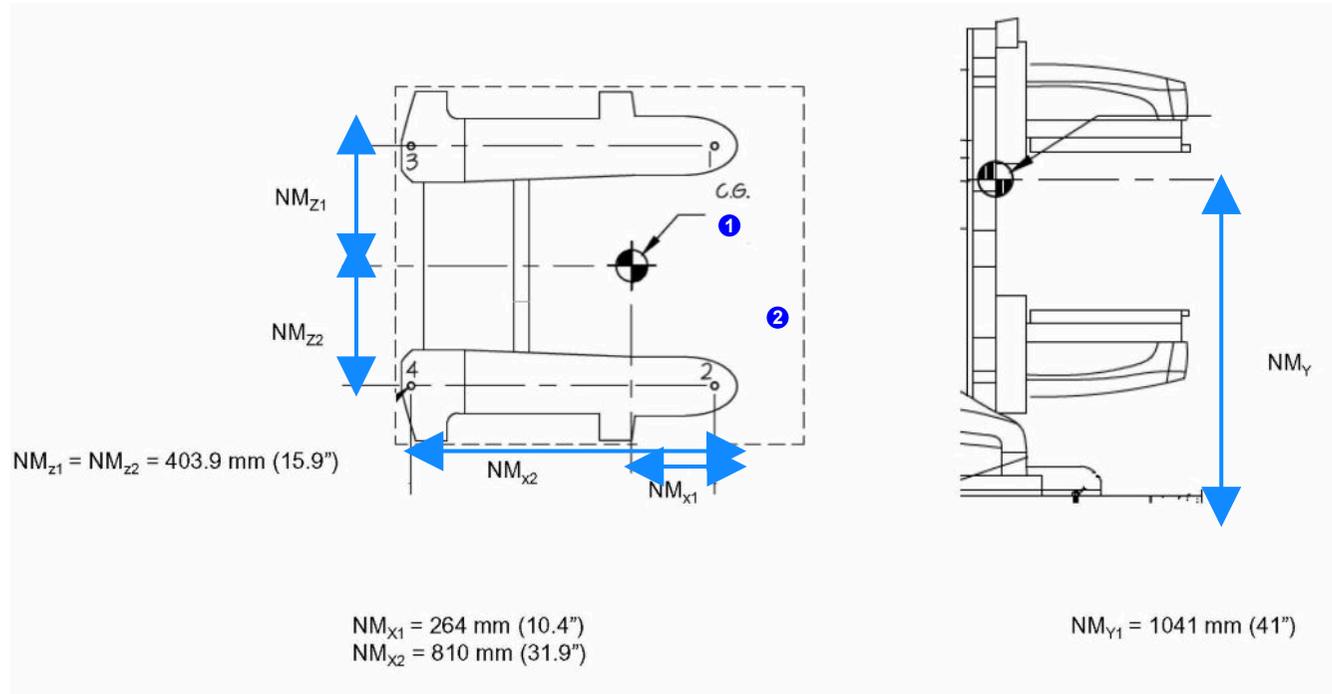

CAUTION
ENSURE CORRECT FLOOR AND ANCHORING

If the system is installed on a floor type thinner than a 166 mm (6.5") concrete floor, the customer shall, at their expense, provide acceptable anchoring and mounting methods that meet all structural specifications provided in sections [2.3.1.2 Floor Loading Requirements on page 67](#) and [2.3.1.3 Floor Anchoring on page 75](#) of this manual.

The customer shall ensure that the floor strength in the collimator cart storage area and along the movement routes for collimator exchange are suitable for the collimator cart load (approx. 250 kg each).

Figure 2-14 NM Gantry with HEGP Collimators Center of Gravity Points

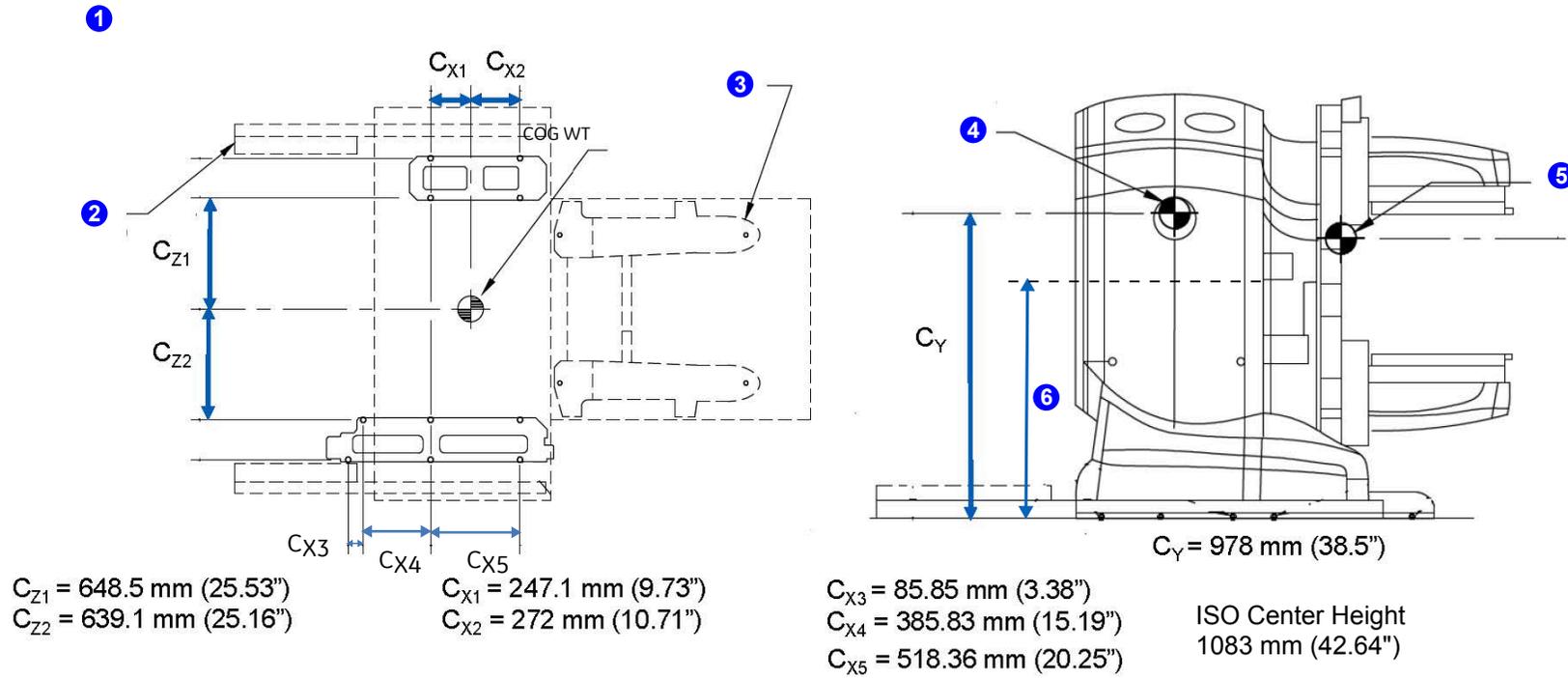
NM gantry CoG weight: 2190 Kg (4828 Lb.)

**Legend**

(1) Center of gravity

(2) Front

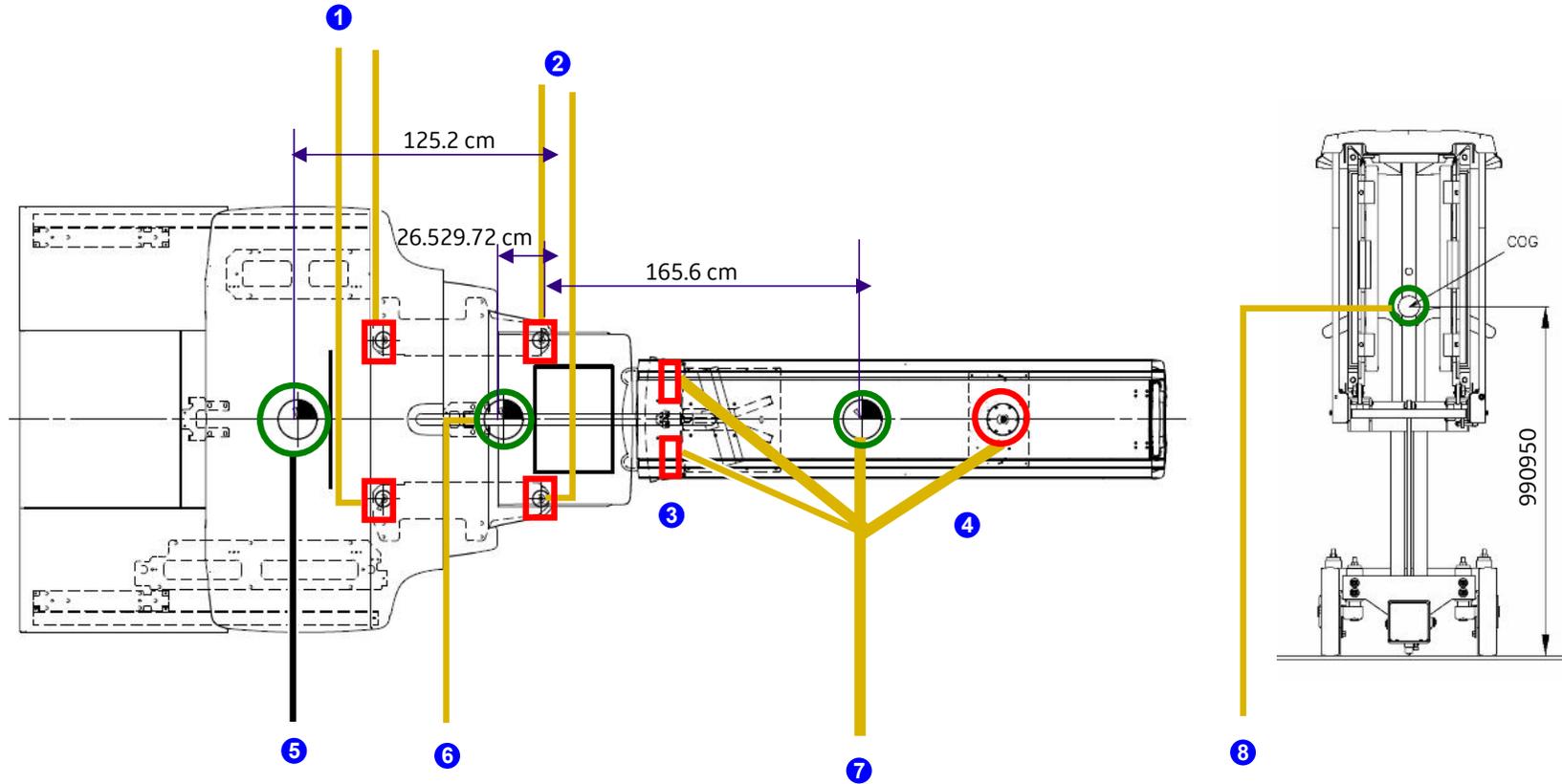
Figure 2-15 CT Gantry Center of Gravity Points



Legend

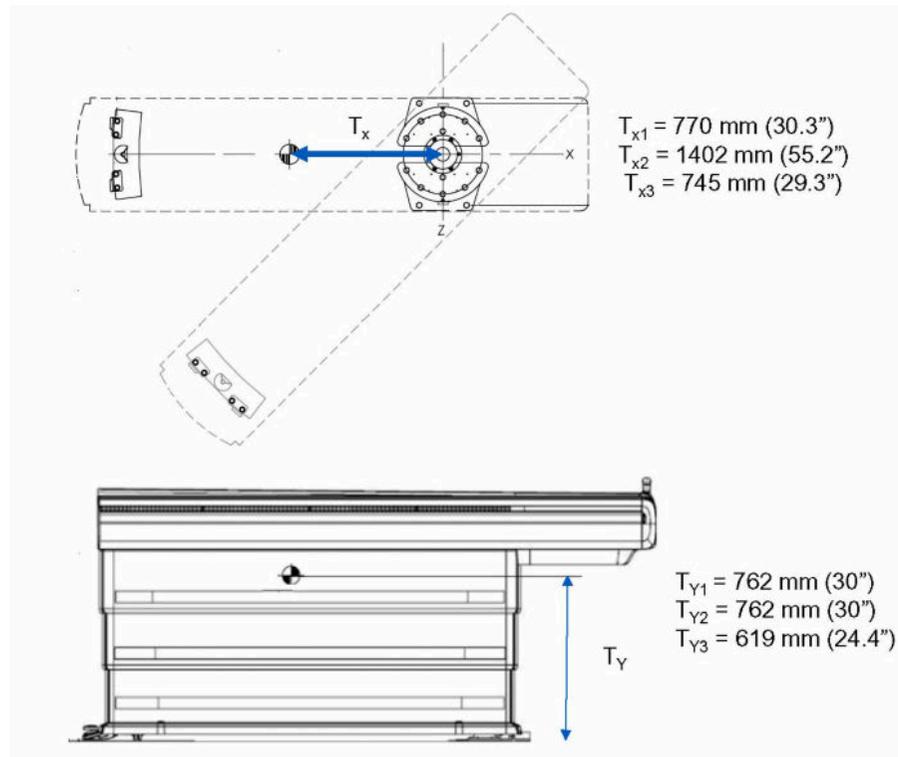
(1) CT gantry CoG weight: 1890 Kg (4166 Lb.)	(4) CT gantry center of gravity
(2) Floor rails for servicing (not structural)	(5) NM gantry center of gravity
(3) NM gantry base	(6) ISO center height 1083 cm (42.64")

Figure 2-16 Floor Loading and Center of Gravity Points for Gantry, Table and Cart



Legend

(1) NM gantry rear pads 250 kg load per pad	(5) CT gantry center of gravity D670-OPT 1890 kg / D670-BSE 1850 kg
(2) NM gantry front pads 845 kg load per pad	(6) NM gantry center of gravity 2190 kg
(3) Two wheels	(7) Table center of gravity 557 kg load (distributed on 2 wheels + pivot). For details, see Figure 2-17 Table Center of Gravity Points on page 72
(4) Pivot diameter 16.5 cm	(8) Collimator cart center of gravity 300 kg load (for heaviest set), including collimator; up to 3 carts in the scan room.

Figure 2-17 Table Center of Gravity Points**Case #1 (Tx1, Ty1):**

- Table loaded with 350 lb.
- Cradle retracted, table at maximum UP

Case #2 (Tx2, Ty2):

- Table loaded with 350 lb.
- Cradle fully expanded (inside gantry), table at maximum UP

Case #3 (Tx3, Ty3):

- Table unloaded (no patient)
- Cradle retracted and at table at maximum UP

Figure 2-18 NIO Console Center of Gravity

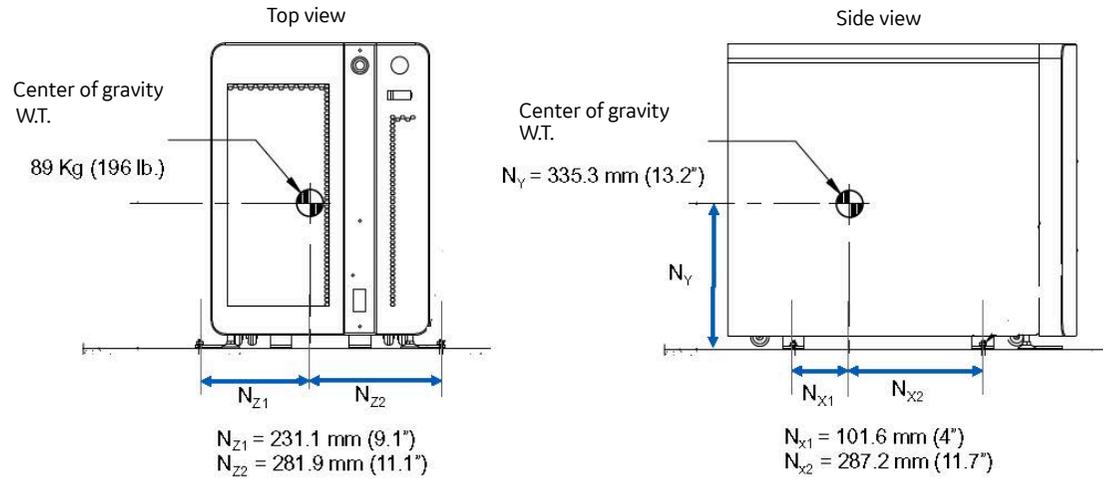


Figure 2-19 CT PDU Center of Gravity

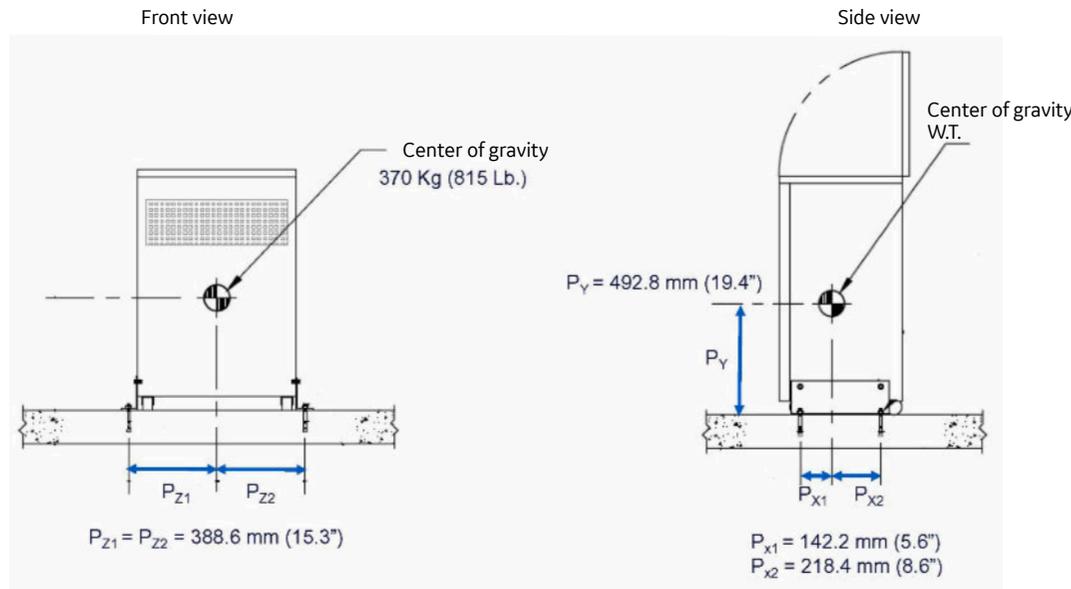


Figure 2-20 CT PIDB Center of Gravity

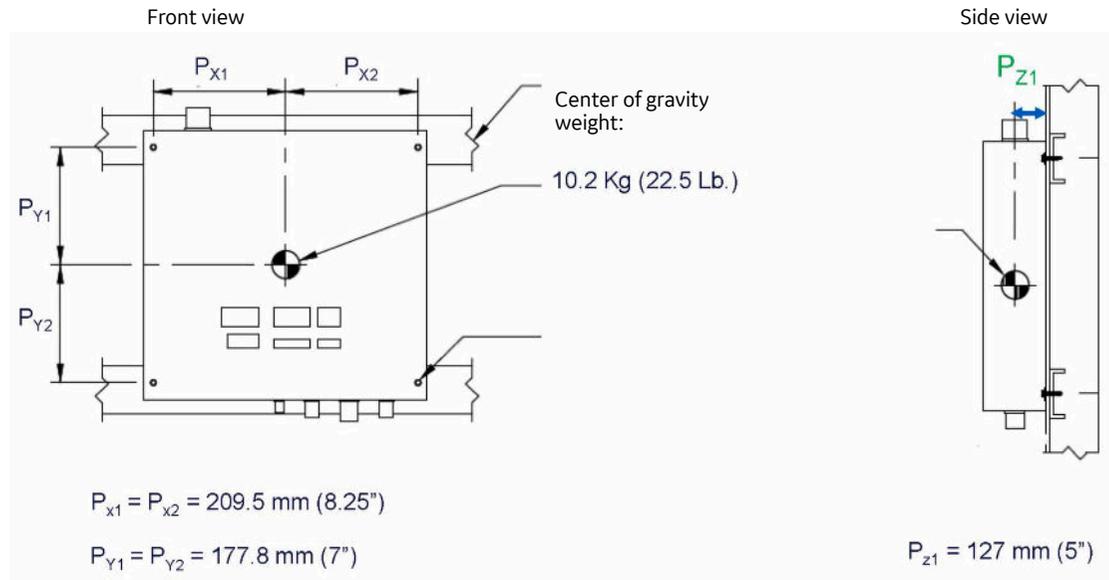
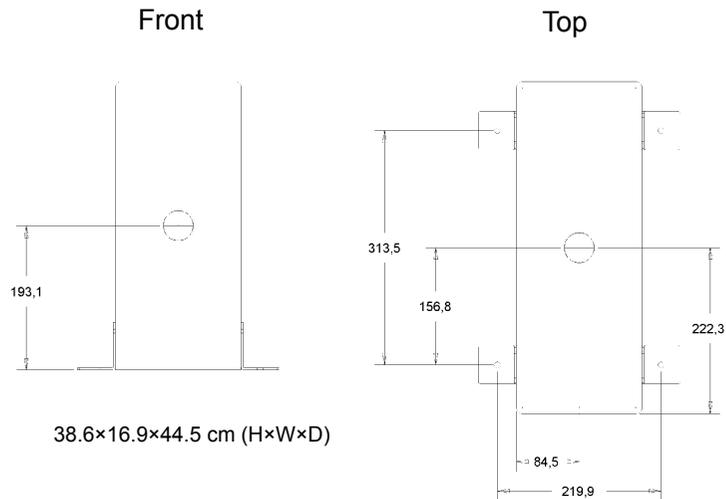


Figure 2-21 NM Acquisition Computer Center of Gravity Points



2.3.1.3 Floor Anchoring

The system's floor anchors are designed for use **only** on concrete floors that meet the minimal 166 mm (6.5") concrete floor requirements.

 **CAUTION**

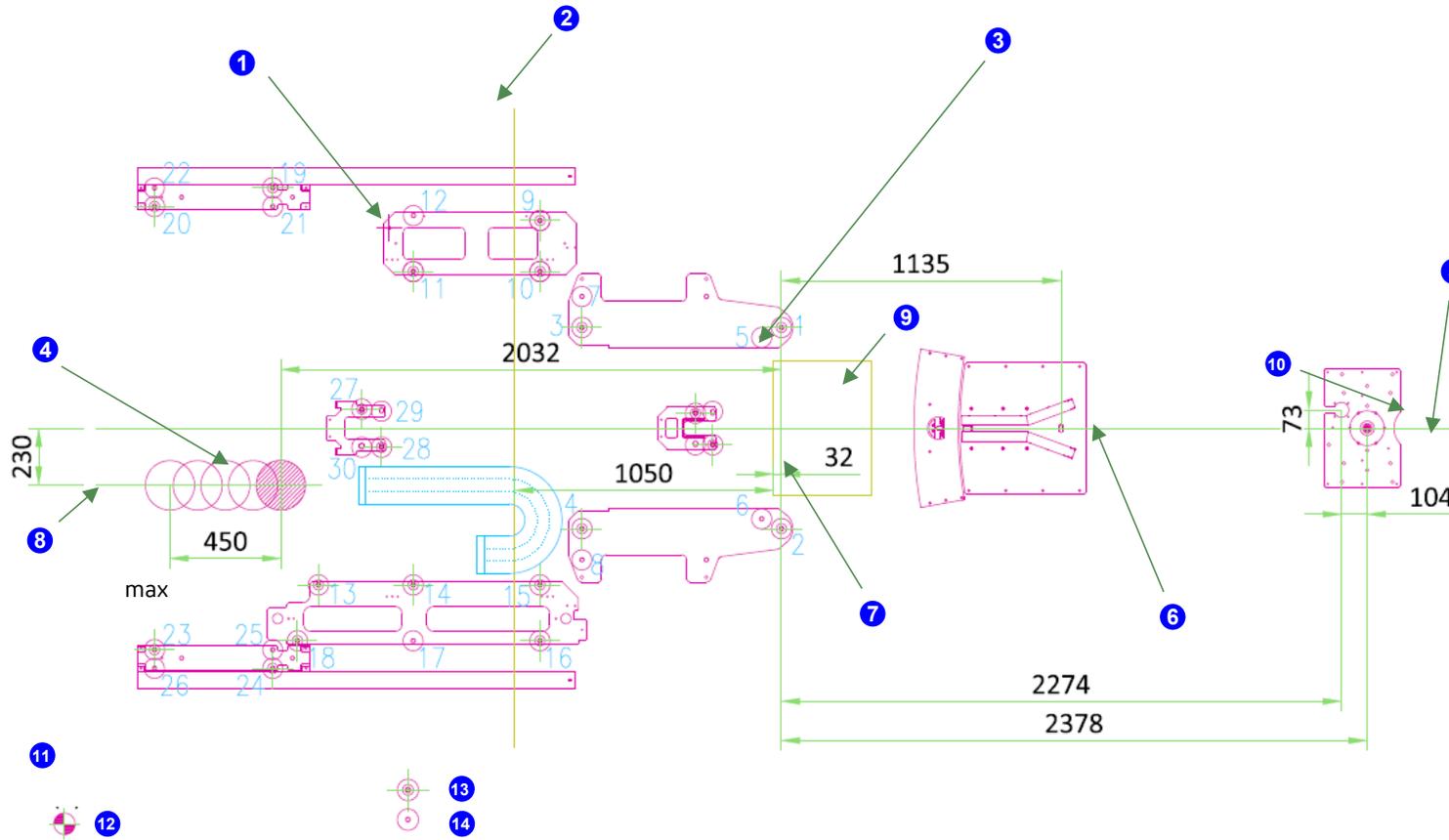


ENSURE CORRECT FLOOR AND ANCHORING

For concrete floors thinner than 166 mm or different floor types other anchoring methods might be required. These must comply with the minimum load requirements (see [2.3.1.2 Floor Loading Requirements on page 67](#)) and must be installed and tested at the customer's expense, by the customer's structural contractor. The selected anchoring method must have a pulling tensile force of 19.7 kN on each of the anchors bolting the NM gantry to the floor.

In such a case, the alternative anchors shall be installed during system installation, and this must be coordinated with the installation team. For anchor point information, see [Figure 2-25 Floor Anchor Points on page 79](#).

Figure 2-22 Main Drills and Cable Ducts



Legend

(1) CT transporter gantry anchor points 8×HILTI-HSL-3-M10/20 anchors	(6) Pocket for collimator cart pin Ø45 depth 35 mm	(11) (1) Longitudinal axis (2) Cable inlet area
(2) CT Scan Line	(7) Coordinates table origin	(12) Center of gravity
(3) NM Gantry anchor points 4×HILTI-HSL-3-M10/100 anchors	(8) Alternative locations for gantry cables inlet	(13) Main anchor

(4) Recommended cable inlet coring $\text{Ø}200$. Customer responsibility $\text{Ø}150$. Alternatively, 200×80 deep flush floor duct in this area

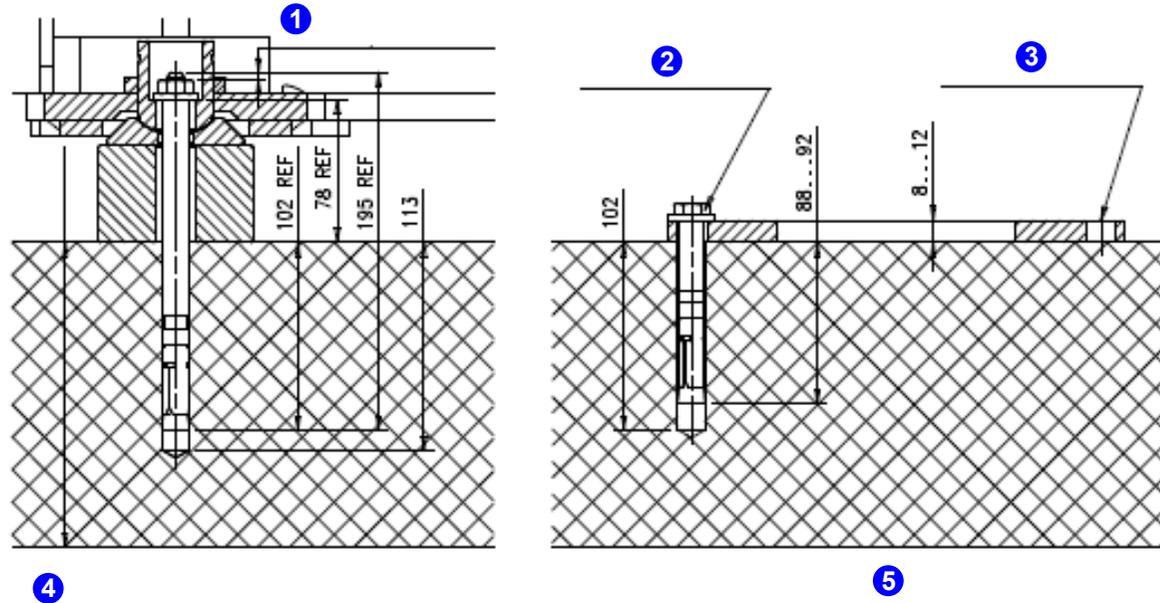
(9) NM FOV

(14) Alternative anchor

(5) Table anchor plate $6 \times$ Hex Head Sleeve Bolt $0.25'' \times 1.75''$ anchor screws

(10) Cable inlet coring $\text{Ø}100$ or 100×80 deep flush floor duct

Figure 2-23 Anchoring Methods



Legend

(1) 4 mm min, 21 mm max after proper torque

(2) (x16) Main anchor

(3) (x10) Alternative anchoring plate

(4) NM gantry main anchoring (4 places)

(5) CT transporter anchoring

Figure 2-24 NM Gantry Alternative Anchoring Methods (4 available places)

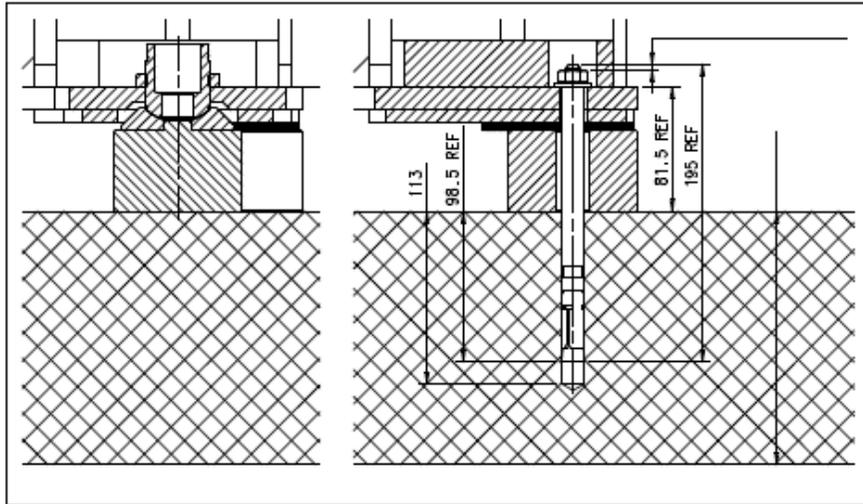
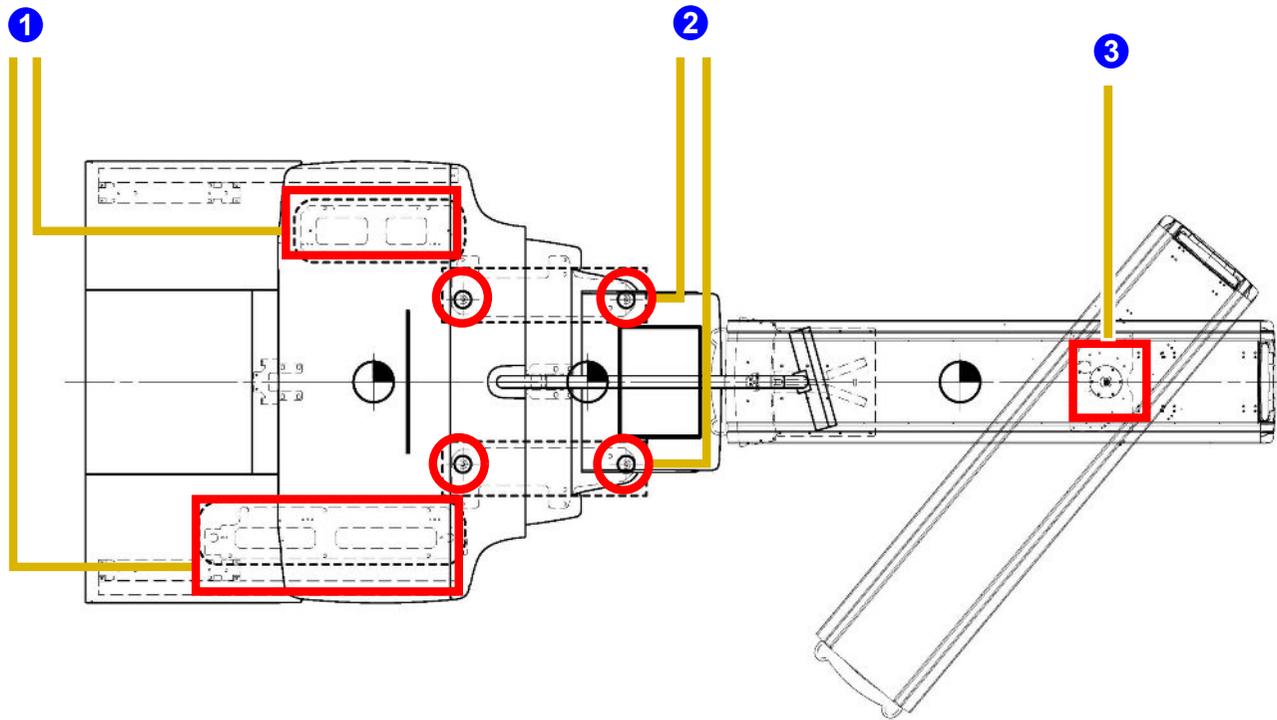


Figure 2-25 Floor Anchor Points**Legend**

- (1) CT gantry anchor points 8 × HILTI-HSL-3 M10/20 anchors
- (2) NM gantry anchor points 4 × HILTI-HSL-3-G M10/100 anchors
- (3) Table anchor plate 6 X Hex Head Sleeve Bolt 0.25" x 1.75" anchor screws

Table 2-3 Drilling and Anchor Chart

No.	X	Y	Drill Hole	Hole Depth	Anchored Part	Hole Purpose	Drilling Method	Anchor Type	Torque Nm.	Section
1	-0.00	405.00	Ø15.0	113.0	NM gantry	Main Anchor	Metal Drilling Template	HILTI HSL-3-G M10/100	35	Figure 2-23 Anchoring Methods on page 77
2	-0.00	-405.00								
3	-810.00	405.00								
4	-810.00	-405.00								
5	-80.00	365.00				Alternative Anchor				Figure 2-23 Anchoring Methods on page 77
6	-80.00	-365.00								
7	-810.00	530.00								
8	-810.00	-530.00								
9	-980.00	835.65		102.0	CT Short Plate	Main Anchor		HILTI HSL-3 M10/20	35	Table 2-3 Drilling and Anchor Chart on page 80
10	-980.00	630.65								
11	-1495.00	630.65								
12	-1495.00	855.65			Alternative Anchor					
13	-1880.00	-630.65			CT Long Plate	Main Anchor				
14	-1495.00	-630.65								
15	-980.00	-830.65								
16	-980.00	-855.65								
17	-1495.00	-855.65			Alternative Anchor					
18	-1965.00	-855.65			Main Anchor					
19	-2055.00	966.85		102.0	CT Service Plate -1	Main Anchor		HILTI HSL-3 M10/20	35	Table 2-3 Drilling and Anchor Chart on page 80
20	-2545.00	891.85				Alternative Anchor				
21	-2065.00	891.85								
22	-2545.00	966.85								
23	-2545.00	-891.85			CT Service Plate -2	Main Anchor				
24	-2065.00	-966.85								

Table 2-3 Drilling and Anchor Chart (Table continued)

No.	X	Y	Drill Hole	Hole Depth	Anchored Part	Hole Purpose	Drilling Method	Anchor Type	Torque Nm.	Section
25	-2065.00	-891.85				Alternative Anchor				
26	-2545.0	-966.85								
27	-1703.50	72.50		102.0	Bearing Plate of Service Lead Screw	Main Anchor	During Lead Screw Installation	HILTI HSL-3 M10/20	35	Table 2-3 Drilling and Anchor Chart on page 80
28	-1623.50	-72.50				Alternative Anchor				
29	-1623.50	72.50								
30	-1703.50	-72.50								
31	-349.00	63.50			Gear Bracket of Service Lead Screw	Main Anchor				
32	-279.00	-63.50				Alternative Anchor				
33	-279.00	63.50								
34	-349.00	-63.50								

 **CAUTION****FLOOR LEVELING REQUIRED**

- The use of floor shims is not suitable to achieve floor levelness.
- Do not use fill material to compensate for holes or depressions in the floor surface.
- Thin fill areas under load will crack and deteriorate over time causing issues with system leveling that may lead to image quality problems. If necessary, level and flatten the entire floor area.

Table 2-4 Floor Leveling Specifications

Item	Requirement
Floor leveling area	640 cm×370 cm (21'×12') (covering the entire planned area of table and gantry installation, depending on room layout)

Table 2-4 Floor Leveling Specifications (Table continued)

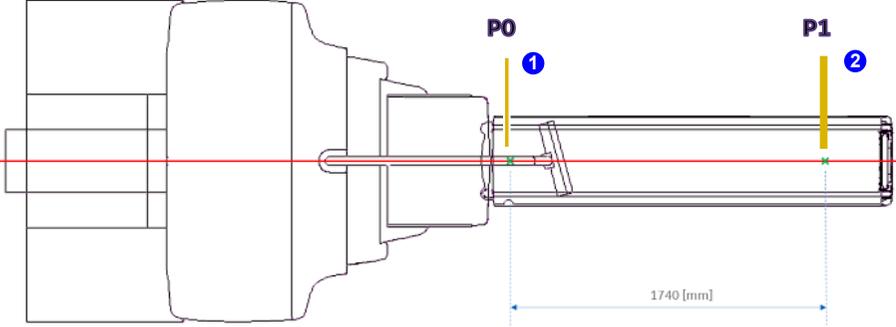
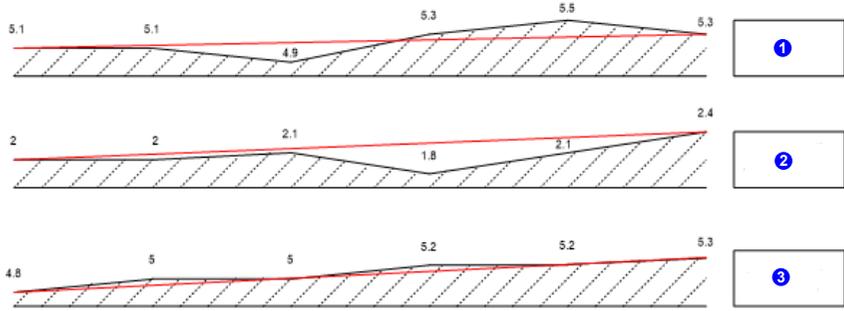
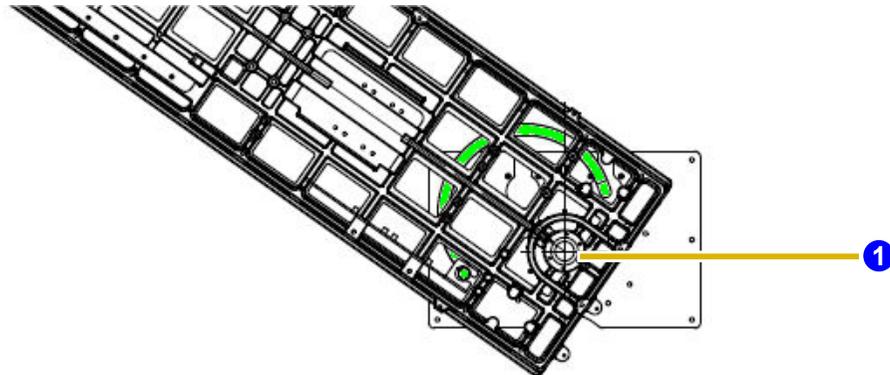
Item	Requirement
Slope	<p>Table B slope: 30 mm over 4300 mm</p> <p>Table A and seismic installations slope: 3 mm (0.125") over 3048 mm (120")</p> <p>Table Duct Considerations</p> <ul style="list-style-type: none"> • If the slope is under 13 mm over 4300 mm, then no additional measurements are required. • If: <ul style="list-style-type: none"> • The slope is above 13 mm over 4300 mm (but still smaller than 30 mm over 4300 mm) • The pivot point P1 is higher than the table wheels P0 <p>Then additional measurements are required to determine table duct planning, as described in 2.3.1.5 Planning Table Conduits/Ducts on page 85.</p>  <p>Legend</p> <p>(1) Table wheels</p> <p>(2) Pivot plate</p>
Floor surface	A single poured surface

Table 2-4 Floor Leveling Specifications (Table continued)

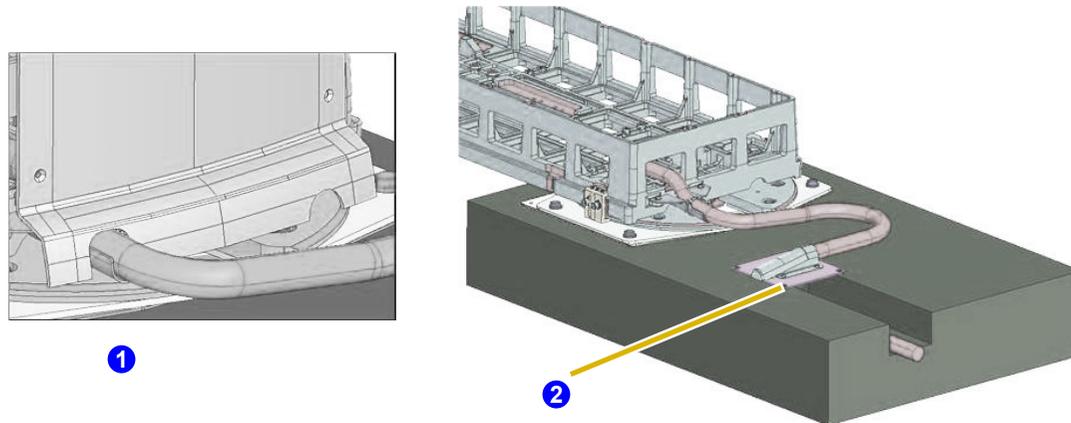
Item	Requirement
Flatness	<p>The surface must be smooth and without significant valleys or peaks.</p> <p>The entire surface area must have an overall flatness of 5 mm over 1500 mm in any direction (see Appendix B Measuring Floor Flatness on page 136 for measurement procedure).</p>  <p>Legend</p> <p>Example (1): The slope (red line) = Pass; the flatness (black line) = Fail</p> <p>Example (2): The slope (red line) = Fail; the flatness (black line) = Fail</p> <p>Example (3): The slope (red line) = Fail; the flatness (black line) = Pass</p>

2.3.1.5 Planning Table Conduits/Ducts

Optimally, the table conduit is routed through the pivot plate.

Figure 2-27 Table Conduit via Pivot Plate (A)

At certain floor slopes, when the table conduit is routed through the pivot plate, the table base might contact the table conduit. In such a case, the cable conduit must be routed via a duct outside of the table base.

Figure 2-28 Table Conduit via Duct**Legend**

(1) External table conduit

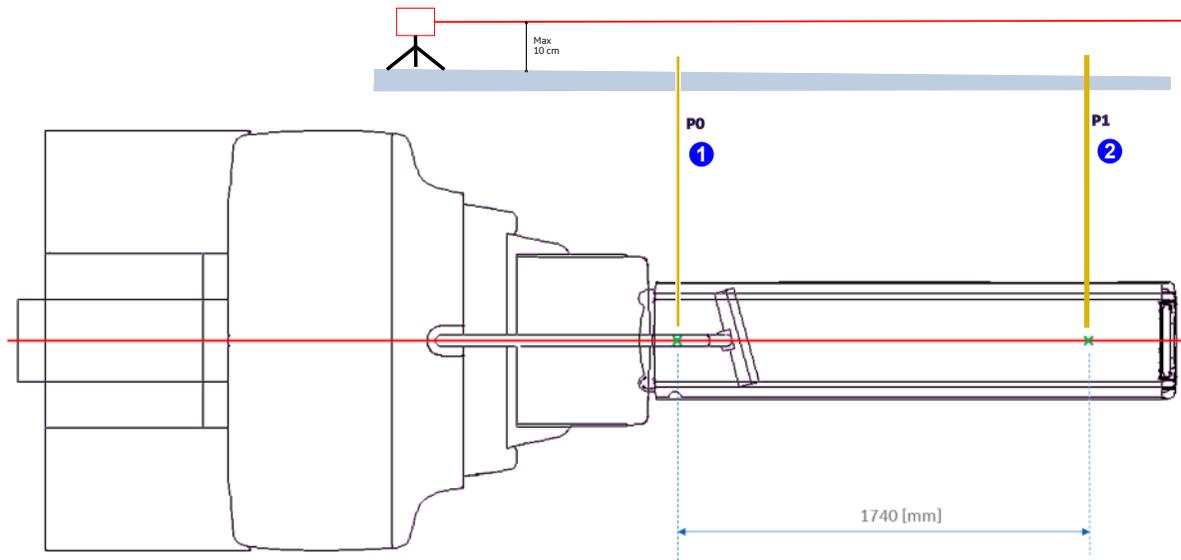
(2) Cable entrance cover

NOTE

The same external conduit routing is equally applicable for seismic and non-seismic installations.

In order to determine whether the slope on the site requires an external duct, measure the height difference between the two points where the patient table will be installed as follows:

1. Place a self-leveling laser as close as possible to the floor and not more than 10 cm high, so that the beam passes through two points **P0** (table wheels) and **P1** (pivot plate).



Legend

(1) P0 = Table wheels

(2) P1 = Pivot plate

2. Position a measuring stick perpendicular to the floor at **P0** and record the height at which the laser intersects the stick.



3. Position the measuring stick perpendicular to the floor at **P1** and record the height at which the laser intersects the stick.

- If $P1 - P0 > 5$ mm, then the table cable conduit cannot be routed through the pivot plate duct and it must be routed through an external duct.

NOTE

If the exact location of points **P0** and **P1** is not clear:

Repeat the measurement at several points around the estimated **P0** and **P1** locations.

- P1**: Use the **maximum** value measured
- P0**: Use the **minimum** value measured

2.3.1.6 Floor Vibration

Floor vibration requirements are included in the general vibration requirements (see [2.3.5 Vibration Specifications on page 89](#)).

2.3.1.7 Floor Conductivity Recommendations

The purpose of this section is to measure the electrical conductivity of the floor surface to the 'GND' (Ground).

- The surface of the conductive floor shall provide a patch of electrical conductivity between all persons and equipment making contact with the floor.
- Using a DVM, measure the impedance between the upper surface of the floor – where the NM gantry is planned to be positioned, and the system power supply GND terminal in the room. The readout should be <35 M Ohm.
- Repeat the measurement in the area where the patient table will be positioned. The readout should be < 35 M Ohm.
- Repeat the measurement in the area where CT gantry will be positioned. The readout should be < 35 M Ohm.

2.3.1.8 Additional Floor Requirements

The floor finish must take into consideration magnetic field and EMI considerations

(see [3.1 Radiation Protection and Shielding Requirements on page 93](#) and [3.5 EMI Considerations on page 98](#)).

2.3.2 Ceiling Requirements

Scan room height must be at least 2.35 meters (7' 8.5").

2.3.3 Wall Requirements

Operator room window

If there is an operator room, the operator must be able to view the patient from the operator room during a scan. The location of the window depends on the position of operator room relative to the scan room. It is recommended that the window is positioned in front of the console so that the operator can look down the length of the bore, as illustrated in [Figure 2-10 Minimal Room Layout on page 57](#).

The recommended patient viewing window dimensions are approximately 120 cm wide by 110 cm high (48"×42").

Consult a qualified radiological health physicist for radiation protection requirements for the window glass (lead content and thickness), in accordance with [3.1 Radiation Protection and Shielding Requirements on page 93](#) and with local requirements.

Radiation protection

For details on wall, door and window radiation protection, see [3.1 Radiation Protection and Shielding Requirements on page 93](#).

Other

Verify that all walls conform with local regulations, such as washability.

2.3.4 Acoustic Specifications

The system creates acoustic noise. In compliance with IEC 601-1-1 standard the measured noise (at 1m distance away from the system) is less than 70 db. It is recommended that the wall and ceiling surface is of a sound dampening material to avoid noise reverberation and amplification.

Take into account that the system includes an intercom communication system connecting the Operator room and the Scan room, to enable the operator to give the patient instructions during the examination.

2.3.5 Vibration Specifications

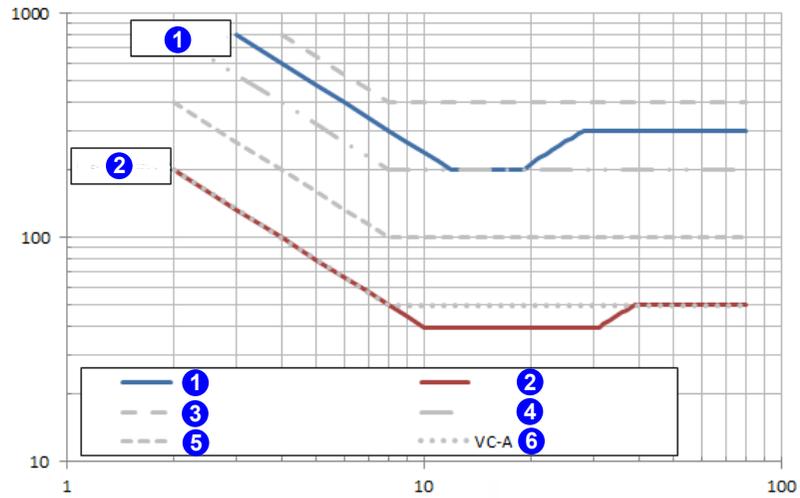
The system components are sensitive to vibration in the frequency range of 0.5 to 20 Hz, depending on the amplitude of the vibration. It is the customer's responsibility to contract a vibration consultant or qualified engineer to verify that these specifications are met and implement an appropriate solution.

To minimize vibrations, the system must be installed on a solid floor, as far as possible from the following vibration sources:

Outside building	Inside building	Other
<ul style="list-style-type: none"> • Parking lots • Roadways • Subways • Heliports • Trains 	<ul style="list-style-type: none"> • Hallways • Elevators 	<ul style="list-style-type: none"> • Hospital power plants containing pumps, motors, air handling equipment and air conditioning units

Figure 2-29 Speed Profile Specifications Micro m/s

X = Frequency [Hz] / Y= Speed RMS [Micro m/s per 1/3 octave band]

**Legend**

(1) 830, D630, B615

(2) 870, D670, 850, 860, O640

(3) Office

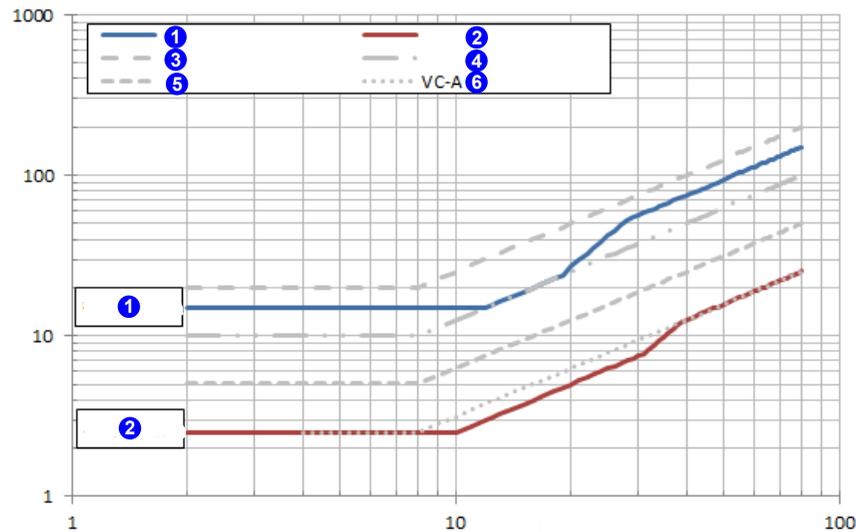
(4) Residential

(5) Operating Theatre

(6) Velocity Curve-A

Figure 2-30 Acceleration Profile mm/s²

X = Frequency [Hz] / Y= Speed RMS [Micro m/s per 1/3 octave band]

**Legend**

(1) 830, D630, B615

(2) 870, D670, 850, 860, O640

(3) Office

(4) Residential

(5) Operating Theatre

(6) Velocity Curve-A

2.4 Seismic Requirements

Important

For special seismic kit details and information refer to the system-specific installation instructions.

Seismic requirements are determined and specified by the hospital design professional of record and must be approved by the specific state or country agency. Seismic attachment hardware shown on seismic calculations may differ from hardware supplied with system. Any additional hardware that is

required will be the responsibility of the institution and/or their contractor.

For additional center of gravity information, see [Table 2-5 Seismic Subsystem Centers of Gravity and Anchoring Points](#) on page 92.

Table 2-5 Seismic Subsystem Centers of Gravity and Anchoring Points

IMPORTANT! For special seismic kit details and information, refer to the specific ITF released for the system seismic install.			
Component	Center of Gravity Location (cm)	Anchoring Method	See also
Patient table	See Figure 2-17 Table Center of Gravity Points on page 72	Anchor plate + 6 × Hex Head Sleeve Bolt 0.25" × 1.75" anchor screws	Figure 2-26 Patient Table Pivot Floor-Plate Anchoring Holes on page 82; Figure 2-17 Table Center of Gravity Points on page 72
NM gantry with heaviest collimators	See Figure 2-14 NM Gantry with HEGP Collimators Center of Gravity Points on page 69	4×HILTI HSL-3-G M12/100 anchors	Figure 2-25 Floor Anchor Points on page 79
CT gantry on floor plates	See Figure 2-15 CT Gantry Center of Gravity Points on page 70	8× HILTI HSL-3 M10/40 anchors	Figure 2-25 Floor Anchor Points on page 79
CT gantry in service position	See Figure 2-16 Floor Loading and Center of Gravity Points for Gantry, Table and Cart on page 71	None	
UPS (optional)		None	
NM acquisition station	See Figure 2-21 NM Acquisition Computer Center of Gravity Points on page 74	Belts and brackets with 4x HILTI anchor and HLC sleeve anchor	
NIO console	See Figure 2-18 NIO Console Center of Gravity on page 73	None	
(870 only) SmartConsole	See	Belts and brackets with 4x HILTI anchor and HLC sleeve anchor	
PIDB	See Figure 2-20 CT PIDB Center of Gravity on page 74	None	
CT PDU	See Figure 2-19 CT PDU Center of Gravity on page 73	None	
Collimator cart/s	See Figure 2-7 Collimator Cart on page 51	Carts cannot be anchored, as they must move freely in the room for collimator exchange.	

*1 <http://powerquality.eaton.com/Products-services/Backup-Power-UPS/9155-info.asp>

Chapter 3 Special Construction Requirements

3.1 Radiation Protection and Shielding Requirements



Specific room shielding requirements should be determined by local regulatory considerations, facility policy and if available, the facility physicist.

Radiation shielding regulations differ from one country or state to another. It is the customer's responsibility to ensure that radiation protection and shielding comply with such regulations and requirements during site preparation and system installation and operation.

The system produces x-ray radiation and involves the use and storage of radionuclides. Appropriate barriers such as walls, lead-shielded glass, lead shields, etc. can be installed to protect staff from unnecessary exposure to radiation.

Patients become significant sources of radioactivity; therefore consideration should be given to maximize the distance between the patient and operator during the uptake and acquisition phases of scan procedures.

Scatter-room shielding requirements must be reviewed by a qualified radiological health physicist taking into consideration:

- Scatter radiation levels within the scan room
- Equipment placement
- Weekly projected workloads (#patient/day technique (kvp*ma))
- Materials used for construction of walls, floors, ceilings, doors and windows
- Access to surrounding scan room areas
- Equipment in surrounding scan room area (for example: film developer, film storage)

3.2 Background Radiation

When the system is calibrated, background radiation from surrounding areas may adversely affect calibration. Therefore all radiation sources must be suitably shielded, including:

- Waiting/Injection areas
- Radionuclide storage and preparation area (sometimes known as “hot lab”)

As a general guideline, if the anticipated background radiation in the Scan Room will be higher than 0.1mR/h (1microGy/h), then appropriate additional shielding should be installed.

If radioactive gases are used in the scan room or in nearby rooms, for example gases used during ventilation lung scans; there must be mitigations to keep the gases away from the detectors. Some gases can settle on the floor while other gases can be drawn into the detector via the cooling fans. A detector's recovery from a gas contamination will depend on the half life of the radioactive gas. Negative room pressure and other air flow mitigations should be considered if radioactive gases are expected to be present in the department.

3.3 Scan Room Shielding

Shielding of the Scan Room includes walls, lead-shielded glass, lead shields, etc. and must be sufficient to protect staff from unnecessary exposure to radiation. The shielding requirements must be determined by a qualified radiological health physicist, taking into consideration:

- Local regulatory requirements
- Facility policy
- CT scatter radiation levels within the scanning room (see [Figure 3-1 Head Phantom Typical Scatter Survey on page 96](#))
- Patient location and level of radiation from patients after intake of radionuclides
- Equipment placement
- Materials used for construction of walls, floors, ceiling, doors, and windows
- Weekly projected work-loads (# patient/day technique (kvp*ma))
- Access to areas surrounding the Scan Room
- Equipment in areas surrounding the Scan Room (for example: film developer, film storage)
- Protection of operator room, included leaded window, walls and door

See [Figure 3-1 Head Phantom Typical Scatter Survey on page 96](#) for measurable CT radiation levels within the scanning room while scanning a 32cm CTDI phantom (body) and a 20 cm water phantom (head), with the technique shown.

The mAs, kV and aperture scaling factors shown in [Table 3-1 Shielding Requirements Scaling on page 95](#) can be used to adjust exposure levels to the scan technique used at the site.

NOTE

Actual measurements can vary. All measurements have an accuracy of $\pm 20\%$ because of measurement equipment, technique, and system-to-system variation. Use the correction factors shown in [Table 3-1 Shielding Requirements Scaling on page 95](#) to adjust exposure levels to the usual scan technique at your site.

Table 3-1 Shielding Requirements Scaling

Changed Parameter	Multiplication Factor	
mAs	new mAs/100	The units of measure used for radiation levels have been changed in this document, from mR (millirads) to μGy (micrograys). The conversion factor is: 1 mR = 8.69 μGy
80 kV	0.21	
120 kV	0.71	
140 kV	1.0	
16 x 0.625 LD 8 x 1.25 LD 4 x 2.5 LD Fluro 5mm	0.59	
4 x 1.25 LD 5 mm (1i) Fluro 2.5 mm	0.40	
1 x 1.25 mm images 2 x 0.625 LD	0.20 0.10	
1 x 1.25		
4 x 3.75 mm images	0.82	

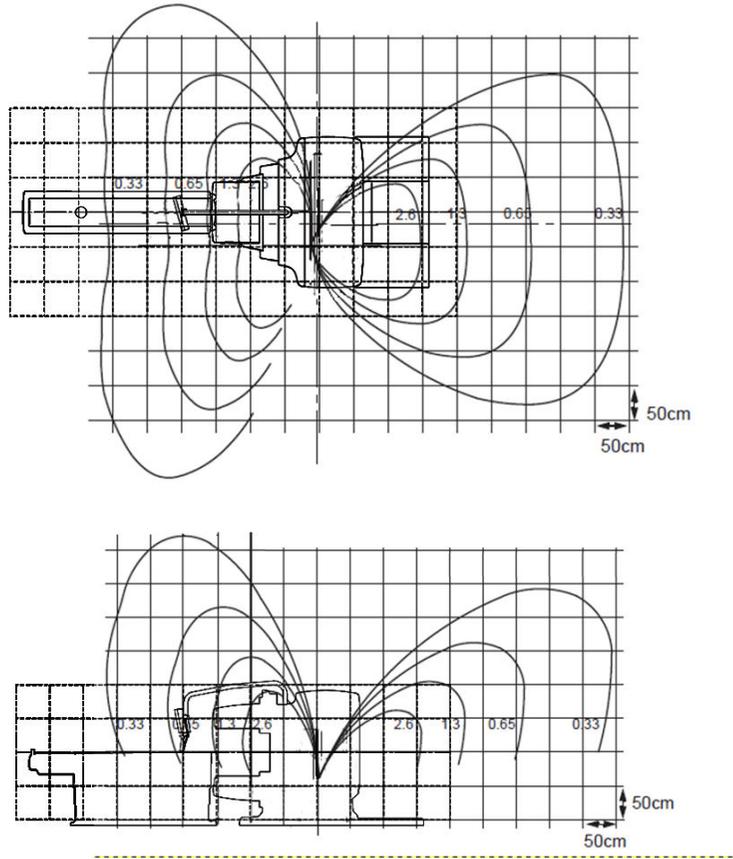
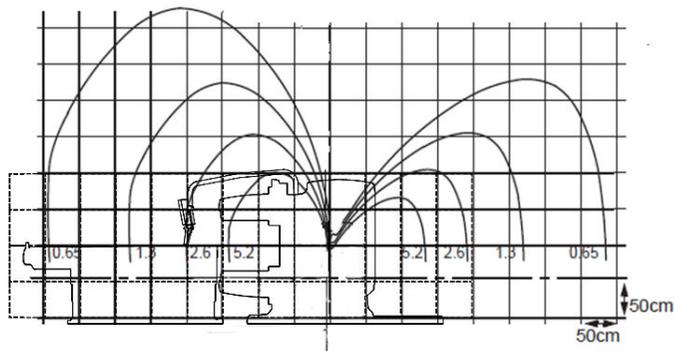
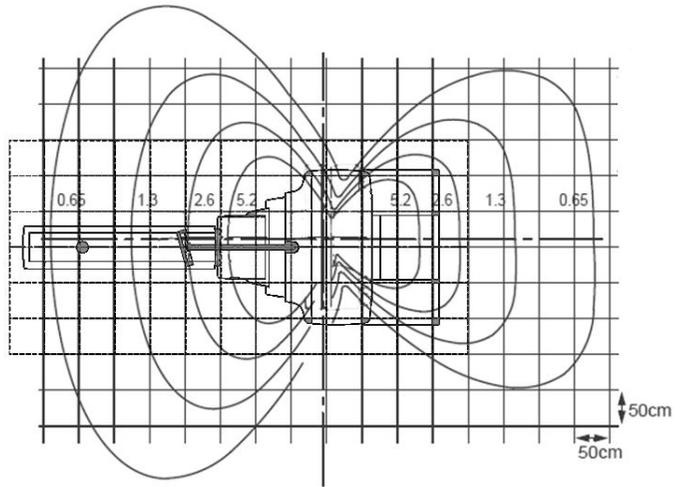
Figure 3-1 Head Phantom Typical Scatter SurveyISO Contour Levels: 0.33, 0.65, 1.3 and 2.6 $\mu\text{Gy}/\text{Scan}$ | Technique: 140 kV 100 mA 1 sec 4x5.00 mm

Figure 3-2 Body Scatter Phantom Typical Scatter SurveyISO Contour Levels: 0.65, 1.3, 2.6 and 5.2 $\mu\text{Gy}/\text{Scan}$ | Technique: 140 kV 100 mA 1 sec 4 \times 5.00 mm

3.4 Magnetic Field Considerations

The ambient static magnetic field in the system location must be less than 10^{-4} tesla (1,000 milligauss). The ambient AC magnetic fields must be below the 10^{-6} tesla (10 milligauss) peak.

Important

The system must be installed in X-ray protected room, see [3.1 Radiation Protection and Shielding Requirements on page 93](#).

Low Frequency Magnetic Field

N/A

Static Magnetic Field Limits

In order to avoid interference on the system, the static field limits from the surrounding environment must be less than 1 Gauss in both the scan and the operator rooms.

3.5 EMI Considerations

3.5.1 Electrostatic Discharge Environment & Recommendations

In order to reduce electrostatic discharge interference, install a charge dissipative floor material to avoid electrostatic charge buildup.

The relative humidity shall be at least 30 percent.

The dissipative material shall be connected to the system ground reference, if applicable.

3.5.2 Electro-Magnetic Interference (EMI) System Placement

NOTE

If power sub-stations exist under or above the scan room, or near the operator room, consider EMI testing to determine if your proposed room meets the published acceptable EMI room limits. This also includes high voltage lines under the scan or operator room floor.

EMI Reduction

If fields of excessive EMI are known or suspected to be present, consult GE Sales & Service for recommendations. Consider the following if you attempt to reduce EMI:

- External field strength decreases rapidly with distance from source of magnetic field.

- External magnetic field leakage of a three-phase transformer is much less than that of a bank of three single phase transformers of equivalent power rating.
- Large electric motors are a source of substantial EMI.
- High-powered radio signals are a source of EMI.
- Ensure sufficiently good screening of cables and cabinets.
- Consider and measure EMI fields of sites with main facility power running under the floor or within the walls or ceilings of the scan room.
- Pay special attention to power substations or high-voltage power lines in proximity to the scan facility.
- If any concerns remain regarding excessive EMI fields, be sure to measure to confirm that your site meets all required specifications.

Table 3-2 Electro-Magnetic Interference (EMI) Constraints

Component	Ambient magnetic fields		System attributes affected	Comments
	Static	AC		
Gantry and Table	< 10 ⁻⁴ tesla (1,000 milligauss)	< 10 ⁻⁶ tesla (10 milligauss) peak	Imaging performance	
Color Monitor	< 10 ⁻³ tesla (10,000 milligauss)	NA	Color purity and display geometry	The CT PDU produces an electromagnetic field that radiates outward from its cabinet in all directions.
Console / Computer Equipment	< 10 ⁻³ tesla (10,000 milligauss)	NA	Data integrity	The UPS provides a consistent power supply in normal conditions and during a site-wide power outage.
Magnetic Media	< 10 ⁻³ tesla (10,000 milligauss)	NA	Data integrity	Do not place sensitive electronics, for example console or computer equipment within 1 m of the CT PDU or 1 m of the UPS, in any direction (including above or below) The UPS and CT PDU are not classified as sensitive electronics.

3.5.3 Electromagnetic Immunity

The system is intended for use in the electromagnetic environment specified in [Appendix C EMC Compliance on page 142](#). The customer must assure that the system is installed and used in such an environment.

The system should not be used adjacent to or stacked with other equipment. If adjacent/stacked use is necessary, the system should be observed to verify normal operation.

3.5.4 Recommended Separation Distances

The system is intended for use in an electromagnetic environment in which radiated RF disturbances are controlled. The customer can help prevent electromagnetic interference by maintaining a minimum distance between portable and mobile RF communications equipment (transmitters) and the system as recommended below, according to the maximum output power of the communications equipment.

NOTE

These guidelines may not apply in all situations. Electromagnetic propagation is affected by absorption and reflection from structures, objects, and people.

For transmissions between 150 kHz and 2.5 GHz, adhering to the recommended distance separation will reduce disturbances recorded at the image level, but may not eliminate all disturbances. However, when installed and operated as specified herein, the system will maintain its essential performance by continuing to acquire, display, and store diagnostic quality images safely. For example, in order to avoid image interference risks, a 1 W mobile phone (800 MHz to 2.5 GHz carrier frequency) must be placed 2.3 meters away from the system.

See also [Table C-4 Separation Distances for Portable and Mobile RF Communications Equipment on page 147](#).

3.5.5 Cable Shielding and Grounding

All interconnect cables to peripheral devices must be shielded and properly grounded, except when technologically prohibited. Use of cables not properly shielded and grounded may result in the equipment causing radio frequency interference. GE Healthcare is not responsible for any interference caused by using other than recommended interconnect cables or panels, or by unauthorized changes or modifications to this equipment.

Unauthorized changes or modifications could void the users' authority to operate the equipment.

Electromagnetic Emission

This equipment complies with IEC 60601-1: 2: 2004, IEC 60601-1: 2: 2007 and IEC 6061-1-2: 2014; EMC standards for medical devices.

NOTE

This system complies with the EMC standard when used with supplied cables. If cables of different lengths are required, contact your PM. Cables cannot be cut, shortened, lengthened, or spliced.

The system is suitable to be used in an electromagnetic environment, in compliance with the limits and recommendations provided in [Table C-5 Electromagnetic Compliance on page 148](#).

Chapter 4 Environmental HVAC Requirements

 **WARNING****IMPEDED SYSTEM OPERATION / IMAGE QUALITY**

Ratings and duty cycles of the system apply only if site environment meets the standards of this section. If environmental specifications are not respected, system operation and image quality may be affected.

The environmental conditions listed in this chapter are essential to maintain proper cooling for the system. These conditions must be maintained at all times, including overnight, weekends and holidays. Only when the system is shut down, for example for major repair, may the air conditioning also be shut down.

Failure to adhere to these requirements can lead to image quality issues.

 **WARNING****OVERHEATING**

If air conditioning is not functioning correctly, the system must be shut down.

4.1 General Guidelines

Maintaining constant temperature and humidity levels is essential in order to ensure system stability over time.

Overheating or underheating, or changes in humidity that exceed the requirements provided in this section can cause technical difficulties and system failures and can cause damage to system components. You must conform to the requirements in [Table 4-1 Requirements for Ambient Temperature, Humidity and Altitude on page 102](#) both during system storage and in as long as the system is operational after installation.

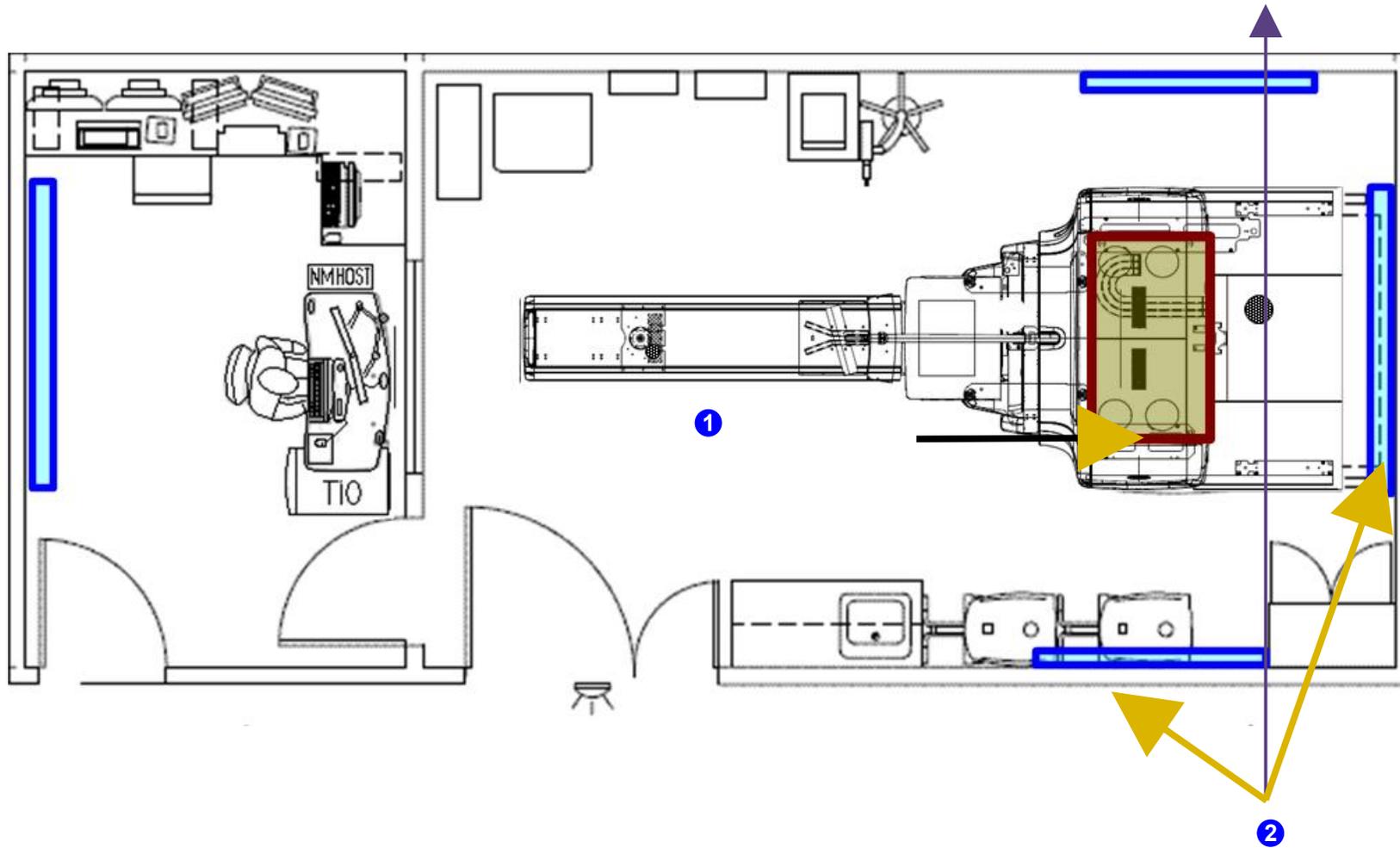
Cooling requirements do not include cooling for room lighting, personnel or other equipment.

Locate a wall air-conditioning vent at floor level beside and behind gantry to meet gantry cooling needs and to provide patient comfort. Do not locate any cooling vents directly above the gantry. Air returns above the gantry are recommended.

Table 4-1 Requirements for Ambient Temperature, Humidity and Altitude

	Maximum	Minimum	Recommended	Maximum rate of change
Temperature	26°C (79°F)	18°C (64°F)	22°C (72°F)	3°C/hr (5°F/hr)
Humidity	60% non- condensing relative humidity	30% non- condensing relative humidity		5%/hr
Altitude	4100 m (13,451 ft.)	-150 m (-492 ft.)		

Figure 4-1 Air-conditioning Ducts

**Legend**

(1) Ceiling area for "Air Returns" above CT gantry. No cooling vents in this area.

(2) Must plan to flow cold air towards the rear and sides of the gantry.

4.2 Heat Output

Table 4-2 Heat Output in Scan Room

System Component	BTU/hr	Watt	Comments
Scan Room			
NM gantry	4,500	1,320	
Table	682	200	
CT gantry	18,766	5,500	Based on 75 scan rotations per patient and up to three patients per hour, as well as during system calibration
CT PDU	3,410	1,000	
CT UPS (optional)	5,000	1,465	
Recommended subtotal	32,358	9,485	
Operator Room			
CT console	2,860	840	Including with 1 IG, 2 monitors and SCSI tower
NM acquisition station	256	75	(computer only)
SmartConsole	256	75	(computer only)
Xeleris workstation	256	75	(computer + 2 monitors)
AW workstation (optional)	256	75	(computer + 2 monitors)
Recommended subtotal without options	3,884	1,140	
SYSTEM TOTAL	36,202	10,625	Cooling requirements do not include cooling for room lighting, personnel or non-NM/CT equipment
NM UPS (optional, in scan room)	< 1500	< 440	If a full-load UPS is used, this adds to heat dissipation levels and should be taken into consideration when planning the room.

4.3 Air Quality

The system is especially sensitive to the presence of sulfide, chloride and nitrate contaminants, with sulfur being the most damaging element. If high levels of contaminants exist, it is recommended that appropriate air filtration systems are installed.

If the system will be used for aerosol/gas ventilation studies, special precautions must be taken:

- Local laws and regulations must be reviewed for compliance.
- Room planning should be evaluated by a Radiation Safety Officer.

Consult your local radiation safety officer or regulatory body for best practices to minimize aerosol leakage and subsequent contamination.

Chapter 5 Electrical Requirements

5.1 Power Feed

A dedicated feeder run from the facility main isolation transformer is recommended to power the system. If the system must be powered from an existing distribution transformer and secondary feeder, such as the equipment distribution panel of an x-ray department, installation with other x-ray equipment that uses rapid film changers should be avoided. These changers use a large number of high powered, closely spaced exposures, which may coincide with the scan and produce image artifacts. If a dedicated distribution transformer is provided for the scanner, the minimum recommended transformer size is as follows, rated 2.4% regulation at unity power factor:

112.5 kVA

For this configuration, the minimum recommended feeder size and overcurrent protection device based on line voltage is shown in [Table 5-3 Minimum Feeder Wire Size on page 107](#).

In all cases, qualified personnel must verify that the transformer and feeder, at point of take-off, plus the run to the system, meet all the requirements provided in this document.

Table 5-1 System Power Characteristics

Selected Technique	Values	Comments
Maximum power demand	140 KV, 380 mA 90 kVA @ 0.85 PF	
Continuous (average) power demand at maximum duty cycle	22 kVA	
Maximum allowable total power source regulation	6%	
Minimum recommended transformer size	112 kVA	With 2.4% rated regulation at unity power factor. Resultant maximum allowable feeder regulation is 3.4%

NOTE

If local regulations require feeding electronic equipment in either the scan room or the operator room via a separate isolation transformer, you can order the Isolation Transformer (P/N E4500BC).

The following tables, and [Table 5-4 Power Supply Requirements on page 108](#)) are based on the use of copper wire, rated 75 C and run in steel conduit. The current rating (ampacity) is determined in accordance with the National Electrical Code (NFPA 70), Table 310-16 (2002).

NOTE

Ampacity, or Current Rating, is the RMS current which a device can carry within specified temperature limitations in a specified environment, depending upon: a) temperature rating, b) power loss, c) heat dissipation.

The ampacity for a power cable depends on properties of the conductor and the insulation and on environmental conditions adjacent to the cable.

The minimum feeder size is determined by the current rating (ampacity) of the circuit protection device listed below. In some cases a larger size may be necessary in accordance with local regulations for total source.

A 6AWG1/0 (55 sq. mm) ground wire is recommended in all cases.

Table 5-2 Nominal Power Line Ranges

The nominal line voltage must fall within one of the ranges listed below						
Nominal line voltage (Volt)	380	400	420	440	460	480
Hi-Line Limit, +10% (Volt)	418	440	462	484	506	528
Lo-Line Limit, -10% (Volt)	342	360	378	396	414	432
Continuous line current (Amp)	30	29	27	26	25	24
Momentary line current (Amp)	137	130	124	118	113	108
Maximum line current (Amp)	152	144	137	131	126	120
Minimum recommended circuit protection rating (Amp)	110	110	100	100	90	90

Table 5-3 Minimum Feeder Wire Size

Feeder Length (MDA to MDP) Feet (Meters)	Minimum feeder wire size, AWG or MCM (Sq. MM)/ VAC					
	380 VAC	400 VAC	420 VAC	440 VAC	460 VAC	480 VAC
50 (15)	2 (35)	2 (35)	3 (30)	3 (30)	3 (30)	3 (30)
100 (30)	2 (35)	2 (35)	3 (30)	3 (30)	3 (30)	3 (30)
150 (46)	2 (35)	2 (35)	3 (30)	3 (30)	3 (30)	3 (30)
200 (61)	2 (35)	2 (35)	3 (30)	3 (30)	3 (30)	3 (30)
250 (76)	1 (45)	1 (45)	2 (35)	2 (35)	2 (35)	3 (30)

Table 5-3 Minimum Feeder Wire Size (Table continued)

Feeder Length (MDA to MDP) Feet (Meters)	Minimum feeder wire size, AWG or MCM (Sq. MM)/ VAC					
	380 VAC	400 VAC	420 VAC	440 VAC	460 VAC	480 VAC
300 (91)	1/0 (55)	1/0 (55)	1 (45)	1 (45)	2 (35)	2 (35)
350 (107)	2/0 (70)	1/0 (55)	1/0 (55)	1 (45)	1 (45)	1 (45)
400 (122)	2/0 (70)	2/0 (70)	1/0 (55)	1/0 (55)	1/0 (55)	1 (45)

5.2 Power Supply Requirements

The system must receive its power supply via a dedicated feeder run from the nearest Main Distribution Panel (MDP).

NOTE

According to local regulations, a primary power disconnect device must be provided on the power line supplying the CT PDU, see [5.6.2 Power Input Distribution Box \(PIDB\) with MDP \(A1\) on page 118](#).

The system is designed to operate on a three-phase plus neutral, five-wire Wye power source (preferably a solidly grounded Wye source).

The neutral wire is used in the NM sub-system only and does not need to be routed to the CT PDU (i.e. five-wire connection).

Table 5-4 Power Supply Requirements

	Characteristics	Comments		
Line voltage specifications	380 to 480 VAC	The difference between the highest line-to-line voltage and lowest line-to-line voltage must not exceed 2% of the lowest line-to-line voltage. The power input is a three phase + neutral + ground.		
Line frequency specifications	50-60 Hz \pm 3 Hz			
Measured kVa load characteristics	90	Maximum power demand	90	@ 0.85 PF, at a selected technique of rotation 3 RPM, L shape with LEHR collimator
		Average (continuous) power demand	22 kVA	At maximum duty cycle
Line Impedance	0.4 Ohm			

Table 5-4 Power Supply Requirements (Table continued)

	Characteristics	Comments
Fuse or Circuit Breaker Ratings	90 A / 110 A / 125 A / 150 A (corresponding to the ordered transformer and MDP model)	
Power requirements for equipment not powered from the system	In scan room and in operator room: 2 one-phase regular power outlets for service tools (such as vacuum cleaner, electric drill, soldering iron etc.)	For service activities
Power stability (transient etc) requirements	Maximum transient voltages should be limited to 1500 V peak	Sags and surges of the power line must not exceed the absolute range limits shown in the Nominal Power Line Ranges table in 5.1 Power Feed on page 106 .
Inrush current	Can withstand up to x10 of the recommended Circuit Breaker Ratings that could be reached during system power up, due to the system main transformer.	

Total load regulation as measured at the PDU input terminals must not exceed 6%. The capacity of the facility transformer and the size and length of feeder wires directly affect the load regulation presented to the system.

NOTE

- The MDP (A1) must provide overcurrent protection for the system and facilitate multi-point remote “Emergency Off” control of system power. An MDP with a disconnect that uses an under-voltage release control is preferred over shunt trip devices. The rating of the MDP disconnect device depends on the nominal line voltage at the site.
- The electrical rating is described on the system rating label attached to the gantry; not on the PDU.

5.3 Grounding

5.3.1 Grounding Requirements

The system has been designed to use an equal potential grounding system. The required ground system is shown in [Figure 5-1 System Grounding Map on page 111](#).

The system includes 3 primary grounding points:

- System power ground point, located in the PDU

- NM Reference ground point, located at the side of the NM gantry base
- CT Reference ground point, located at the front of the CT gantry base

All exposed metal surfaces in the patient vicinity are grounded to the reference ground point.

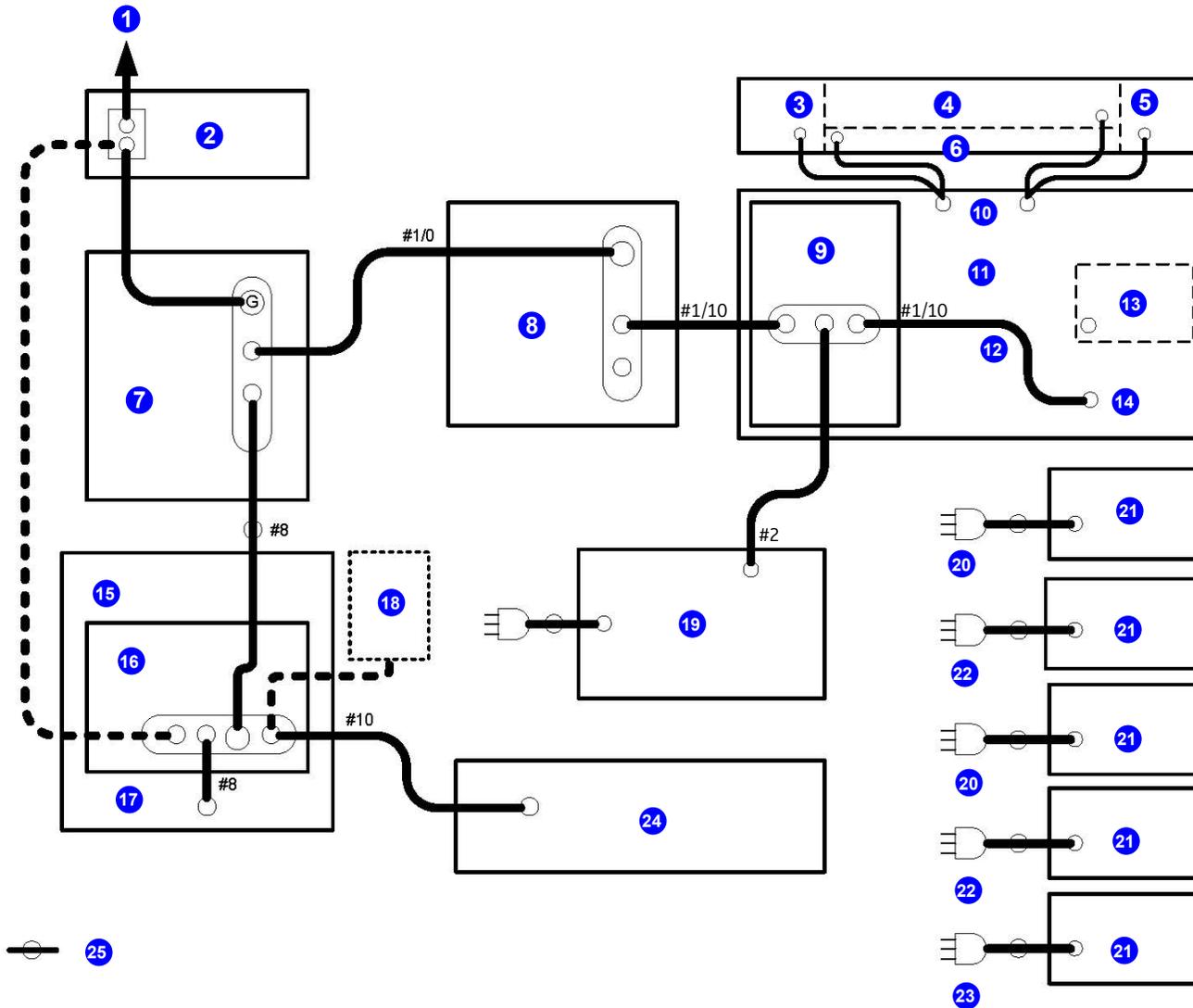
Figure 5-1 System Grounding Map

A ground bus inside the PIDB is used to centralize the NM and CT gantries grounding. Two local ground bus at the CT and NM gantry base are used to centralize the ground of each gantry subsystem. The CT ground is tied to vault around at the CT PDU, through its chassis.

Shield/signal grounds are not shown.

Wire+circle = Ground wire in supplied cable.

Disk units are located in CC1 and SCU.



Legend

(1) To power vault ground	(8) CT Power Distribution Unit (PDU)	(14) Frame	(20) To console (CT1)
(2) A1 Power Disconnect	(9) CT ground bar (located at gantry front)	(15) NM gantry	(21) In-room monitor (option)
(3) Deck side #1	(10) Frame	(16) NM gantry ground bar (located at gantry side)	(22) To console (CT2)
(4) Deck center #1	(11) CT gantry (CT2)	(17) (Part of gantry)	(23) To CT gantry or console
(5) Deck side #2	(12) (part of gantry)	(18) NM UPS	(24) Patient table
(6) Deck center #2	(13) Rotating assembly frame	(19) Operator console;/computer (OC1)	(25) Ground wire in supplied cable.
(7) NM Power Input Distribution Box (PIDB)			

5.3.2 Grounding of System Input Power

Make sure to comply with both of the following grounding requirements:

- Connecting to the Power Input Distribution Box (PIDB)

Connect the metal conduit, raceway, or the armor of the armored cable used to power the system, to the PIDB.

- **Grounding wire**

- Run a dedicated 1/0 (50 mm²) or larger insulated copper ground wire with the phase wires from the main distribution panel to the main facility ground.
- Connect the ground wire to the MDP (A1) through which it passes, in accordance with local codes.
- Ensure that the resistance between the PIDB ground and the facility earth ground at the MDP does not exceed 0.5 Ohm. Measure with an ohm meter and a piece of wire.
- Ensure that the total resistance between the PIDB ground and earth does not exceed 2 Ohm. The system's ground conductor must be in the same conduit as the system phase conductors. This ground conductor must be bonded to the main facility ground.

NOTE

The shield or armor of armored cable is not sufficient for this purpose.

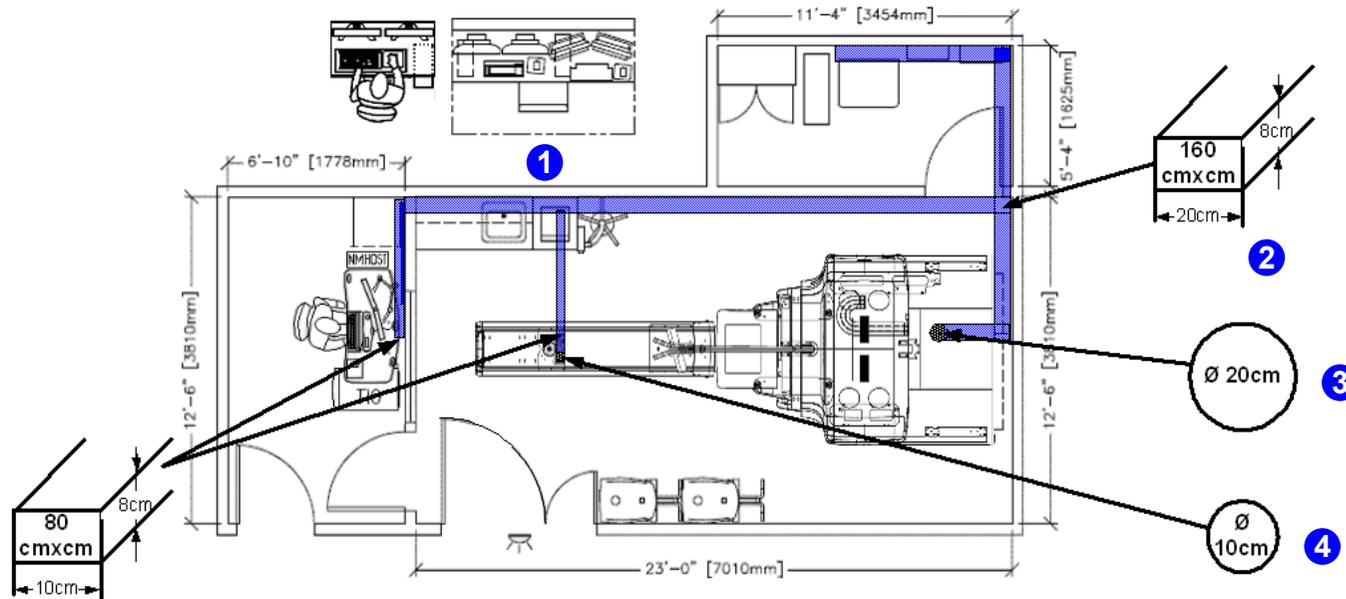
5.4 Interconnections

It is recommended that all cables are run inside ducts or conduits, as illustrated below.

Ensure adequate duct or conduit sealing to prevent penetration of liquids or other objects that may damage the cables.

Figure 5-2 Example 1 of Suggested Cable Ducts Routing in Standard Room

Minimum room size – separate electronics closet & locating review stations elsewhere



Legend

(1) (Located elsewhere – such as a reading room)

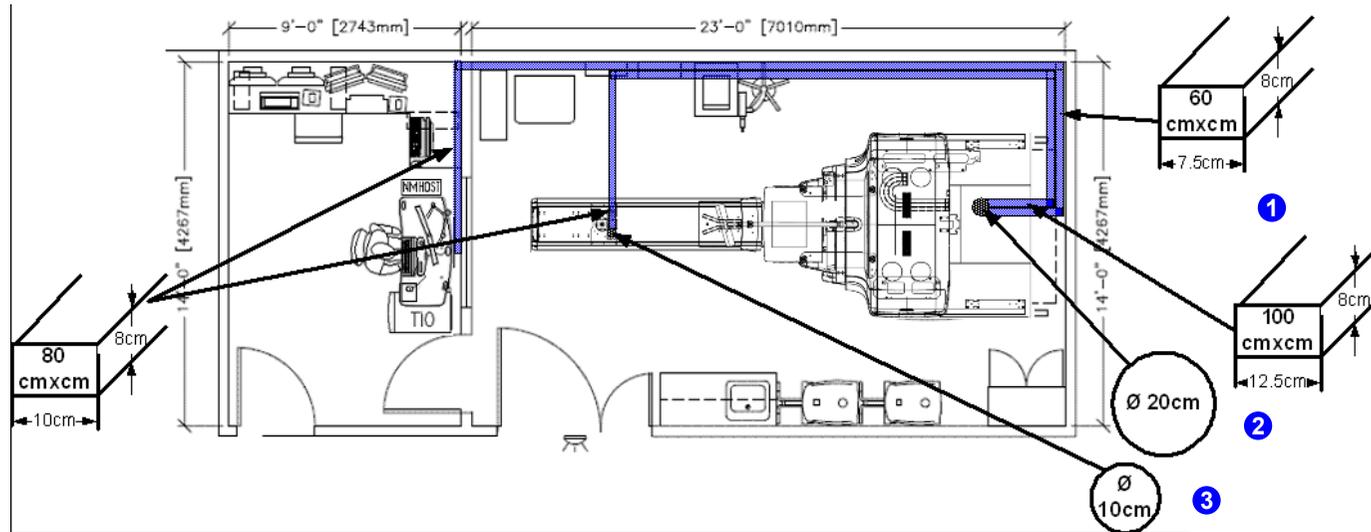
(2) Recommended duct width × depth

(3) Floor openings behind gantries

(4) Floor openings under table

Figure 5-3 Example 2 of Suggested Cable Ducts Routing in Standard Room

Minimum room size – electronics on the side



Legend

- (1) Recommended duct width x depth
- (2) Floor openings behind gantries
- (3) Floor openings under table

5.5 System Cable Information

This section provides technical information regarding system cables connecting different sub-systems, in order to facilitate the planning of cable routing.

Table 5-5 Sub-system Inter-connection Cables

Start / Destination		H/V Separation (Y or N)	Run #	Actual Length (Usable Length)		Description
From	To			Feet	Meters	
PDU	CT gantry	Y	050	63.5 (55)	19.35 (16.76)	HVDC, PDU to gantry

Table 5-5 Sub-system Inter-connection Cables (Table continued)

Start / Destination		H/V Separation (Y or N)	Run #	Actual Length (Usable Length)		Description
From	To			Feet	Meters	
PDU	CT gantry	Y	051	63.5 (55)	19.35 (16.76)	HVAC, PDU to gantry
PDU	CT gantry	Y	052	63.5 (57)	19.35 (17.56)	LVAC, PDU to gantry
PDU	Console (adaptor box)	Y	053	80 (75)	24.5 (22.86)	LVAC, PDU to console
PDU	CT gantry	N	055	63.5 (55)	19.35 (16.76)	Ground, PDU to raceway
Console	CT gantry	N	056	83 (75)	25.5 (22.86)	Ground, raceway to console
PDU	CT gantry	N	100	70 (62)	21.4 (18.86)	Signal, gantry MSUB to PDU
Console	CT gantry	N	101	86.45 (78)	26.35 (23.71)	Signal, gantry MSUB to OC
Console	CT gantry	N	102	86.45 (81)	26.35 (24.86)	Signal (LAN), gantry to OC
Console	CT gantry	N	103	80 (75)	24.3 (22.86)	Fiber optic, gantry to OC
PDU	UPS	Y	060	15 (12)	4.6 (3.6)	Power cable, CT PDU to UPS
PDU	UPS	Y	061	15 (12)	4.6 (3.6)	Power cable, UPS disconnect panel to CT PDU
UPS	MDP (A1)* ²	Y	110	45 (37)	13.6 (11.3)	UPS control cable
Injector	CT gantry	N		100	30.5	Gantry to injector
Injector	Console (adaptor box)	Y		82	25	Power cable injector to console
ECG	CT gantry	N		30	10	Gantry to ECG monitor signal
NM gantry	CT gantry	N	126	29.5	9	CT table interface cable
NM gantry	CT gantry	N	124	29.5	9	NM-CT gantry interface cable
NM gantry	CT gantry	N	125	29.5	9	ECG and trigger/respiratory cable
NM gantry	CT gantry	N	129	29.5	9	ECG trigger cable
NM gantry	Patient table	N	130	65.6 (54.1)	20 (16.5)	Table cable harness* ³
NM gantry	PDU	Y	120	78.74 (67.24)	24 (20.5)	NM mains cable
NM gantry	NM host	N	128	65.6 (54.1)	20 (16.5)	NM gantry-to-computer Ethernet cable

Table 5-5 Sub-system Inter-connection Cables (Table continued)

Start / Destination		H/V Separation (Y or N)	Run #	Actual Length (Usable Length)		Description
From	To			Feet	Meters	
NM gantry	NM host	N	127	65.6 (54.1)	20 (16.5)	NM gantry-to-computer display monitor cable
From PDU	To PIDB	Y	002	40 (34.4)	12 (10.5)	CT mains cable
MDP	PIDB	Y		9	2.5	PIDB-to-MDP power feed

*1 Actual length is the entire cable length, connector to connector, including cable run inside each sub-system. Usable Length is the portion of the cable routed externally between sub-systems.

*2 The MDP can be the A1 or other primary power disconnect device

*3 The standard table cable provided is 20 M. There is an optional 10 M cable available.

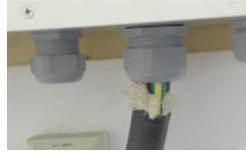
Connector Sizes

The table below shows information about the largest connector size for each sub-system interconnect cable bundle.

Table 5-6 Connectors

	Largest Connector Size	Connector
Acquisition Station	5.6 cm	
Table	6 cm	

Table 5-6 Connectors (Table continued)

	Largest Connector Size	Connector
Gantry	6 cm	
PIDB	4 cm	

5.6 Typical Customer Supplied Cables and Wiring

5.6.1 Primary Power Disconnect

MDP with lockout /tagout (LOTO)

In order to install and service the system, the customer must have a lockout /tagout (LOTO) compatible Main Disconnect Panel (MDP) installed in the room.

The MPD and the lockout /tagout must be visible when servicing the system.

The customer must ensure that all cables and wiring specified in this section are prepared in advance. These cables and wiring components are not supplied with the system.

5.6.2 Power Input Distribution Box (PIDB) with MDP (A1)

In order to service the system safely, the customer must have a lockout /tagout (LOTO) compatible Main Disconnect Panel (MDP(A1)) installed in the examination room. The MDP must be located within 1 m (3.2 ft.) of the PIDB, visible when servicing the system.

Figure 5-4 MDP (A1) and Power Input Distribution Box (PIDB) Configuration Options**NOTE**

The PIDB can be installed on either side of the MDP (left or right), or below the MDP.

If a UPS is ordered, it is strongly recommended that you order UPS from GE (PN B7999PP). In this case, you must also order the MDP that is designed to work with the UPS.

GE-orderable MDP units (A1) include:

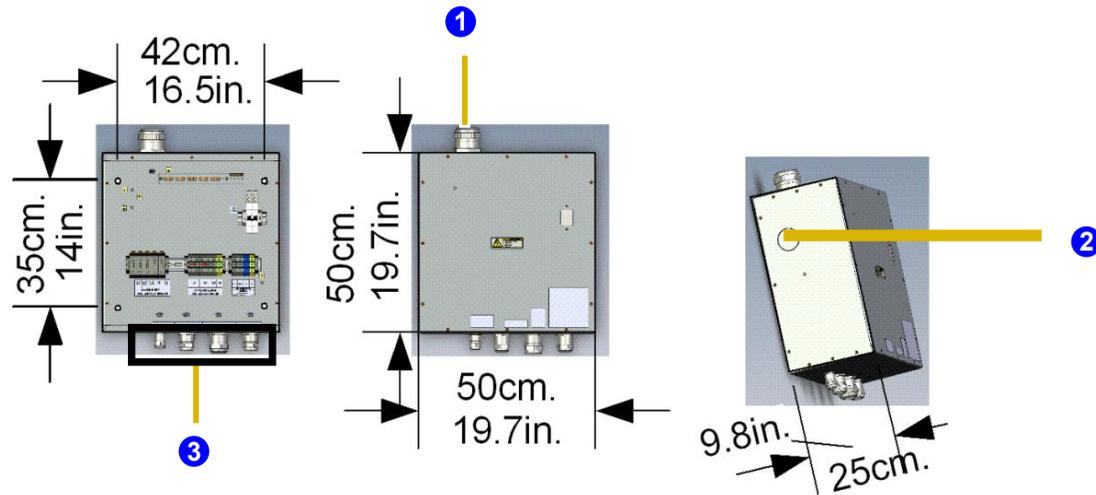
- For the U.S. (440V or 460-480V) – PN E4502AB or E4502AG (90A)
- For Europe and Asia (380-400V or 420V) – PN E4502AC or E4502AH (110A) (or equivalent)

NOTE

The GE orderable MDP, such as A1, has an Emergency OFF (EMO) switch integrated into the front panel.

Table 5-7 Customer Supplied Cables and Wiring on page 120 lists the technical details for customer-supplied wiring.

Figure 5-5 PIDB Detailed Description



Legend

- (1) Default terminal for input power cable from MDP
- (2) Alternative location for MDP power cable terminal
- (3) Terminals for cables leading to PDU and NM gantry

NOTE

The power cable terminal can be moved from the top of the PIDB (default) to the left or right side, depending on the site plan.

Table 5-7 Customer Supplied Cables and Wiring

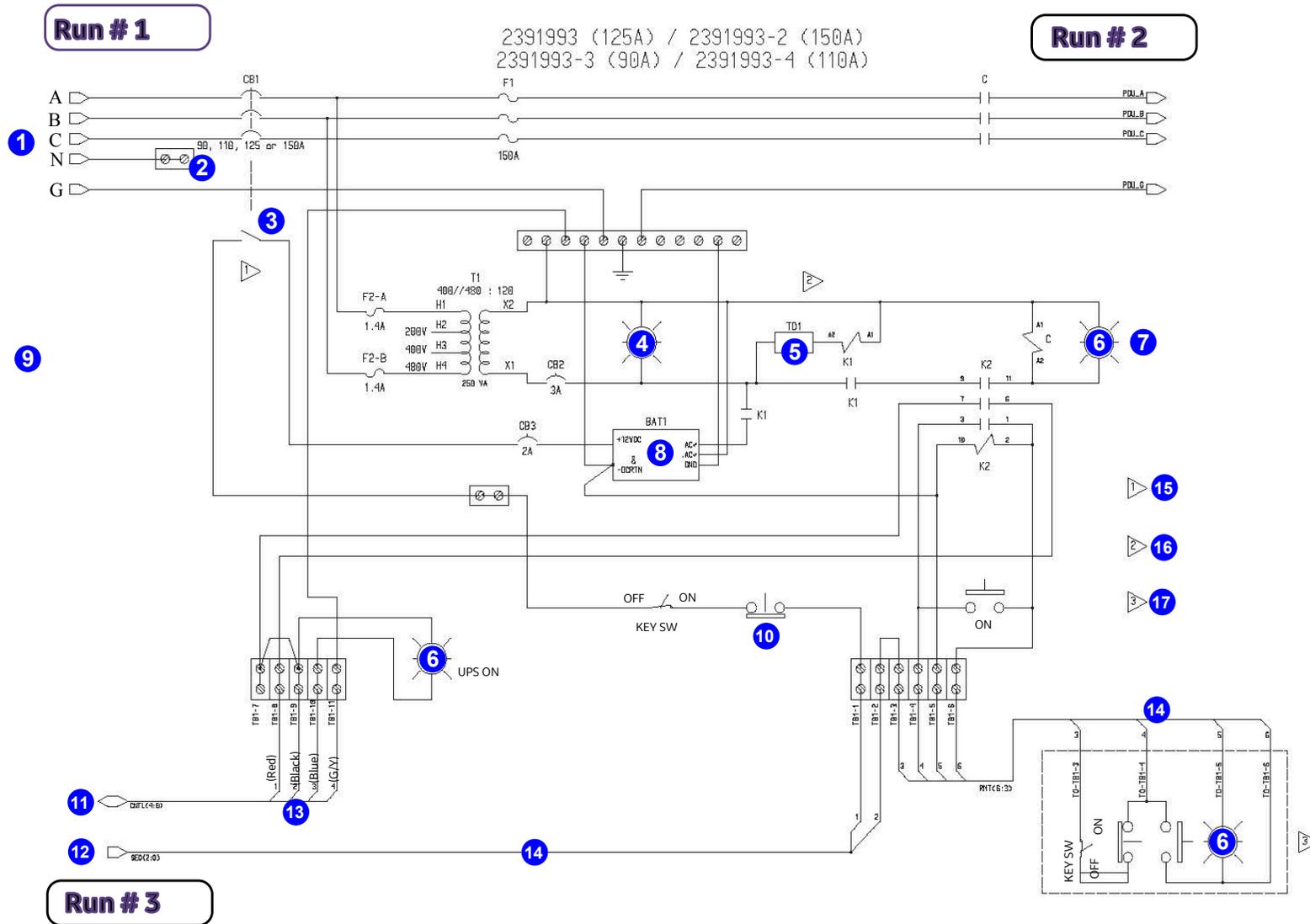
Wiring		Description	Maximum run length Meter (ft.)	
			From	To
Quantity	Size AWG (mm ²)			
Run No. 1 – from primary power source to MDP (see Figure 5-6 MDP (A1) Main Disconnect & UPS Control Panel – Primary Power Disconnect – Fusible Disconnect & Magnetic Contactor on page 122)				

Table 5-7 Customer Supplied Cables and Wiring (Table continued)

Wiring		Description	Maximum run length Meter (ft.)	
Quantity	Size AWG (mm ²)		From	To
3	*1	Power	1 (3)	1 (3)
1	1/0 (50)	Ground	1 (3)	1 (3)
1	*1	Neutral (not required)	1 (3)	1 (3)
Run No. 3 – from MDP to System Emergency Off (SEO) (see Figure 5-6 MDP (A1) Main Disconnect & UPS Control Panel – Primary Power Disconnect – Fusible Disconnect & Magnetic Contactor on page 122)				
2	14 (2)	Power	2 (6)	2 (6)
1	14 (2)	Ground	2 (6)	2 (6)
Run No. 4 – CT PDU to warning light control (see Figure 5-7 Typical TS6 Warning Light and Door Interlock Connections on page 124)				
2	14 (2)	Warning light 24 volt control A3J2-1,2,3,4	N/A	N/A
Run No. 5 – CT PDU to scan room door interlock (see Figure 5-7 Typical TS6 Warning Light and Door Interlock Connections on page 124)				
2	14 (2)	Scan room door interlock A3J6-1,2	N/A	N/A

*1 Refer to [Table 5-3 Minimum Feeder Wire Size on page 107](#) for AWG (mm²) wire sizes

Figure 5-6 MDP (A1) Main Disconnect & UPS Control Panel – Primary Power Disconnect – Fusible Disconnect & Magnetic Contactor



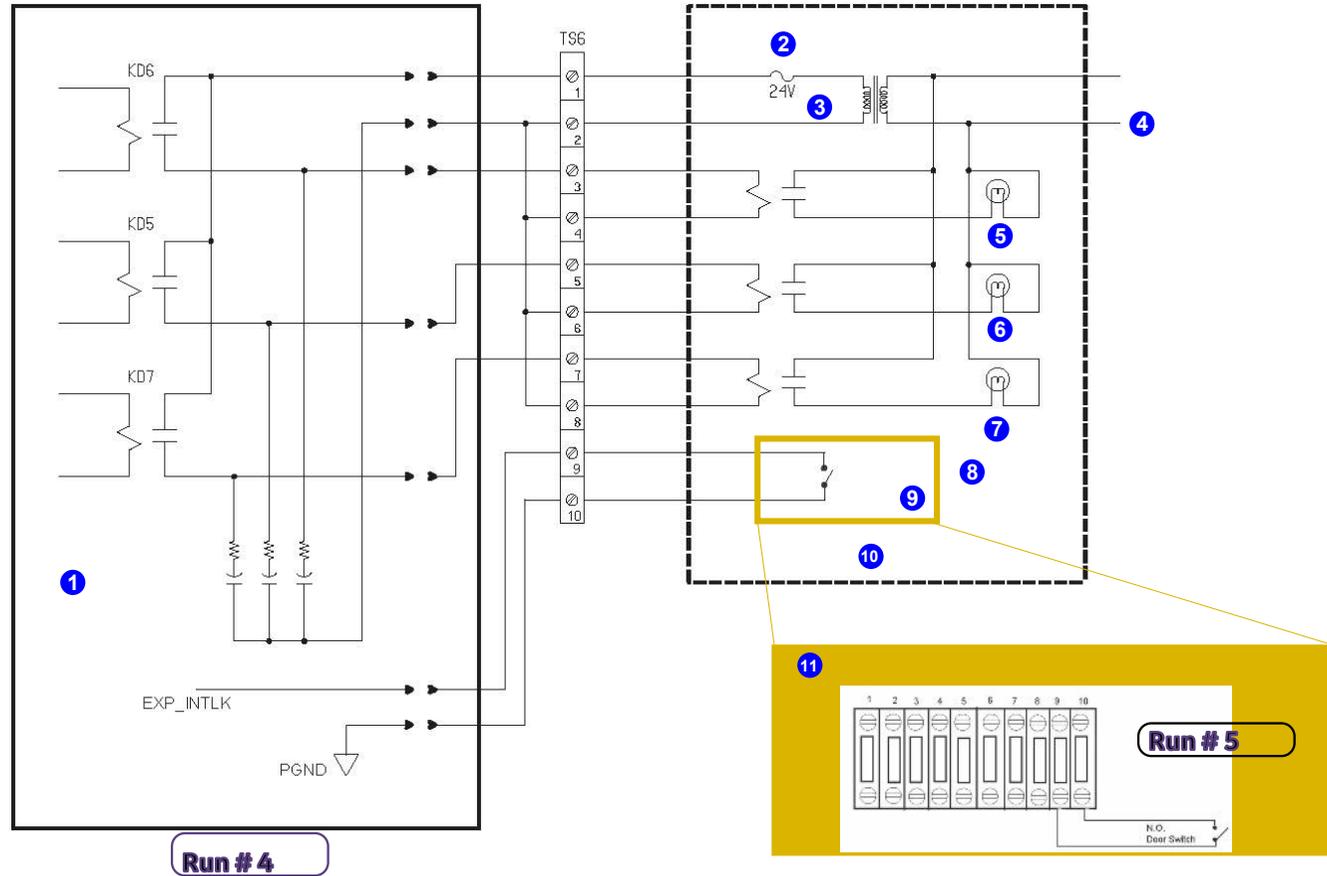
Legend

(1) Mains _A / B / C / N / G	(7) Contactor ON	(13) (Supplied with UPS kit)
(2) Isolated neutral block	(8) Battery & charger	(14) Field supplied wiring
(3) Aux switch	(9) (Located elsewhere – such as a reading room)	(15) Auxiliary Switch Installed Internal to Main Circuit Breaker
(4) White	(10) Emergency OFF	(16) Electronic Time Delay Device (TD1) Set to Nominal 5 Second Delay
(5) Time delay	(11) Control cable to UPS disconnect panel	(17) Remote On / Off Control Components (Included with A1 Panel)
(6) Green	(12) To scan room SEO button	

5.6.3 Warning Light and Door Interlock Connections

- Warning light and door interlock are not mandatory in some countries. If you install an x-ray warning light in the room, it is recommended that you use the 4-wire method which:
 - Minimizes EMC interference
 - Increases contact life of the relay used in the PDU
- If a door switch will not be used, an additional jumper must be added to TS6 in the PDU during installation. If the jumper is not in place, exposures will not be made.

Figure 5-7 Typical TS6 Warning Light and Door Interlock Connections



Legend

(1) Control board	(4) Neutral	(7) Ready light	(10) Facility supplied
(2) Fuse	(5) X-ray light	(8) Room warning lamp	(11) (Terminal TS6 in PDU)
(3) Secondary transformer	(6) System ON light	(9) Door switch	

5.7 Lighting Specifications

5.7.1 Scan Room Lighting

The lighting should be planned so there is sufficient light for:

- Scan preparation
- Scan setup
- Patient unloading
- Working light for service and maintenance activities

The lighting should be designed so that it can be dimmed or otherwise changed in order to minimize discomfort for patients lying supine for extended periods on the patient table with the ceiling in view.

NOTE

- Scan room lighting above the gantry and patient table area should consist of fluorescent lights only (no direct sunlight or direct bright light from filament light bulbs).
- During system servicing in the scan room, a relatively bright light is required in the area behind and around the gantry.

5.7.2 Operator Room Lighting

The lighting should be planned taking into account that operators will be working with computer monitors and reading digital images during much of the day. Reflections in monitors should be avoided, and other ergonomic factors taken into account.

The operator room lighting must also take into account that relatively bright light is required while servicing the CT console (NIO) and/or NM acquisition station.

5.8 Power Line Outlets for Service

It is recommended to install at least two standard power outlets in the scan room and in the operator room, to be used for electrically powered service tools. The exact location of these outlets should be defined according to regulatory and service clearances around the system.

Chapter 6 Network and GE Remote Access Requirements

6.1 Network Requirements

The system requires the following network connections:

- Broad-Band Network Connection (BBNC) (required): broad-band network connection wall jack, located within 1 m (40") of the operator computer location, for internal hospital networking and GE remote broadband connectivity.
 - Local Area Network (LAN) (required)
 - LAN connections are usually required in the operator room for:
 - Xeleris and/or A/W workstation
 - SmartConsole (870 only)
 - CT subsystem
 - NM subsystem
 - DICOM LAN printer (optional)
- The LAN and WAN Networks sockets/outlets (minimum 4; recommended 5) must be available in the operator room within a distance of 1 m (40") of the operator computer location, processing workstations (Xeleris or A/W) and LAN printer installed in the operator room.
- In the scan room it is recommended to have one LAN socket/outlet available in close proximity to the CT or NM gantry for service engineer activities actions.
 - Wide Area Network (WAN) (optional)

6.2 RSVP Requirements

From SP62XX and above, the system requires direct internet connectivity as follows:

- The system allows for DNS configuration or Proxy server connection to the internet.
- If replacing an existing system that has a remote GE connection, the current internet connection supporting GE remote access (InSite) connection can be reused.

- RSVP meets the security specifications defined in the product's Privacy and Security manual or relevant software document.
- Proxy configuration for internet access may also include authentication credentials (user name and password). Local IT contact must be able to authenticate these details on the system if necessary.
- If the site would like to whitelist only certain URLs, the following addresses can be used for RSVP connectivity. All service traffic is via port 443:
 - Initial connectivity: <https://insite.gehealthcare.com:443>
 - Remote access: <https://as1-insite.gehealthcare.com:443>
 - Remote access: <https://as2-insite.gehealthcare.com:443>
- It is not recommended to route the connection over an existing site VPN tunnel (instead of over the internet). If the customer requires the use of a VPN tunnel, a case must be escalated to the local connectivity team.

Appendix A Customer Checklist

The checklist must be completed by the customer and delivered to GE prior to installation.

Important

This checklist is general in nature and is intended to assist the customer in verifying site preparation. The checklist does not cover all details in this manual, and it is the customer's responsibility to fully prepare the site, taking into account all details and specifications set out in this manual.

Site Information	Contact Information	Contact Persons	Name	Telephone	email
Site name		Site project coordinator			
Department		System administrator			
Street		Chief technologist			
City, State, Zip		Facilities engineer			
Country		Shipping / Receiving			
Telephone		Physician			
Fax		Other			
Safety Declaration					
I hereby confirm that the relevant site personnel have read the <i>Safety and System Overview Manual</i> , in conjunction with this Pre-Installation Manual.			Name		
			Position		
			Signature		
Completion Sign Off					
I hereby confirm that pre-installation is complete and that I have examined and confirmed all items in the Pre-Installation Customer Checklist			Name		
			Position		
			Signature		

Table A-1 Deviation from Specifications in Site Preparation Manual

Description		Personal Details	
Floor and anchoring	I hereby confirm that the site takes full responsibility for the floor and anchoring methods differing from the specifications in this manual	Name	
		Position	
		Signature	

Table A-2 Site Preparation Timetable

Description	Status	See	Comments
Scheduling	Project schedule verified with GE		
	3rd party vendors scheduled		
	Can meet the committed site ready date		
	Construction completion date matches delivery date		
	System delivery date scheduled for		
	Detectors delivery date scheduled for		
	Installation dates scheduled for		
	Applications/Training date scheduled for		
	Site Ready date scheduled for		
First Use date scheduled for			

Table A-3 Room Preparation

Description	Status	See	Comments
Pre-construction	Site layout drawings completed and approved		
	Radiologist health physician has reviewed the room layout		

Table A-3 Room Preparation

Description		Status	See	Comments
	3rd party vendors identified: ----- ----- -----			
Post-construction: Room measurements and layout	• Length			
	• Height			
	• Width			
Servicing clearance	Meets all requirements, including local codes and local regulatory requirements as detailed in Appendix D Regulatory Clearances on page 149 . No grounded walls are present in the regulatory clearance areas.			
Egress	Sufficient egress space per local regulatory requirements			
Structural and floor preparation	Floor tolerates specified loads			
	Floor meets thickness requirements or alternate anchoring has been specified and is available from the customer's structural engineer			
	Floor meets leveling requirements			
	Floor meets flatness requirements			
	Floor meets vibration requirements			
Ducts	Ducts installed in floor, according to approved room layout			
	Ducts meet requirements (size, depth, sealing, high voltage separation)			
Electricity requirements	Three-phase Main Distribution Panel (MDP (A1)) meets requirements and is installed			

Table A-3 Room Preparation (Table continued)

Description		Status	See	Comments
	Three-phase power line meets requirements, and neutral has been pulled			
	Wall outlets are live and available for installation and service tools			
Environmental conditions	Ample working light is available for service			
	Air-conditioning meets requirements for system thermal loads			
	Air-conditioning meets humidity requirements			
	Magnetic field in camera room is < 1 Gauss			
	Room is clean and free of dust, ready for installation			
Room shielding	Shielding of scan room meets requirements			
	Shielding of operator room meets requirements			
	External exposure x-ray light installed			
Safety	Planned location of emergency button in scan room is easily accessible by operator			
	Interlock system installed			
Customer-Provided Cabling and Connections	Door switch			
	Warning lights			
	System Emergency Off button (SEO)			
	Additional wiring from MDP to PDU and UPS available			

Table A-4 Unloading, Conveyance and Storage

Description		Status	See	Comments
Temporary storage	System will be delivered on first install day or Some or all crated components will be stored until installation date			
	Site has sufficient storage area			
Staging area	If a staging area is required, its size and all environmental conditions meet the system's requirements.			
Loading dock	Is a loading dock with 112 cm (44") truck-height available?			
	Full-size truck can access loading dock or Site will arrange for short truck delivery			
Unloading by forklift	Site has forklift with weight capacity to lift a fully crated gantry (2230 kg) (4917 lbs.) or			
	Site will arrange for appropriate forklift			
Rigging (required if halls/ elevator/doors access is not available)	Rigging company details: Name: _____ Contact person: _____ Phone: _____			
	Rigging company has insurance policy			
	Insurance policy of rigger company is attached			
Pallet truck	Site has pallet truck or Site will arrange for pallet truck			
	Delivery route is defined by site and meets requirements			
Delivery route	Delivery route is defined by site and meets requirements			
	Delivery route is tested by site			

Table A-4 Unloading, Conveyance and Storage (Table continued)

Description		Status	See	Comments
Installation room	Room can be locked during installation			
Suitability of halls, elevators and doors for conveyance of all components, when mounted on moving kit/wheels Note: All items must refer to conveyance as follows: - From truck to installation room (crated or uncrated) or - From truck to storage (crated) and from storage to installation room (crated or uncrated)	All door openings, hallways are large enough			
	Pathways can tolerate weight			
	Elevator openings and size are large enough			
	Elevator can tolerate weight			
	Gantry can clear all corners			
	Inclines on the route to the camera room are suitable (weight, size and incline angle)			
	State the incline angle			
	There are delicate carpets or tiles along the conveyance route			
	Floor protection is supplied for delicate surfaces			
	Patient table can clear all 90° corners			
Waste materials	Site has arranged for disposal of empty wooden cases, foam blocks and large cardboard boxes after installation			

Table A-5 Network Preparation

Description		Status	See	Comments
Local networking or IT Contact information	Info provided			
Network cabling and hardware	Installation complete			
Broadband	Installed and tested			
Network definitions and testing	Acquisition station site name, hostname and IP address defined and tested			

Table A-5 Network Preparation (Table continued)

Description		Status	See	Comments
	Xeleris workstation site name, hostname and IP address defined and tested			
	CT console site name, hostname and IP address defined and tested			
	AW workstation site name, hostname and IP address defined and tested			
	870: SmartConsole site name, hostname and IP address defined and tested			

Network Definition Details					
Item	Hostname	IP	Wired (Y/N)	DICOM Port	AE Title
NM Acquisition Station					
Processing host					
Hardcopy host					
LAN Net Mask					
Gateway to other networks					
870: SmartConsole					

Table A-6 Radioactive Isotopes for System Calibration

Description		Status	See	Comments
Basic calibration	Site has license for Tc ^{99m}			
	Tc ^{99m} will be available during installation			
Isotopes to be used at site are available for installation. Specify age and strength of source in Comments	Co ⁵⁷ (Rectangular Flood Source)			
	Tl ²⁰¹			
	I ¹³¹			
	I ¹²³			

Table A-6 Radioactive Isotopes for System Calibration (Table continued)

Description		Status	See	Comments
	In ¹¹¹			
	Ga ⁶⁷			
	Xe ¹³³ (inhalation gas)			

Appendix B Measuring Floor Flatness

The floor must meet strict flatness specifications. The information in this appendix is provided as a tool for accurate measurement of the floor flatness.

Required Tools

- Self-leveling fan beam laser tool (self-leveling for at least 3 degrees)
- Masking tape
- Chalk line
- 1 m (3') level with minimum 1 mm (1/16") gradations (alternatively, use a tape measure securely taped to a spirit level)

1. Map the floor as follows:

NOTE

In the following graphic:

The "interest area" that needs to be checked (marked with two green X markers in the diagram) differs depending on the system type. This example demonstrates the area for 870 and D670 systems.

The "interest area" for table installation is indicated by the two green X marks.

Maximum height of laser: 10 cm (4")

- c. Add x marks at 30 cm (1 ft) intervals from center line, so that the system footprint is covered with a grid of x marks (C).
 - d. Place the level flat on the floor and move it around the footprint area. Visually inspect the floor for any significant highs/lows, and add x marks (B) to identify them.
3. Keeping the measuring stick (F) exactly perpendicular to the floor, at each tape mark record the height at which the laser hits the ruler.
 4. Record the measurements in a table that represents the system footprint. Add notes for any significant high/low measurements found in between the grid locations.

The table provides a visual contour of the floor, where each cell in the grid represents 30 cm (1 ft). Compare to the system specifications to determine whether the floor meets the requirements.

[Table B-1 Floor Flatness Conforming with 0.5 cm over 150 cm Specs \(0.5 Deviation\) on page 138](#) shows a floor that meets the specification of 0.5 cm over 150 cm: there is no deviation greater than 0.5 between any 5 cells in the grid.

[Table B-2 Floor Flatness Outside 0.5 cm over 150 cm Specs \(1.1 Deviation\) on page 139](#) shows a floor with three areas out of specification.

Table B-1 Floor Flatness Conforming with 0.5 cm over 150 cm Specs (0.5 Deviation)

Measurements in CM					Center						Notes
	1.3	1.2	1.1	1.1	1	1.1	0.9	0.9	1		Greatest Deviation: 1.4 - 0.9 = 0.5
	1.2	1.1	1.1	1.1	1	1	1	0.9	1		
	1.2	1	1	1	1	1	1	1	1		
	1.1	1	1	1	1	1	1.1	1.1	1.1		
	1	1	1	1	1	1	1.1	1.2	1.2		
	1	1	1	1	1	1	1.2	1.2	1.3		
	1.1	1.1	1.1	1	1	1.1	1.2	1.3	1.3		
		1.1	1.1	1.1	1.1	1.1	1.2	1.3			
		1.2	1.2	1.1	1.1	1.1	1.2	1.2			
		1.2	1.2	1.2	1.1	1.1	1.2	1.2			
				1.2	1.2	1.2					
		1.2	1.2	1.2	1.2	1.2	1.2	1.2			
1.3	1.3	1.2	1.2	1.2	1.3	1.3	1.2	1.2	1.1	1	
1.3	1.3	1.2	1.2	1.2	1.3	1.3	1.2	1.2	1.1	1	
	1.2	1.2	1.2	1.3	1.3	1.3	1.3	1.3	1.1		

Table B-1 Floor Flatness Conforming with 0.5 cm over 150 cm Specs (0.5 Deviation) (Table continued)

Measurements in CM					Center						Notes
		1.2	1.3	1.3	1.3	1.3	1.3	1.3			
			1.3	1.4	1.3	1.3	1.3				
				1.4	1.4	1.3					

Table B-2 Floor Flatness Outside 0.5 cm over 150 cm Specs (1.1 Deviation)

Measurements in CM					Center						Notes
	5.2	5.3	5.4	5.4	5.4	5.4	5.4	5.4	5.5		Greatest Deviation: 5.9 - 4.8 = 1.1
	5.3	5.4	5.4	5.3	5.4	5.4	5.4	5.4	5.4		
	5.4	5.4	5.3	5.2	5.2	5.3	5.1	5.3	5.4		
	5.3	5.3	5.2	5.1	5.1	5.2	5	5.3	5.6		
	5.4	5.4	5.4	5.2	5	5.1	5.2	5.2	5.3		
	5.3	5.3	5.3	5.1	5	5	5.1	5.2	5.2		
		5.1	5.1	5	5	5.1	5.3	5.3			
		5	5	5.1	5.1	5.3	5.4	5.6			
		4.8	4.9	5.1	5.2	5.4	5.6	5.9			
				5.1	5.2	5.3					
		5.1	5.2	5.2	5.2	5.3	5.4	5.5			High spot between orange blocks = 4.8
5.1	5.1	5.1	5.2	5.2	5.3	5.3	5.5	5.6	5.8	5.9	
5	5.1	5.2	5.2	5.3	5.4	5.4	5.5	5.6	5.8	5.9	
	5.2	5.2	5.3	5.4	5.5	5.5	5.6	5.6	5.7		
		5.3	5.4	5.5	5.6	5.6	5.6	5.7			
			5.5	5.6	5.7	5.6	5.7				
				5.7	5.8	5.7					
	5.2	5.3	5.4	5.4	5.4	5.4	5.4	5.4	5.5		

Table B-3 Blank Table for Measurements

Measurements in CM					Center						Notes
											Greatest Deviation:

Table B-3 Blank Table for Measurements (Table continued)

Measurements in CM					Center						Notes

Appendix C EMC Compliance

This equipment complies with IEC60601-1-2 Edition 4 EMC Standard for medical electrical equipment.

The system is suitable to be used in an electromagnetic environment, in compliance with the limits and recommendations provided in the following tables:

- Emission compliance level and limits
- Immunity compliance level and recommendations to maintain equipment clinical utility

Table C-1 EMC Emission Declaration

Emissions Test	Compliance	Electromagnetic Environment Guidance
RF emissions CISPR 11	Group 1	The system uses RF energy only for its internal function. Therefore, its RF emissions are very low and are not likely to cause any interference in nearby electronic equipment.
RF emissions CISPR 11	Class A	
Harmonic emissions IEC 61000-3-2	NA	The system is suitable for use in all establishments other than domestic and those directly connected to the public low-voltage power supply network that supplies buildings used for domestic purposes.
Voltage fluctuations/flicker emissions IEC 61000-3-2	NA	

Table C-2 Immunity Guidance and Declaration

Immunity Test	EC 60601-1-2 Test Level	Compliance Level	Electromagnetic Environment Guidance
Electrostatic discharge (ESD) IEC 61000-4-2	±6 kV contact ±8 kV air ±8 kV contact ±15 kV air	[Edition 2 and 3] • ±6 kV contact ±8 kV air [Edition 4] • ±8 kV contact • ±15 kV air	Floors should be wood, concrete, or ceramic tile. If floors are covered with synthetic material, the relative humidity should be at least 30%.

Table C-2 Immunity Guidance and Declaration (Table continued)

Immunity Test	EC 60601-1-2 Test Level	Compliance Level	Electromagnetic Environment Guidance
Electrical fast transient/burst IEC 61000-4-4	±2 kV for power supply lines 100 Khzrate ± 1 kV for input/ output lines 100 Khzrate	[Edition 2 and 3] <ul style="list-style-type: none"> • ±2 kV for power supply lines, 100Khz rate • ±1 kV for input/ output lines, 100Khz [Edition 4] <ul style="list-style-type: none"> • ±2 kV for power supply lines, 100Khz rate • ±1 kV for input/ output lines, 100Khz rate 	Mains power quality should be a typical commercial or hospital environment.
Surge IEC 61000-4-5	±1 kV line-line ±2 kV line-earth	[Edition 2,3, and 4] <ul style="list-style-type: none"> • ±1 kV line-line • ±2 kV line-earth 	Mains power quality should be a typical commercial or hospital environment.
Voltage dips, short interruptions and voltage variations on power supply input lines IEC 61000-4-11	0% UT for 5 sec	[Edition 2 and 3] <ul style="list-style-type: none"> • < 5 % UT (>95% dip in UT) for 5 sec [Edition 4] <ul style="list-style-type: none"> • 0% UT for 5 sec 	Mains power quality should be a typical commercial or hospital environment. If the user of the system requires continued operation during power mains interruptions, it is recommended that the system is powered from an uninterruptible power supply or a battery.
Power frequency (50/60 Hz) magnetic field IEC 61000-4-8	3 A/m 30 A/m	[Edition 2 and 3] <ul style="list-style-type: none"> • 3 A/m [Edition 4] <ul style="list-style-type: none"> • 30 A/m 	Power frequency magnetic fields should be at levels characteristic of a typical location in a typical commercial or hospital environment.
NOTE UT equals the alternating current mains voltage prior to application of the test level.			

Table C-2 Immunity Guidance and Declaration (Table continued)

Immunity Test	EC 60601-1-2 Test Level	Compliance Level	Electromagnetic Environment Guidance
Conducted RF IEC 61000-4-6	3 Vrms 150 kHz to 80 MHz 6 Vrms in ISM bands 150 kHz to 80 Mhz	[Edition 2, 3, and 4] <ul style="list-style-type: none"> • 3 Vrms • 150 kHz to 80 MHz [Edition 4] <ul style="list-style-type: none"> • 6 Vrms in ISM bands • 150 kHz to 80 Mhz 	Do not use portable and mobile RF communications equipment closer to any part of the system, including cables, than the recommended separation distance (d) calculated from the equation appropriate for the frequency of the transmitter. Recommended Separation Distance (d): $d = \left[\frac{3.5}{3} \right] \sqrt{P}$ See Table C-4 , where P is the maximum output power rating of the transmitter in watts (W), according to the transmitter manufacturer and d is the recommended separation distance in meters (m) . Field strengths from fixed RF transmitters, as determined by an electromagnetic site survey, should be less than the compliance level in each frequency range. Interference may occur in the vicinity of equipment marked with the following symbol: 

Table C-2 Immunity Guidance and Declaration (Table continued)

Immunity Test	EC 60601-1-2 Test Level	Compliance Level	Electromagnetic Environment Guidance
Radiated RF Fields / Proximity Fields from Wireless Transmitters IEC 61000-4-3	3 V/m 80 MHz to 2.7 GHz 80% AM 1 kHz 9V/m to 28 V/m Spot frequencies 385 / 450 / 710 / 745 / 780 / 810 / 870 / 930 / 1720 / 1845 / 1970 / 2450 / 5240 / 5500 / 5785 MHz PM 18 Hz or 217 Hz (50% duty cycle) See Table C-4 for details.	[Edition 2 and 3] <ul style="list-style-type: none"> • 3 V/m • 80 MHz to 2.5GHz • 80%AM 1 kHz [Edition 4] <ul style="list-style-type: none"> • 3 V/m • 80 MHz - 2.7 GHz • 80%AM 1 kHz [Edition 4] <ul style="list-style-type: none"> • 9 V/m to 28 V/m • spot frequencies 385 / 450 / 710 / 745 / 780 / 810 / 870 / 930 / 1720 / 1845 / 1970 / 2450 / 5240 / 5500 / 5785 MHz • PM 18 Hz or 217 Hz • (50% duty cycle) See Table C-4 for details.	Do not use portable and mobile RF communications equipment closer to any part of the system, including cables, than the recommended separation distance (d) calculated from the equation appropriate for the frequency of the transmitter. Recommended Separation Distance (d): $d = \left[\frac{3.5}{3} \right] \sqrt{P}$ $d = \left[\frac{7}{3} \right] \sqrt{P}$ See Table C-4 , where P is the maximum output power rating of the transmitter in watts (W), according to the transmitter manufacturer and d is the recommended separation distance in meters (m). Field strengths from fixed RF transmitters, as determined by an electromagnetic site survey, ^{*1} should be less than the compliance level in each frequency range. ^{*2} Interference may occur in the vicinity of equipment marked with the following symbol: 

*1 Field strengths from fixed transmitters, such as base stations for radio (cellular/cordless) telephones and land mobile radios, amateur radio, AM and FM radio broadcast, and TV broadcast cannot be predicted theoretically with accuracy. To assess the electromagnetic environment due to fixed RF transmitters, an electromagnetic site survey should be considered. If the measured field strength in the location in which the system is used exceeds the applicable RF compliance level above, the system should be observed to verify normal operation. If abnormal performance is observed, additional measures may be necessary, such as reorienting or relocating the system.

*2 Over the frequency range 150 kHz to 80 MHz, field strengths should be less than 3V/m.

Table C-3 Spot Frequencies

Spot Frequency (Mhz)	Band (Mhz)	Service	Maximum Power (Watts)
385	380-390	TETRA 400	1,8
450	430-470	GMRS 460 FRS 460	2,0
710	704-787	LTE Band 13, 17	2
745			
780			
810	800-960	GSM 800/900 TETRA 800 IDEN 820 CDMA 850 LTE Band 5	2
870			
930			
1720	1700-1990	GSM 1800 CDMA 1900 GSM 1900 DECT LTE Band 1, 3, 4, 25 UTMS	2
1845			
1970			
2450	2400-2570	Bluetooth WLAN 802.11 b/g/n RFID 2450 LTE Band 7	2
5240	5100-5800	WLAN 802.11 a/n	0,2
5300			
5785			

Table C-4 Separation Distances for Portable and Mobile RF Communications Equipment

Rated Max Output Power (P) of Transmitter (Watts)	Separation distance according to frequency of transmitter (meters)			Comments
	150 kHz to 80 MHz	80 MHz to 800 MHz	800 MHz to 2.7 GHz	
	$d = \left[\frac{3.5}{3} \right] \sqrt{P}$	$d = \left[\frac{3.5}{3} \right] \sqrt{P}$	$d = \left[\frac{7}{3} \right] \sqrt{P}$	Where P is the maximum output power rating of the transmitter in watts (W) according to the transmitter manufacturer and d is the recommended separation distance in meters (m). Field strengths from fixed RF transmitters, as determined by an electromagnetic site survey, should be less than the compliance level in each frequency range. Interference may occur in the vicinity of equipment marked accordingly.
0.01	0.12	0.12	0.23	
0.1	0.37	0.37	0.74	
1	1.17	1.17	2.33	
10	3.69	3.69	7.38	
100	11.7	11.7	23.3	

*1 Field strengths from fixed transmitters, such as base stations for radio (cellular/cordless) telephones and land mobile radios, amateur radio, AM and FM radio broadcast, and TV broadcast cannot be predicted theoretically with accuracy. To assess the electromagnetic environment due to fixed RF transmitters, an electromagnetic site survey should be considered. If the measured field strength in the location in which the system is used exceeds the applicable RF compliance level above, the system should be observed to verify normal operation. If abnormal performance is observed, additional measures may be necessary, such as re-orienting or relocating the system.

*2 Over the frequency range 150 kHz to 80 MHz, field strengths should be less than 3 V/m.

For transmitters rated at a maximum output power not listed above, the separation distance can be estimated using the equation in the corresponding column, where power (P) is the maximum output power rating of the transmitter in watts (W) according to the transmitter manufacturer.

NOTE

- At 80 MHz to 800 MHz, the separation distance for the higher frequency range applies.
- These guidelines may not apply in all situations. Electromagnetic propagation is affected by absorption and reflection from structures, objects, and people. As an example, keep a 1 W mobile phone (800 MHz to 2.7 GHz carrier frequency) at least 2.3 m from the NM/CT system (to avoid image interference risks).

Limitations Management: Adhering to the distance separation recommended in (150 KHz to 2.7 GHz) reduces disturbances recorded at the image level, but may not eliminate all disturbances. However, when installed and operated as specified, the system maintains its essential performance by continuing to acquire, display, and store diagnostic quality images safely.

Table C-5 Electromagnetic Compliance

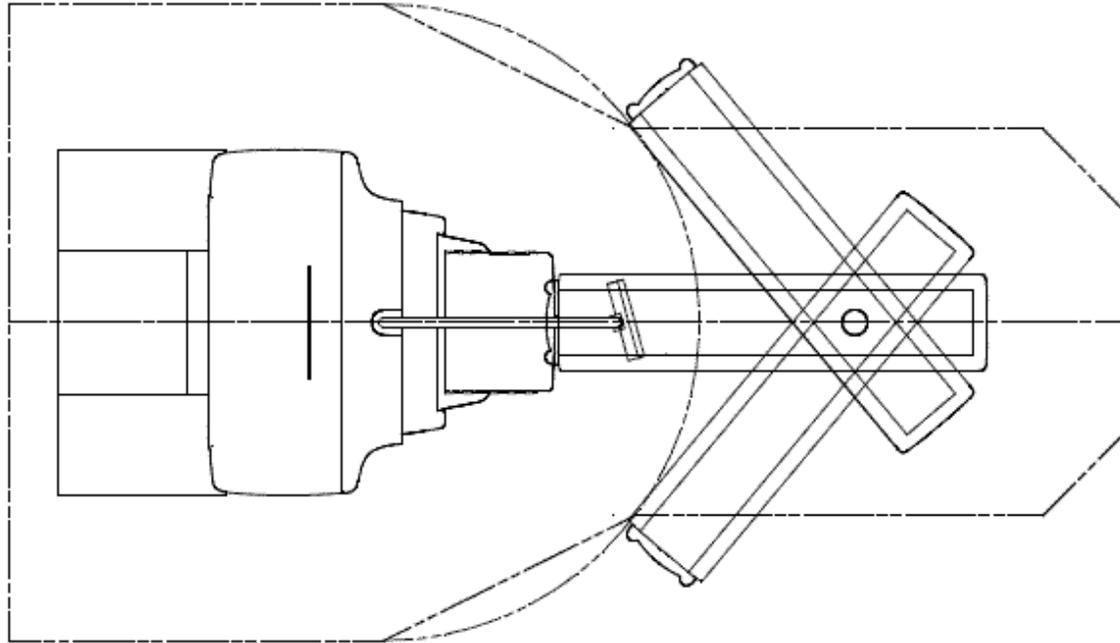
Emissions Test	Compliance	Electromagnetic Environment Guidance
RF emissions CISPR 11	Group 1	The system uses RF energy only for its internal function. Therefore, its RF emissions are very low and not likely to cause interference in nearby electronic equipment.
RF emissions CISPR 11	Class A	When installed in such a shielded location, the scanner is suitable for use in all establishments other than domestic, and those directly connected to the public low-voltage power supply network that supplies buildings used for domestic purposes.
Harmonic emissions IEC 61000-3-2	N/A	N/A
Voltage fluctuation/ flicker emissions IEC 61000-3-2	N/A	N/A

Appendix D Regulatory Clearances

MINIMUM CLEARANCES UNDER U.S. FEDERAL REGULATIONS AND NATIONAL STANDARDS: 29 CFR 1910 (OSHA), NFPA 70E (STANDARD FOR ELECTRICAL SAFETY IN THE WORKPLACE), AND NFPA 101 (LIFE SAFETY CODE):

[Figure D-1 Regulatory Clearance Requirements on page 149](#) is a map of clearance requirements for U.S. regulatory compliance. See clearance tables on the following pages for detailed dimensional clearances. Please note all systems installed in the United States must comply with all Federal and local regulations. For installations outside the United States, country-specific or other local regulatory clearance requirements must be met. See [D.5 Service Clearances on page 155](#) for additional information.

Figure D-1 Regulatory Clearance Requirements



D.1 Regulatory Code Description

Egress: 29 CFR 1910 Subpart E (OSHA) and NFPA 101 (Life Safety Code) define the minimum requirements for means of egress. The requirement most applicable to equipment installation and room layout is minimum width of exit access. Under OSHA 1910.37(f)(6), the minimum width of exit access shall in no case be less than 28 in. from any potentially occupied point in the room.

Under NFPA 101 (2006 edition) 7.3.4.1, the minimum width of any means of egress is 36 in. However, NFPA allows this to be reduced to 28 in. around furniture or equipment, provided that a 36 in. clearance would otherwise be available without moving permanent walls.

Electrical Clearance: 29 CFR 1910 Subpart S (OSHA) and NFPA 70E (Standard for Electrical Safety in the Workplace) define minimum clearance requirements for the workspace around electrical equipment. Under both OSHA 1910.303(g)(1) and NFPA 70E (2004 edition) 400.15, a minimum clear space of 36" depth (with minimum 30" width and 78" height) must be provided in front of electrical equipment with parts operating at 600 volts or below and likely to require examination, adjustment, servicing, or maintenance while energized.

This safety clearance requirement applies to all GEHC equipment. Although 36 in. is the minimum clearance for most installations, the standards require an increased minimum clearance distance where parts operate above 150 volts (but still below 600 volts) under the following circumstances:

- If the wall or surface directly facing the electrical equipment is grounded (for example: brick, concrete, or tile) or includes grounded protrusions (such as medical gas ports, metal door or window frames, water sources and metallic sink structures, metallic cabinetry, electrical disconnects or emergency off panels, air conditioners or vents), then a 42" clearance depth is required.
- If the possibility exists of exposed and unguarded live parts on both sides of the workspace (for example if a power distribution unit were positioned on the wall directly facing the GEHC equipment), then a 48" clearance depth is required.

D.2 Regulated Minimum Working Clearance by Major Subsystem

Requirements apply to equipment operating at 600V or less, where examination, adjustment, servicing, or maintenance is likely to be performed while live parts are exposed.

Direction of Service Access is defined as perpendicular to the surface of the equipment being serviced. Required regulatory clearance distances must be maintained and may not be used for storage. This includes normal system operation as well as service inspection or maintenance.

For the gantry and table, distances are measured from the enclosure, not the finish covers.

Table D-1 Gantry Subsystem

Work Space Requirement	Minimum Clear Space	Additional Conditions
Direction of service access (all sides)	914 mm (36")	If exposed live parts of 151 - 600 volts are present, 1219 mm (48 in.) on both sides of workspace with the operator between is required. If the opposite wall is grounded and exposed live parts of 151-600 volts are present, 1067 mm (42 in.) is required.
Service access width (left-right of workspace)	762 mm (30")	This is the width of the working space in front of the equipment. A minimum of 762 mm (30 in.) or the width of the equipment, whichever is greater, is required.

Table D-2 Table Subsystem

Work Space Requirement	Minimum Clear Space	Additional Conditions
Direction of service access (table head or foot)	914 mm (36")	There are no exposed live parts hazards with the cover in place. This component is typically serviced from all four sides. This is the width of the workspace on each side of the equipment. A minimum of 914.4 mm (36 in.), or the width of the equipment, whichever is greater, is required.
Direction of service access (table sides)	914 mm (36")*	*This distance can be reduced to 711 mm (28 in.) provided a written and signed approval is obtained by the local team from the local AHJ (Authority Having Jurisdiction). The signed document must be on file with GE.
Direction of Service access (table foot)	711 mm (28")	For the front gantry cover removal, a minimum of 457 mm (18 in.) is allowed only if an unobstructed egress space of 711 mm (28 in.) is maintained around the equipment for room exit. This also means no trip hazards exist along the path of egress.
Service access width (left-right of workspace)	762 mm (30")	This is the width of the working space in front of the equipment. A minimum of 762 mm (30 in.) or the width of the equipment, whichever is greater, is required.

Table D-3 Console Subsystem

Work Space Requirement	Minimum Clear Space	Additional Conditions
Direction of service access: front of console	914 mm (36")	There are no exposed live part hazards with the cover in place. If the console is placed under a counter, the front edge of the console must be even with the vertical edge of the console workspace. This component is typically serviced from the front with access to the rear.
Service access width: Front of console	762 mm (30")	This is the width of the workspace in front of the equipment. A minimum of 762 mm (30 in.) or the width of the equipment, whichever is greater, is required.

Table D-3 Console Subsystem (Table continued)

Work Space Requirement	Minimum Clear Space	Additional Conditions
Head clearance	1981.2 mm (78")	This is the height of the workspace measured from the floor at the front edge of the equipment to the ceiling or overhead obstruction(s). A minimum of 1981.2 mm (78 in.) or the height of the equipment, whichever is greater, is required.

Table D-4 CT PDU Subsystem

Work Space Requirement	Minimum Clear Space	Additional Conditions
Direction of service access (front of CT PDU)	914.4 mm (36")	There are no exposed live part hazards with the cover in place. This component is typically serviced from the front with access to the rear. <ul style="list-style-type: none"> • If exposed live parts of 151–600 volts are present, 1219 mm (48 in.) is required on both sides of the workspace with the operator between. • If the opposite wall is grounded and exposed live parts of 151–600 volts are present, 1067 mm (42 in.) is required.
Service access width (left-right of workspace)	762 mm (30")	This is the width of the working space in front of the equipment. A minimum of 762 mm (30 in.) or the width of the equipment, whichever is greater, is required.
Head clearance	1981 mm (78")	This is the height of the workspace measured from the floor at the front edge of the equipment to the ceiling or overhead obstruction(s). A minimum of 1981 mm (78 in.) or the height of the equipment, whichever is greater, is required

Table D-5 UPS Subsystem

Work Space Requirement	Minimum Clear Space	Additional Conditions
Direction of service access (front of UPS)	914.4 mm (36")*	There are no exposed live part hazards with the cover in place. This component is typically serviced from the front with access to the rear. <ul style="list-style-type: none"> • If exposed live parts of 151 - 600 volts are present, 1219 mm (48 in.) is required on both sides of the workspace with the operator between. • If the opposite wall is grounded and exposed live parts of 151 - 600 volts are present, 1067 mm (42 in.) is required.
Service access width (right side and length of UPS)	762 mm (30")	This is the width of the working space in front of the equipment. A minimum of 762 mm (30 in.) or the width of the equipment, whichever is greater, is required

Table D-5 UPS Subsystem (Table continued)

Work Space Requirement	Minimum Clear Space	Additional Conditions
Head clearance	1981 mm (78")	This is the height of the workspace measured from the floor at the front edge of the equipment to the ceiling or overhead obstruction(s). A minimum of 1981 mm (78 in.) or the height of the equipment, whichever is greater, is required.

Table D-6 MDP (A1) Disconnect Subsystem

Work Space Requirement	Minimum Clear Space	Additional Conditions
Direction of service access (front of MDP/A1)	914.4 mm (36")*	There are no exposed live part hazards with the cover in place. This component is typically serviced from the front with access to the rear. <ul style="list-style-type: none"> If exposed live parts of 151 - 600 volts are present, 1219 mm (48 in.) is required on both sides of the workspace with the operator between. If the opposite wall is grounded and exposed live parts of 151 - 600 volts are present, 1067 mm (42 in.) is required.
Service access width (right side and length of MDP/A1)	762 mm (30")	This is the width of the working space in front of the equipment. A minimum of 762 mm (30 in.) or the width of the equipment, whichever is greater, is required.
Head clearance	1981 mm (78")	This is the height of the workspace measured from the floor at the front edge of the equipment to the ceiling or overhead obstruction(s). A minimum of 1981 mm (78 in.) or the height of the equipment, whichever is greater, is required.

D.3 Terms and Definitions

Egress: The path of exit from within any room, constituting a continuous and unobstructed space, without trip hazards along the path of exit.

Workspace: The dimensional box required for safe inspection or service of energized equipment. It consists of depth, width, and height. The depth dimension is measured perpendicular to the direction of access. Additional conditions can increase the minimum dimension requirement. GE defines this as the envelope of the component superstructure with the external covers in place.

Service Access Width: The width of the workspace in front of the equipment. A minimum of 762 mm (30"), or the width of the equipment, whichever is greater.

Head Clearance: The height dimension of the workspace. The height of the workspace measured from the floor at the front edge of the equipment to the ceiling or overhead obstruction(s). 1981.2 mm (78"), or the height of the equipment, whichever is greater.

Grounded Wall: Any wall that can be electrically conductive to earth ground. Masonry, concrete, and tile are considered conductive. Additional commonly found aspects of a wall should also be considered grounded.

The following is not an all-inclusive list:

<ul style="list-style-type: none"> • Medical gas ports and plates • Metal doors and window frames • Water sources and metallic sink structures • Metallic wall-mounted cabinetry • MDP (A1) • Equipment Emergency OFF panels • Industrial equipment (such as air conditioners and vents) • Expansion joints • Surface raceway • Exposed wall conduits • Floor outlets boxes 	<p>The following are not considered as grounded elements of a common wall:</p> <ul style="list-style-type: none"> • Standard wall outlet • Light switches • Telephones • Communication wall jacks • Ceiling tile grids
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D.4 Additional Regulatory Clearance Information

D.4.1 Minimum Room Size (Limited Access)

Servicing of the CT System can be safely performed within the regulatory envelopes; however, sufficient space must be maintained to remove system covers, and replace large system components. To achieve this clearance for the gantry, clear space must be available to maneuver the gantry covers mounted on the service dollies. Surface floor raceway cannot be used in the egress route areas. OSHA ramps are available. Service personnel lifting the covers to avoid floor obstructions is not approved by EHS. One service engineer shall be able to accomplish all service component replace tasks listed without the need for special tools or equipment, such as a tube change, detector change, and HV tank.

D.4.2 Regulatory Caution

Site prints are required for all system installations including relocation and moves. The CT room layout, as shown on your site print, shall meet all regulatory requirements as described in the installation manual. Additional room components, such as cabinets, reduce room size. Equipment not shown on the site print may void the caution statement, making the room non-compliant. Actual site measurements before installation will be taken to determine room size and compliance.

D.4.3 Egress Clearance

Egress requires a clear, unobstructed route out of the room, either around the back of the gantry or around the back of the table. If your egress route is not around the back of the table, maintain 457 mm (18") of clearance between the back of the table, with a continuous width of 3200 mm (126"), 1600 mm (63") on each side of the table center line, on each side to any obstruction so that the front cover can be removed.

Exceptions: Rooms smaller than 630 cm×370 cm (21 ft.×12'), require construction to meet the minimum requirements. The design center or your GE PMI may have additional recommendations for your room size.

D.5 Service Clearances

Servicing of the system can be safely performed within the regulatory envelopes defined in [Appendix D Regulatory Clearances on page 149](#); however sufficient space must be maintained to remove the covers from the system.

To achieve this clearance for the gantry, clear space must be available to maneuver the gantry rear covers mounted on the service dollies. One Service Engineer can accomplish this.

Appendix E NM Partial UPS

Important

The EATON 6KVA NM UPS is not applicable in Europe and some other countries.

The GEDE 6KVA NM UPS is not applicable in US.

Make sure you have the Dale 600/601 Leakage Current Meter or equivalent to perform the ground wire testing after installation.

Table E-1 UPS Specifications

Parameter	Value for GEDE 6KVA NM UPS	Value for Eaton 6KVA NM UPS
Rating	6 KVA	
Input and output voltage	(Auto-configuration) 220-240V	
Input/output frequency	40-70 Hz Auto-sensing	
AC Input current	23.7A@230VAC	25.2A@230VAC
Recommended input breaker	35A D curve	30A D curve
AC output	27 A Max @220V load	
Battery rating	8 minutes @ max load	8 minutes @ max load @ 70% load
Audible noise	Max 50 db. Max 45 db.	Max 45 db. Max 45 db.
NOTE Locate UPS away from patient area		
Nominal DC voltage	230V	240V
Heat dissipation at normal operation	2235 BTUs/hr (400 watt)	1350 BTUs/hr (395 watt)
Inverter full load efficiency	Up to 88% at nominal load	Up to 94% online mode
Installed weight with batteries	253 lbs. (115Kg)	105.8 lbs. (48Kg)
Height	21.14" (537 mm)	17.3" (440 mm)* ¹
Width	12.32" (313 mm)	5.12" (130 mm)* ¹
Depth	23.22" (590 mm)	25.4" (645 mm)* ¹

*1 Tower configuration dimensions

Take into account the following:

- **Clearances**

- The unit draws air in through the front and exhausts at the back of the unit. It is suggested to provide 12" clearance at the rear for that purpose. All other servicing is performed from the front of the unit, including electronics and battery modules hot swap.
- For GEDE 6KVA NM UPS, also provide access at the rear to the maintenance bypass switch and circuit breakers.
- For Eaton 6KVA NM UPS, if the tower stand feet are used, they extend 3.7" (9.4cm) from each side of the UPS system for a total footprint width of 17.72" (45cm).
- The UPS must be connected to the facility grounding using a dedicated grounding cable.
- Eaton 6KVA NM UPS Power configuration:
 - The system has 2 mains power rating, 480V or 380V 3 Line mains connection.
For systems with a 480V 3 Line mains connection, a step-down transformer (supplied with the UPS collector) is required. The transformer is use to change the input voltage to the UPS from 280VAC, which is the single Line (L-N) voltage of $\sim 3/480V$ into 230VAC.

Important

Before installation, verify the system mains power rating.

- The followings items are used to connect the UPS to the system:

Table E-2 UPS Collector Items

UPS model		Description	Length
GEDE	Eaton		
V	V	UPS input power D670 cable	15m
V	V	UPS output power D670 cable	15m
V	V	UPS ground D670 cable	20m
V	NA	UPS GEDE EMO control cable	15m
NA	V	UPS EATON EMO control cable	15m
NA	V	UPS transformer output cable	20m
NA	V	EMO RELAY PIDB control cable	15m
NA	V	PLC Relay, 12VDC, rail mount	NA

Table E-2 UPS Collector Items (Table continued)

UPS model		Description	Length
GEDE	Eaton		
NA	V	End bracket for NS35 mounting rail	NA
V	V	Circuit breaker, 30A, Curved (Type D)	
V	V	Extension terminal 35 mm ²	
V	V	Cable gland ST-M 25 x 1.5 13-18mm	
V	V	Locking nut 25 x 1,5	
V	V	Mechanics collector	
NA	V	STEP-DOWN transformer 280VAC to 230VAC	
Additional parts used for installations without a CT UPS			
V	V	NM operator console AC power cable	20m
V	V	NM-to-PDU 24VPS AC power cable	20m
V	V	PDU 24VPS DC Estop power cable	0.75m
V	V	TDK-Lambda PS, AC to 24VDC, 30W	
V	V	Labels collector	NA

